

Renewable Energy & the Future Power Grid

Dr. Bri-Mathias Hodge

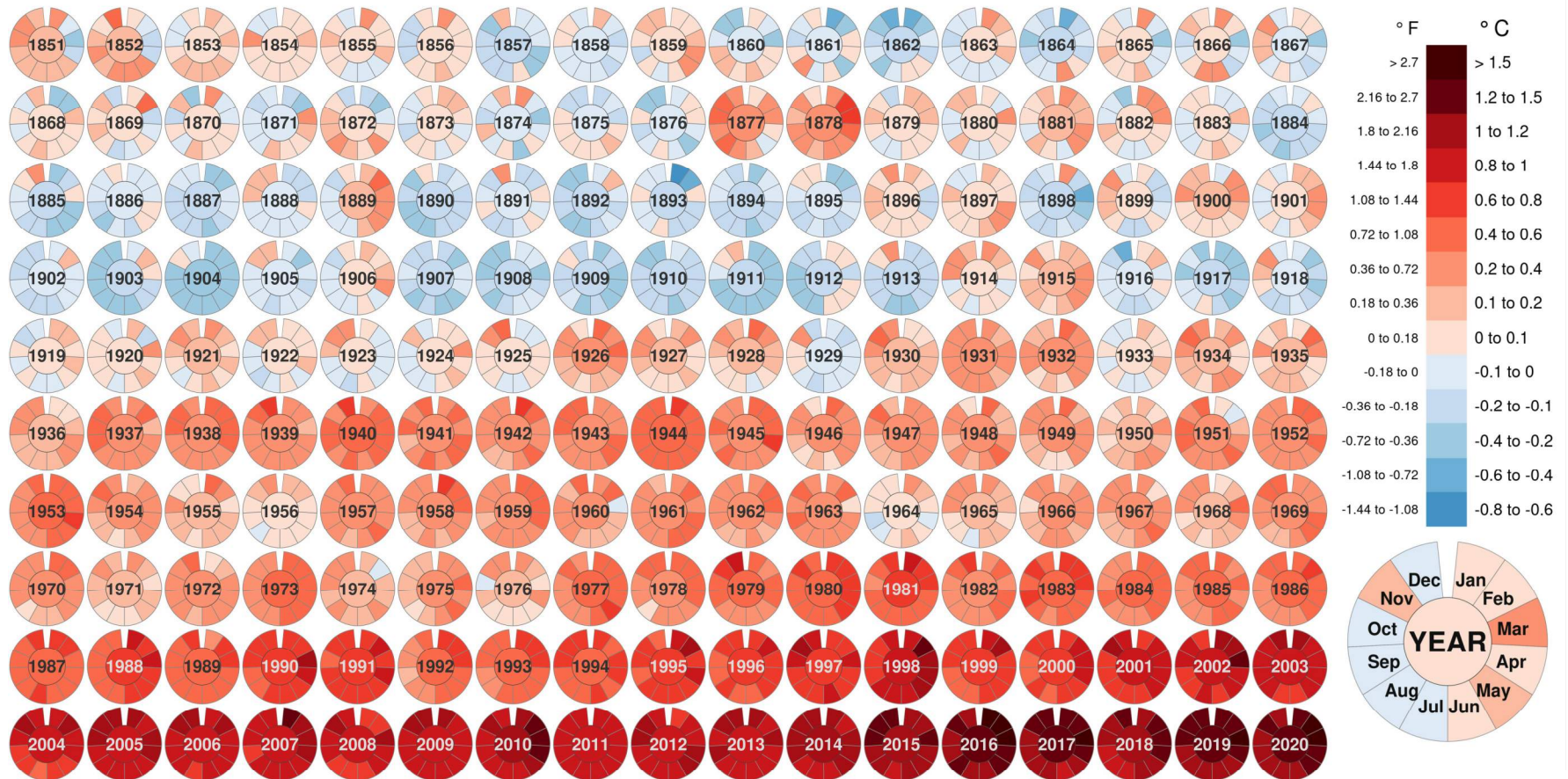
A.J. Sauter, Ph.D. Student



University of Colorado **Boulder**

The Elephant in the Room

Monthly global mean temperature 1851 to 2020 (compared to 1850-1900 averages)

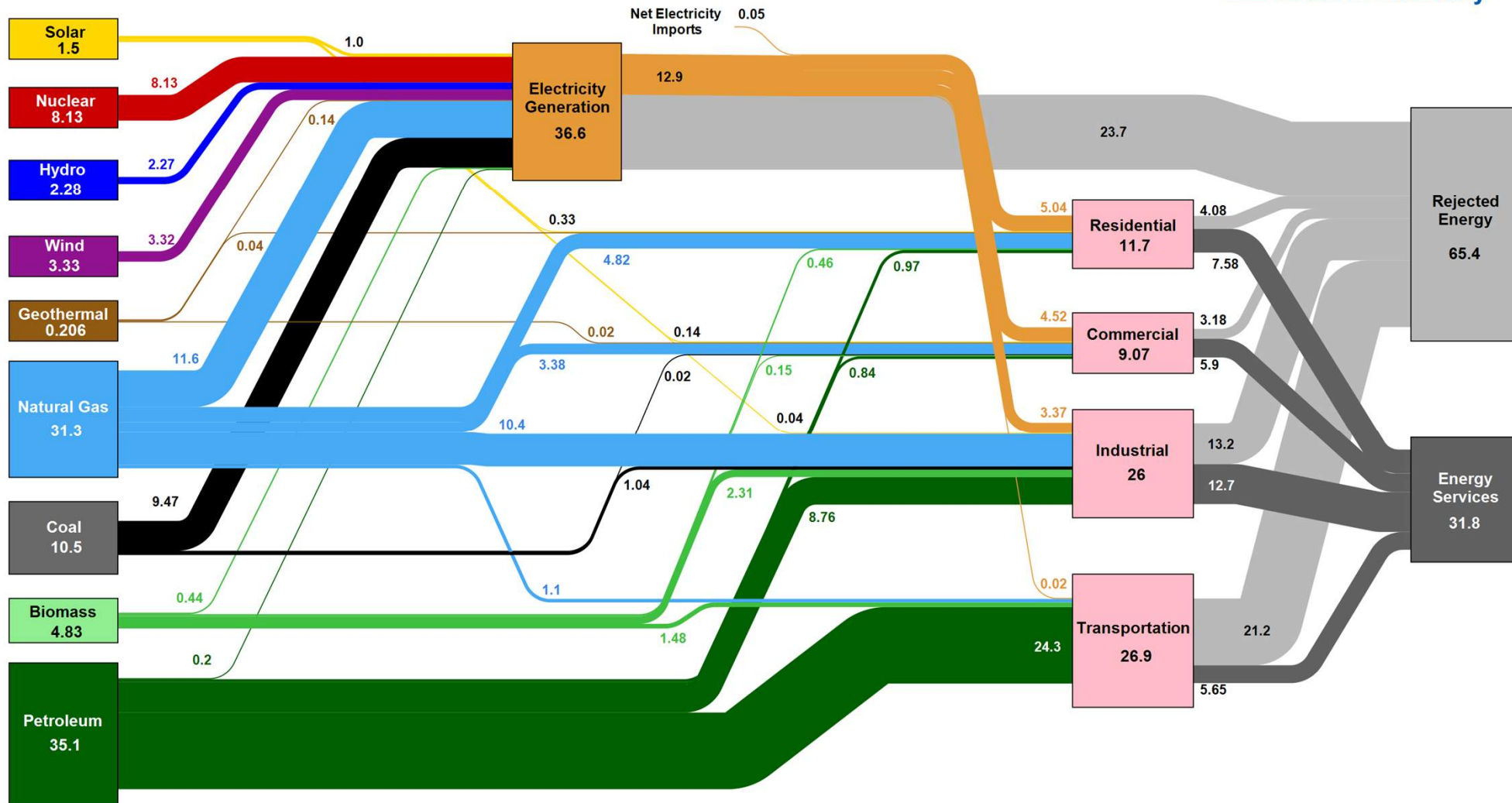


Ref: <https://www.visualcapitalist.com/global-temperature-graph-1851-2020/>

Data: HadCRUT5 - Created by: @neilkaye

US Total Energy Consumption

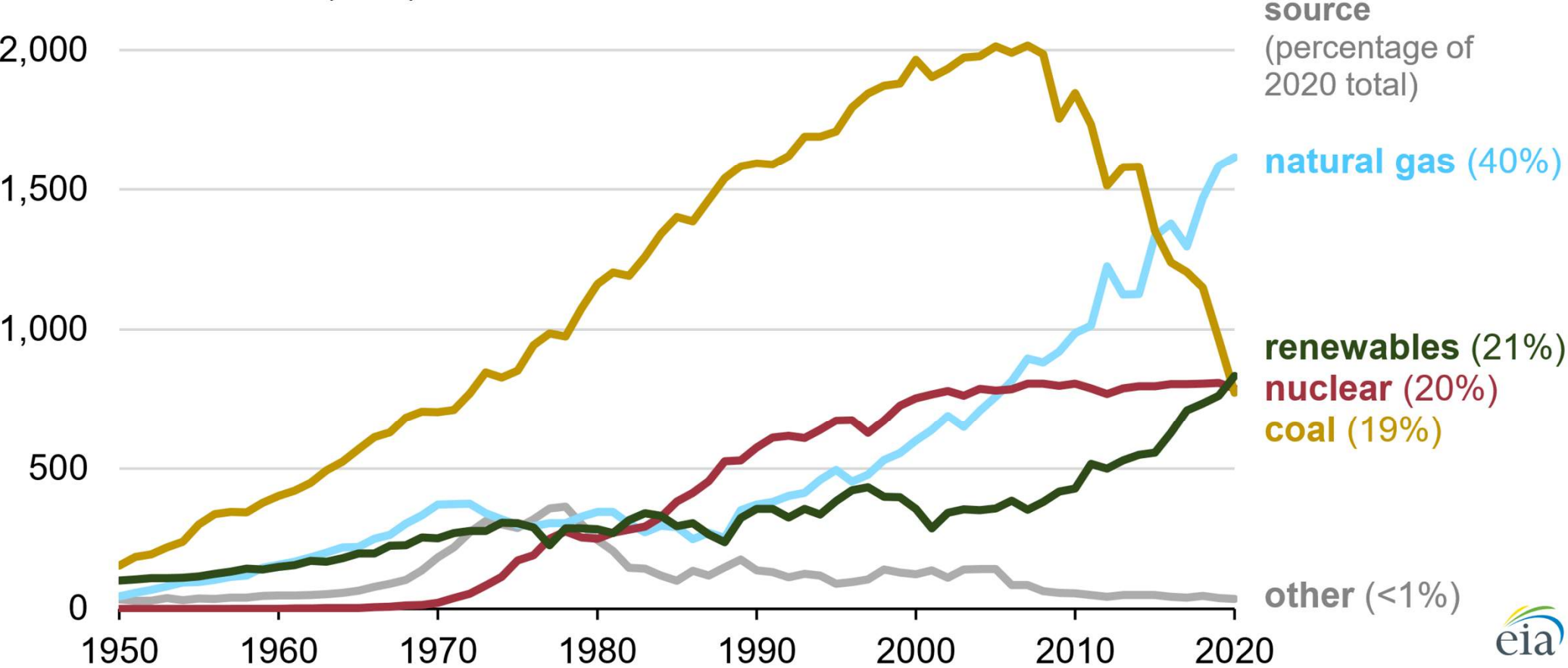
Estimated U.S. Energy Consumption in 2021: 97.3 Quads



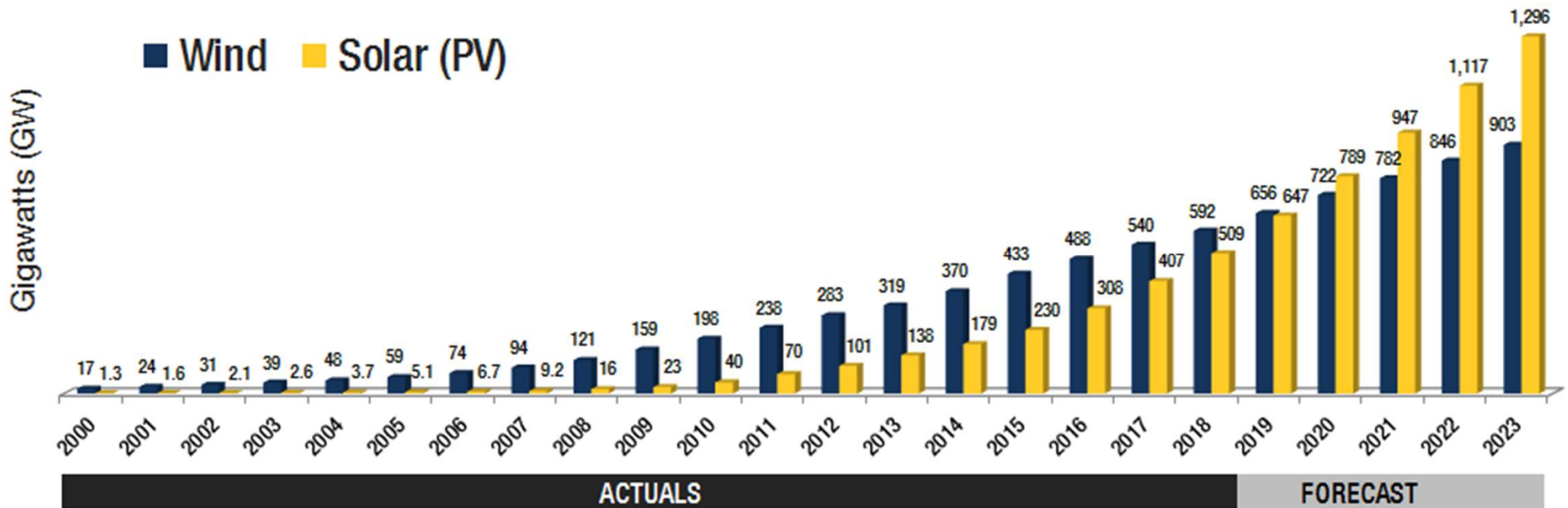
Source: LLNL March, 2022. Data is based on DOE/EIA MER (2021). If this information or a reproduction of it is used, credit must be given to the Lawrence Livermore National Laboratory and the Department of Energy, under whose auspices the work was performed. Distributed electricity represents only retail electricity sales and does not include self-generation. EIA reports consumption of renewable resources (i.e., hydro, wind, geothermal and solar) for electricity in BTU-equivalent values by assuming a typical fossil fuel plant heat rate. The efficiency of electricity production is calculated as the total retail electricity delivered divided by the primary energy input into electricity generation. End use efficiency is estimated as 65% for the residential sector, 65% for the commercial sector, 21% for the transportation sector and 49% for the industrial sector, which was updated in 2017 to reflect DOE's analysis of manufacturing. Totals may not equal sum of components due to independent rounding. LLNL-MI-410527

US Electricity Generation Mixture

Annual U.S. electricity generation from all sectors (1950–2020)
billion kilowatthours (kWh)

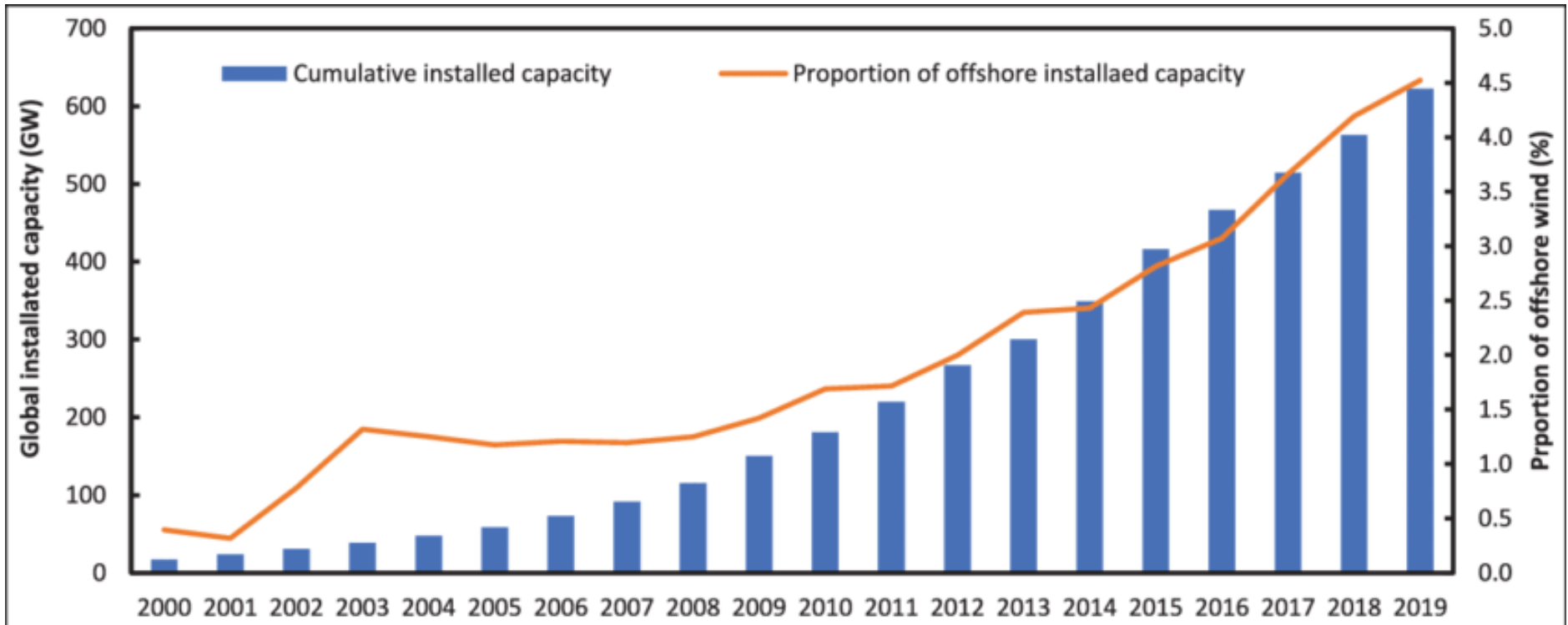


Global Wind and Solar Installation by Capacity



Wind Electricity Generation

United States: ~ 118 GW
Record 14.2 GW installed in 2020
8.4% share in 2020

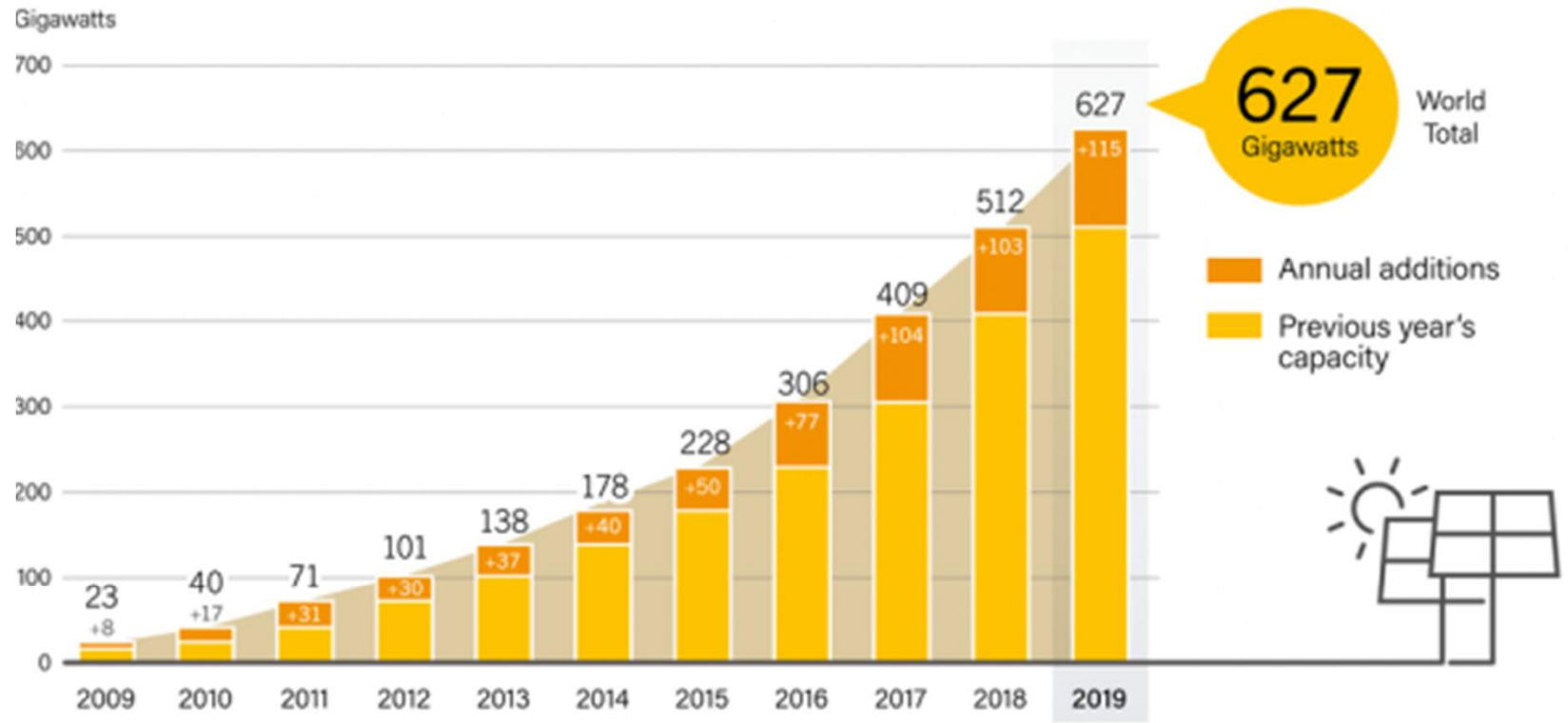


Global wind capacity end of 2019: ~ **600 GW**, Global electricity generation capacity ~ **6500 GW**

Solar Electricity Generation

United States: ~ 95 GW
2.3% share in 2020

Solar PV Global Capacity and Annual Additions, 2009-2019



Note: Data are provided in direct current (DC). Totals may not add up due to rounding.

Source: Becquerel Institute and IEA PVPS.

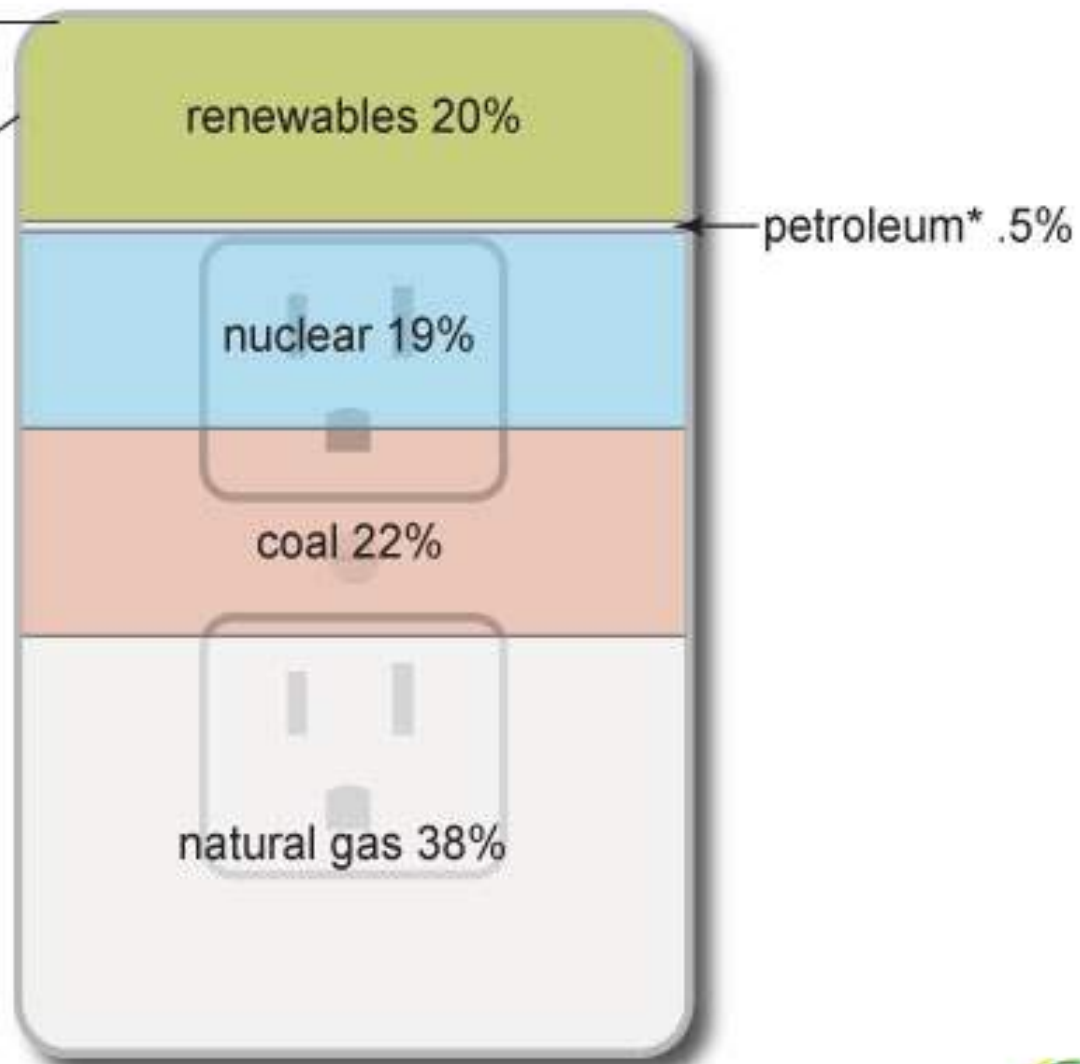
REN21 RENEWABLES 2020 GLOBAL STATUS REPORT

Global solar installations end of 2010: ~ 40 GW, Global solar capacity end of 2019: > 600 GW

Sources of U.S. electricity generation, 2021

Total = 4.12 trillion kilowatthours

wind	9.2%
hydro*	6.3%
solar	2.8%
biomass	1.3%
geothermal	0.4%



Data source: U.S. Energy Information Administration, *Electric Power Monthly*, February 2022, preliminary data



Note: Includes generation from power plants with at least 1,000 kilowatts of electric generation capacity (utility-scale).

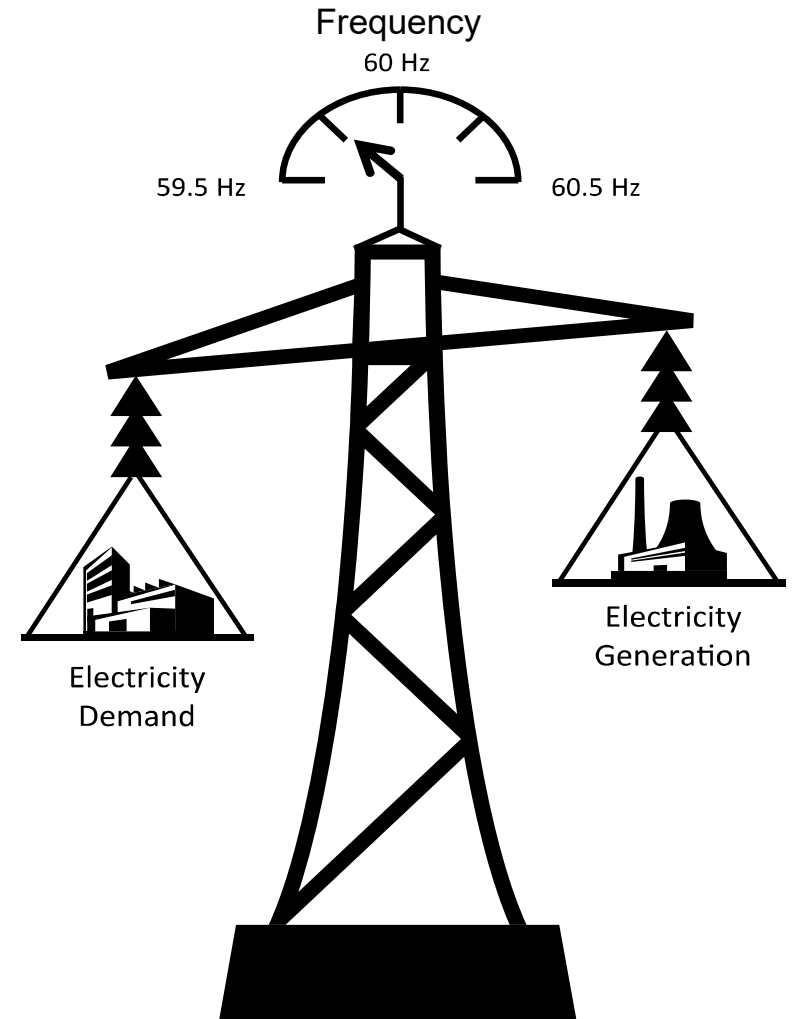
*Hydro is conventional hydroelectric. *Petroleum includes petroleum liquids, petroleum coke, other gases, hydroelectric pumped storage, and other sources.

Power System Objective

Supply electric power to customers

- Reliably
- Economically

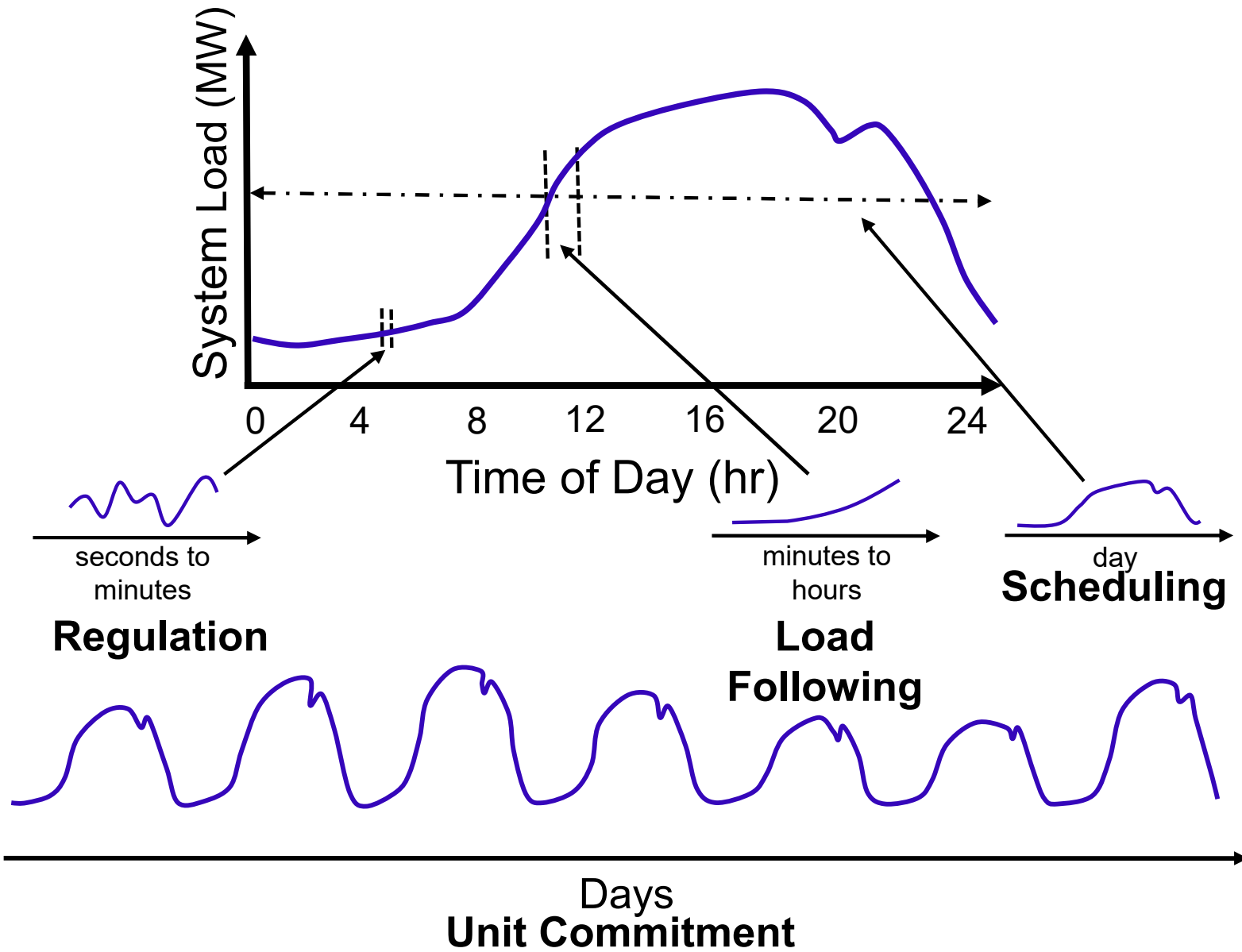
Consumption and production must be ***balanced continuously and instantaneously***



Maintaining system frequency is one of the fundamental drivers of power system reliability

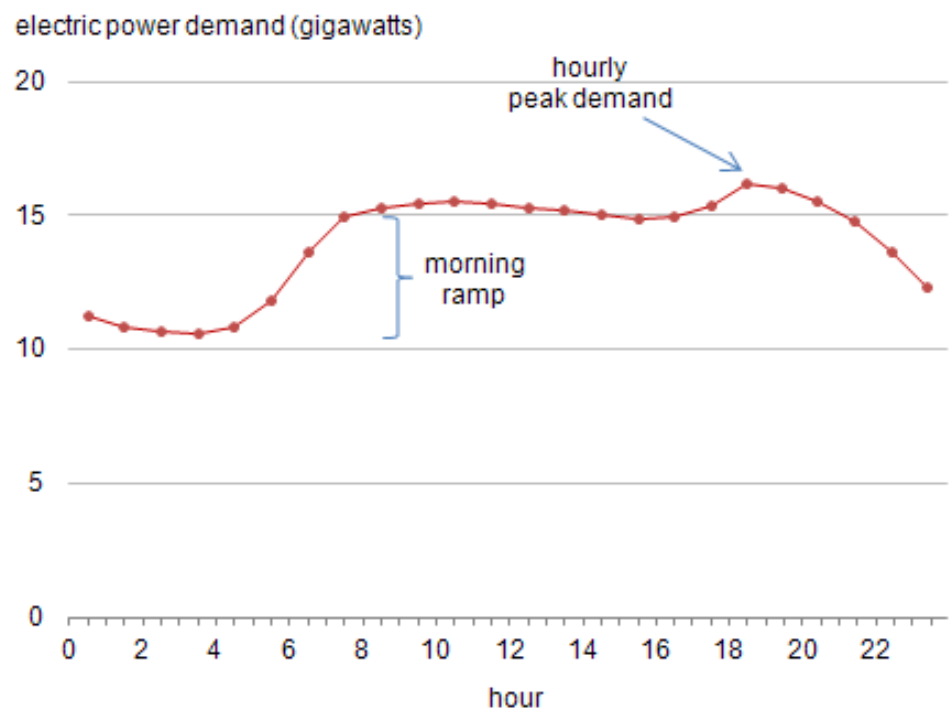
Slide credit: B. Kirby

Power System Timescales

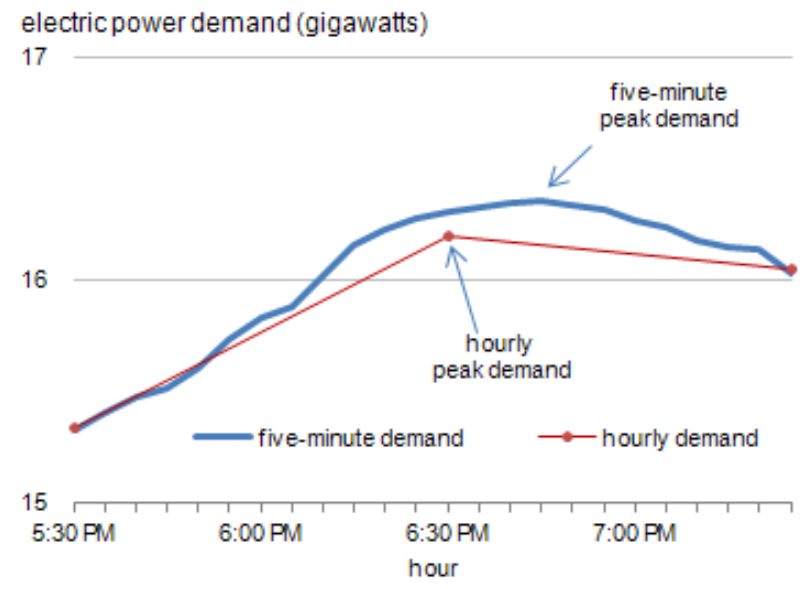


Daily Load Variability

Electric load curve: New England, 10/22/2010

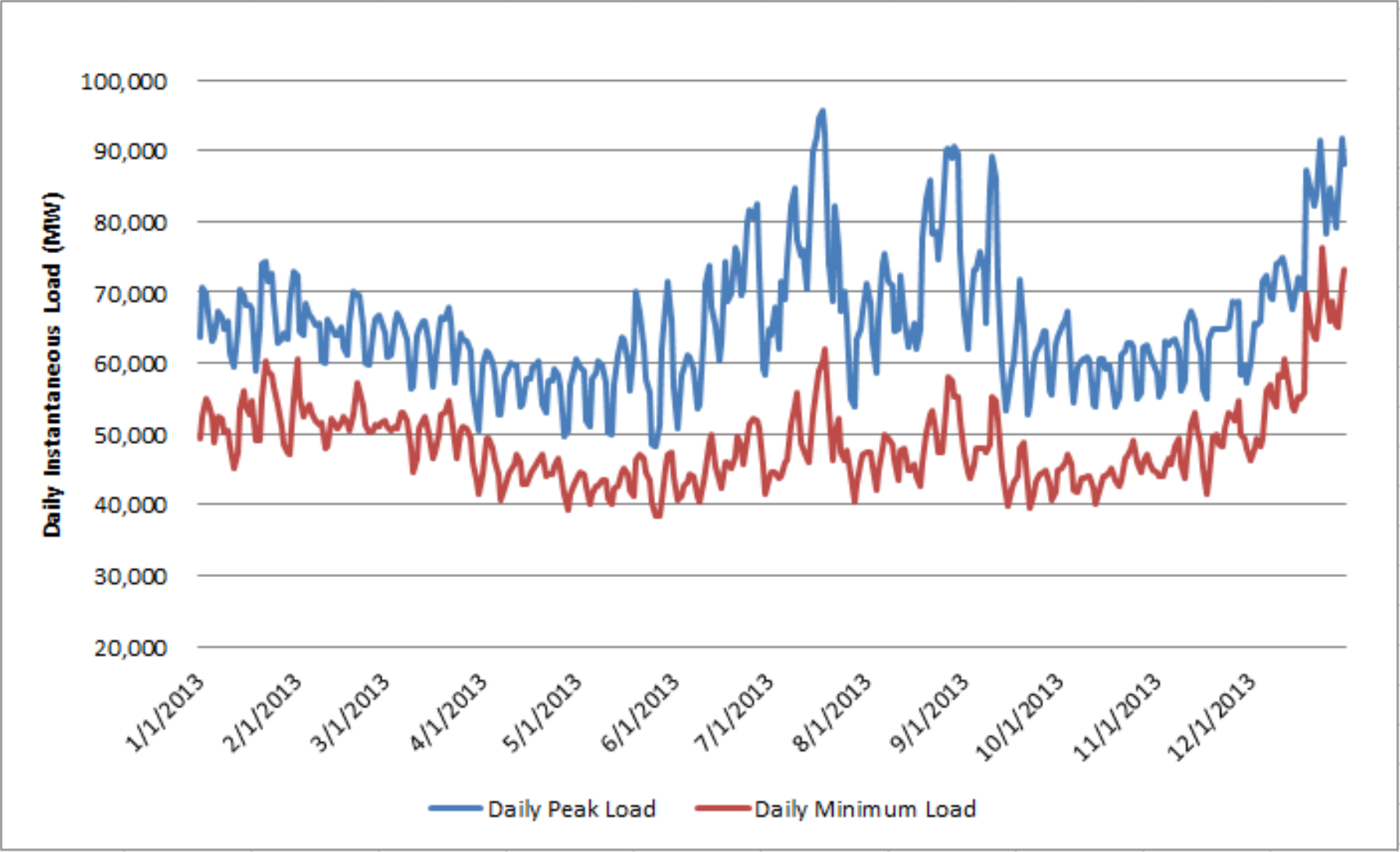


Electric load curve: New England, 10/22/2010



Source: <https://www.eia.gov/todayinenergy/detail.php?id=830>

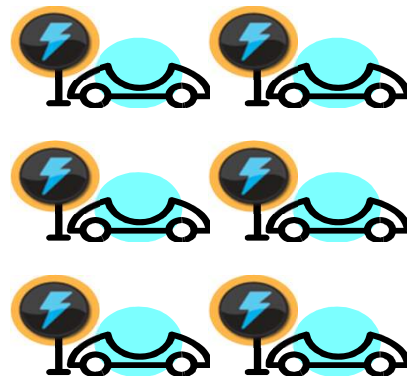
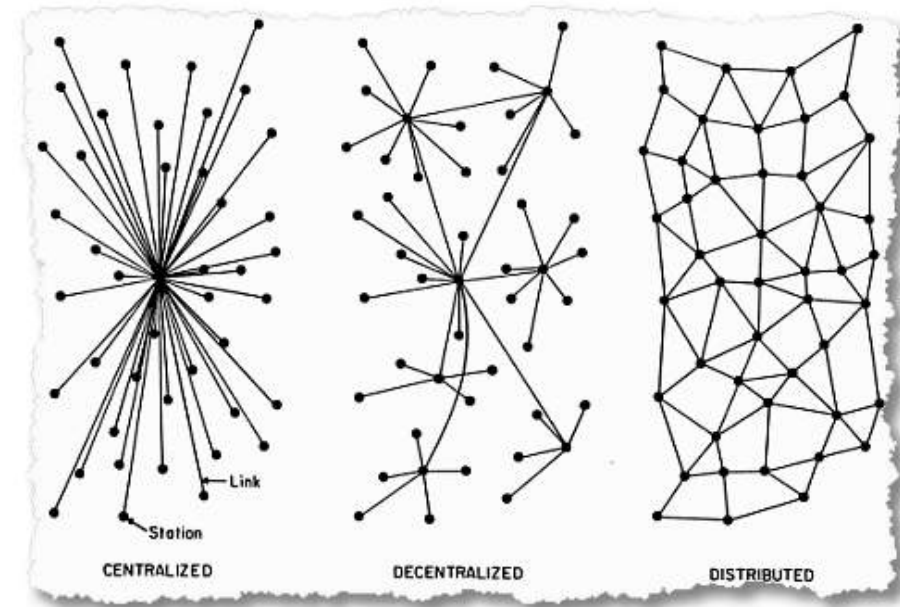
Seasonal Load Variability



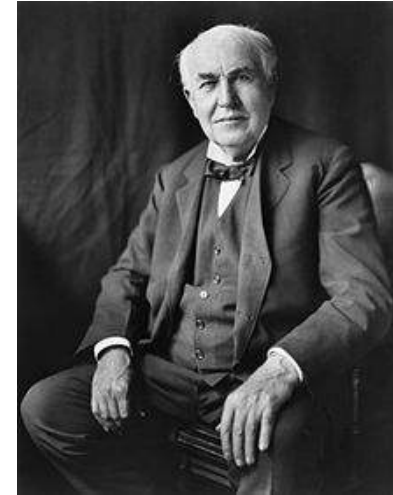
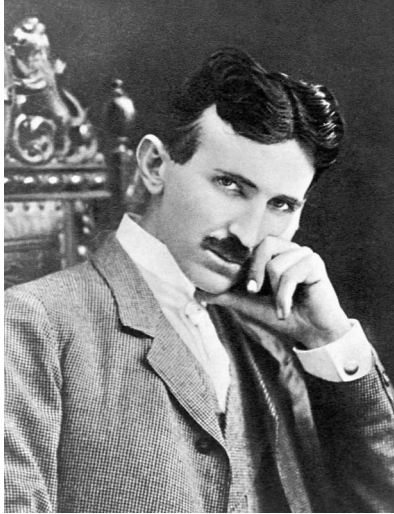
Source: MISO, <http://www.misomtep.org/load-statistics/>

Power System Background

- Transition from centralized to distributed generation
- Variable and uncertain renewable generators
- Advanced communications enable decentralized control of devices



AC vs. DC



- AC
 - Easy to generate
 - Low losses in long distance transmission
 - Can be changed to DC (bridge rectifier)
 - Central generation
- DC
 - Easy to generate
 - Difficult for long distance transmission
 - Many devices require DC
 - Local generation

Complex Power

- If load is purely **resistive**, current and voltage are in phase, and the product of voltage and current is positive or zero. The **direction of energy flow does not reverse** and **only active power is transferred**.
- If load is purely **reactive**, current and voltage are 90° out of phase, and for 2 quarters of each cycle, the product of voltage and current is positive, and for the other 2 quarters, the product is negative. On average, exactly **as much energy flows into the load as flows back out**.

$$S = |V||I|[\cos(\theta_v - \theta_I) + j \sin(\theta_v - \theta_I)]$$

j = imaginary unit

$$S = P + jQ$$

P = Real Power (W)

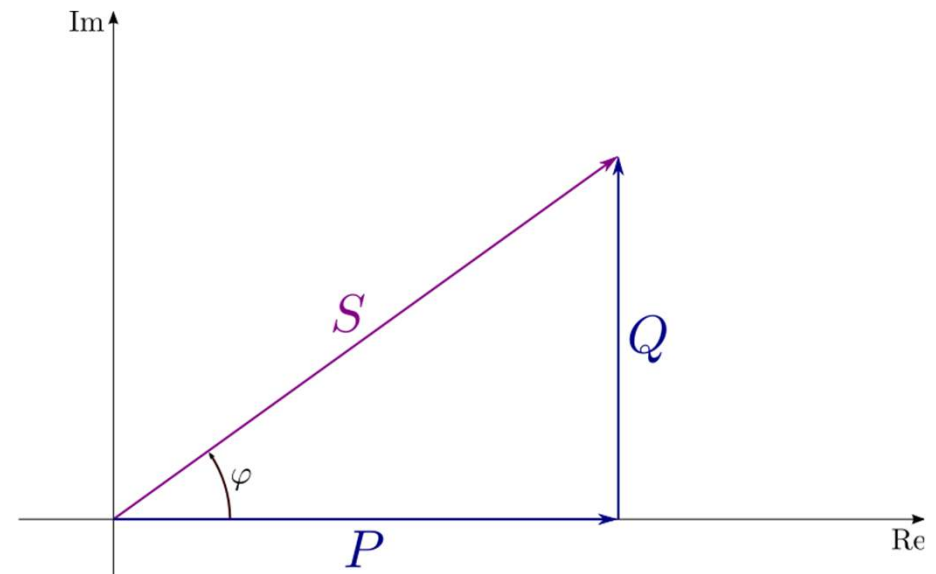
Q = Reactive Power (var)

S = Complex Power (VA)

|S| = Apparent Power

$$\phi = \theta_v - \theta_I$$

Power factor = $\cos(\phi)$



Source: https://en.wikipedia.org/wiki/AC_power

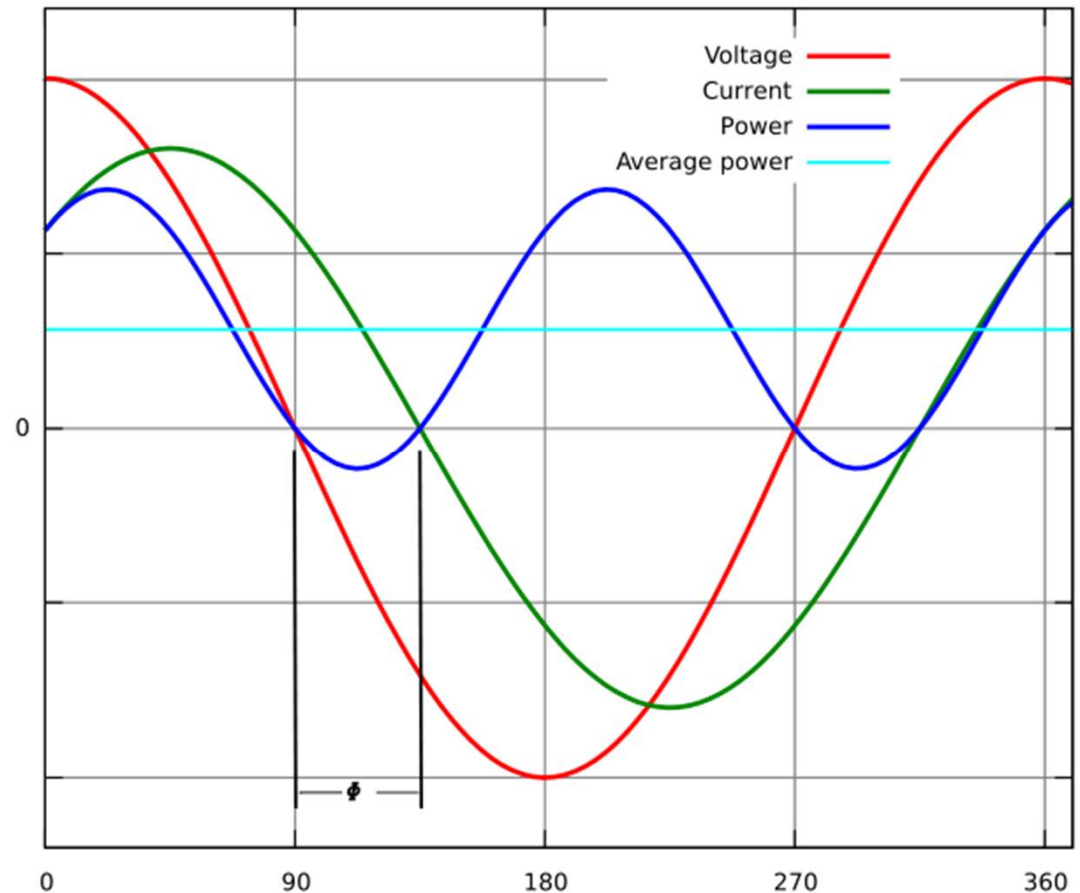
Power Factor

$$\cos\theta = \frac{P}{S}$$

where

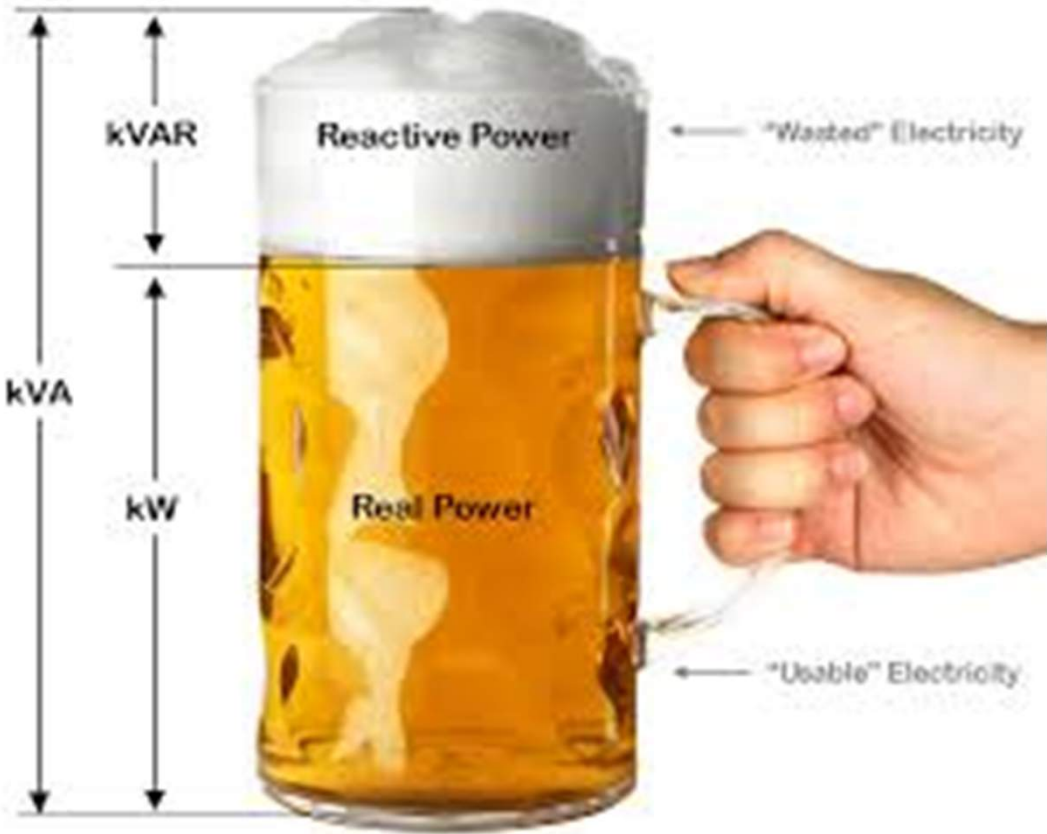
$$\begin{aligned}\cos\theta &= \text{power factor (pf)} \\ P &= \text{true power (watts)} \\ S &= \text{apparent power (VA)}\end{aligned}$$

Can change the phase angle between current and voltage to change the power factor.



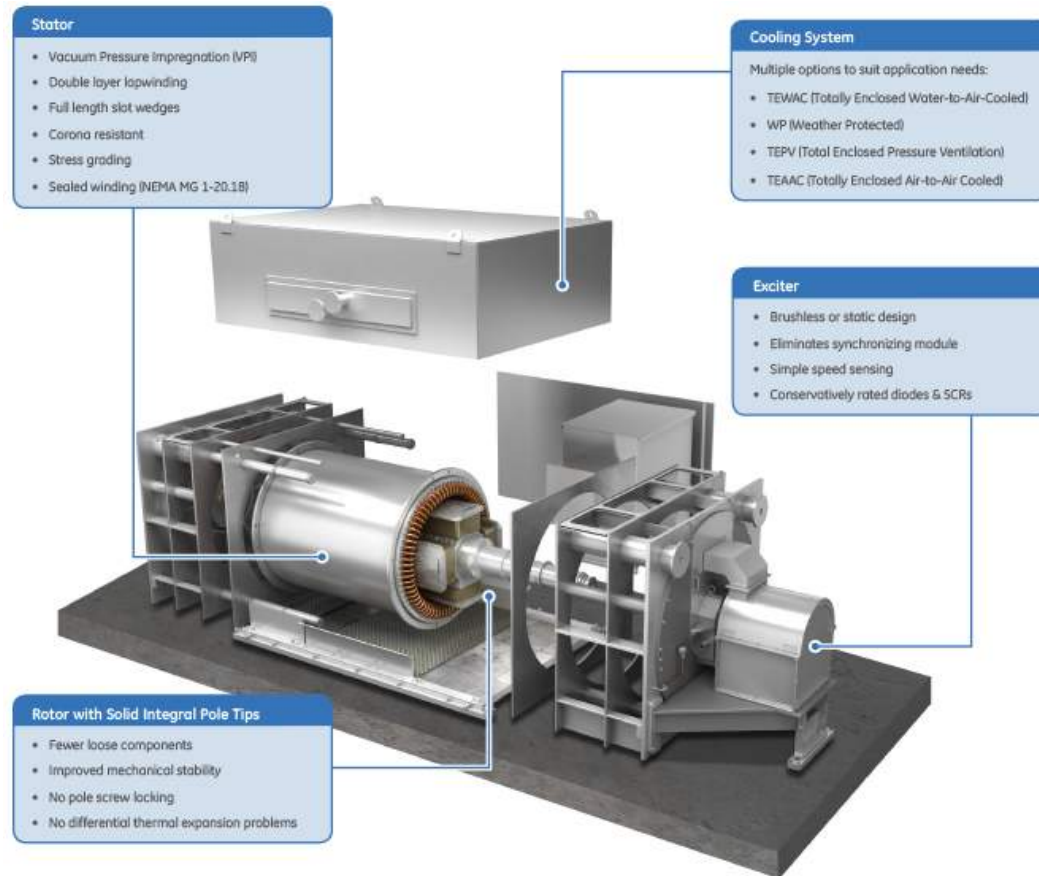
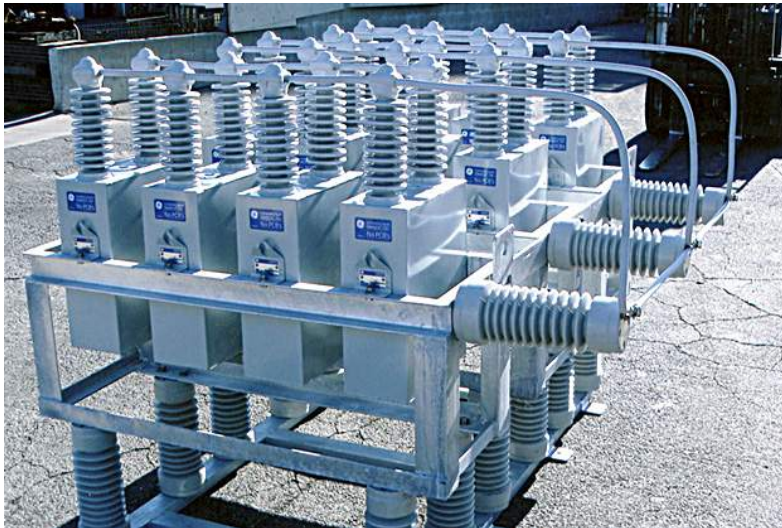
Source: DOE Fundamentals Handbook: Electrical Science

Beer Analogy



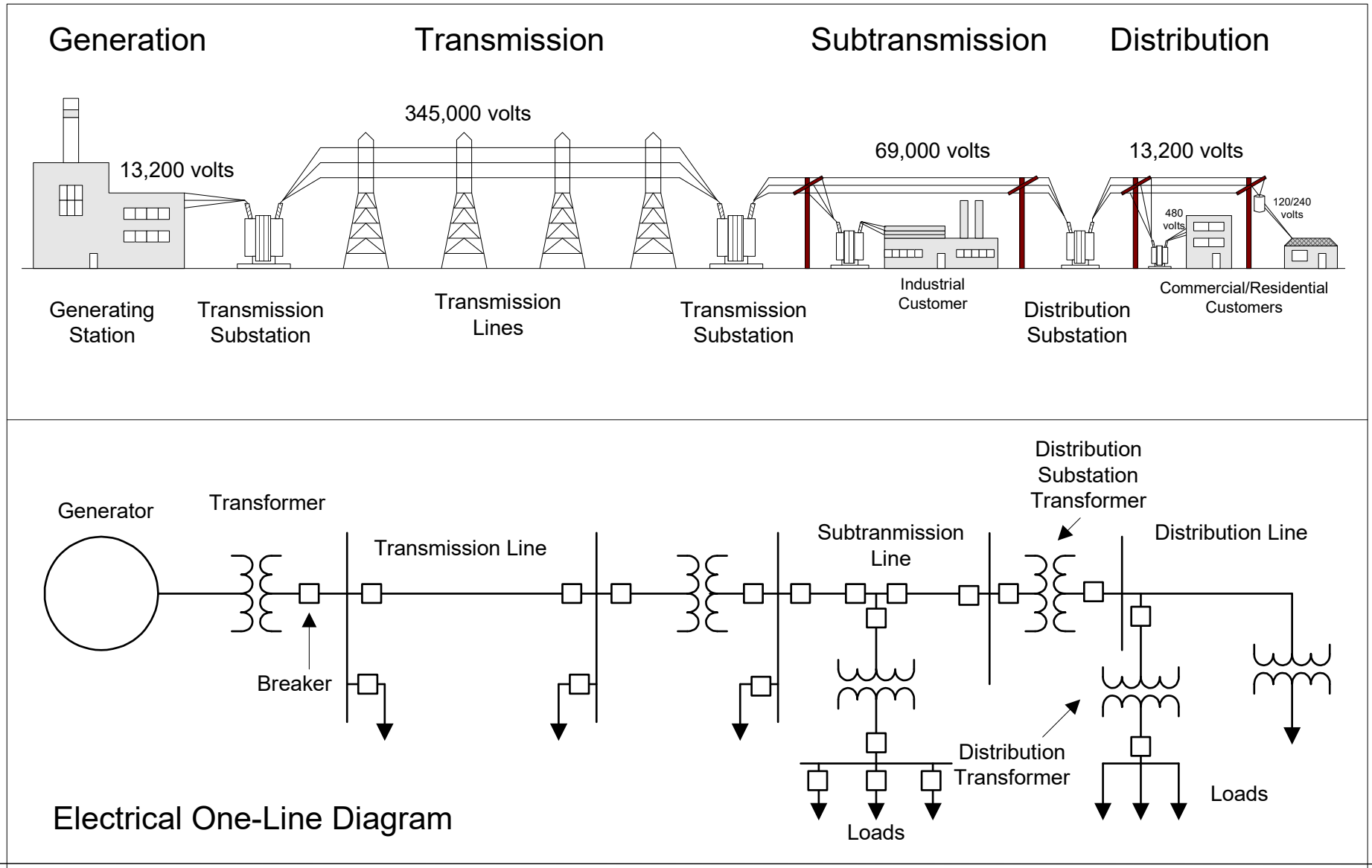
Reactive Power Regulation

- Synchronous generators
- Asynchronous generators (with power electronics)
- Synchronous condensers
- Static VAR compensators
- Capacitor banks

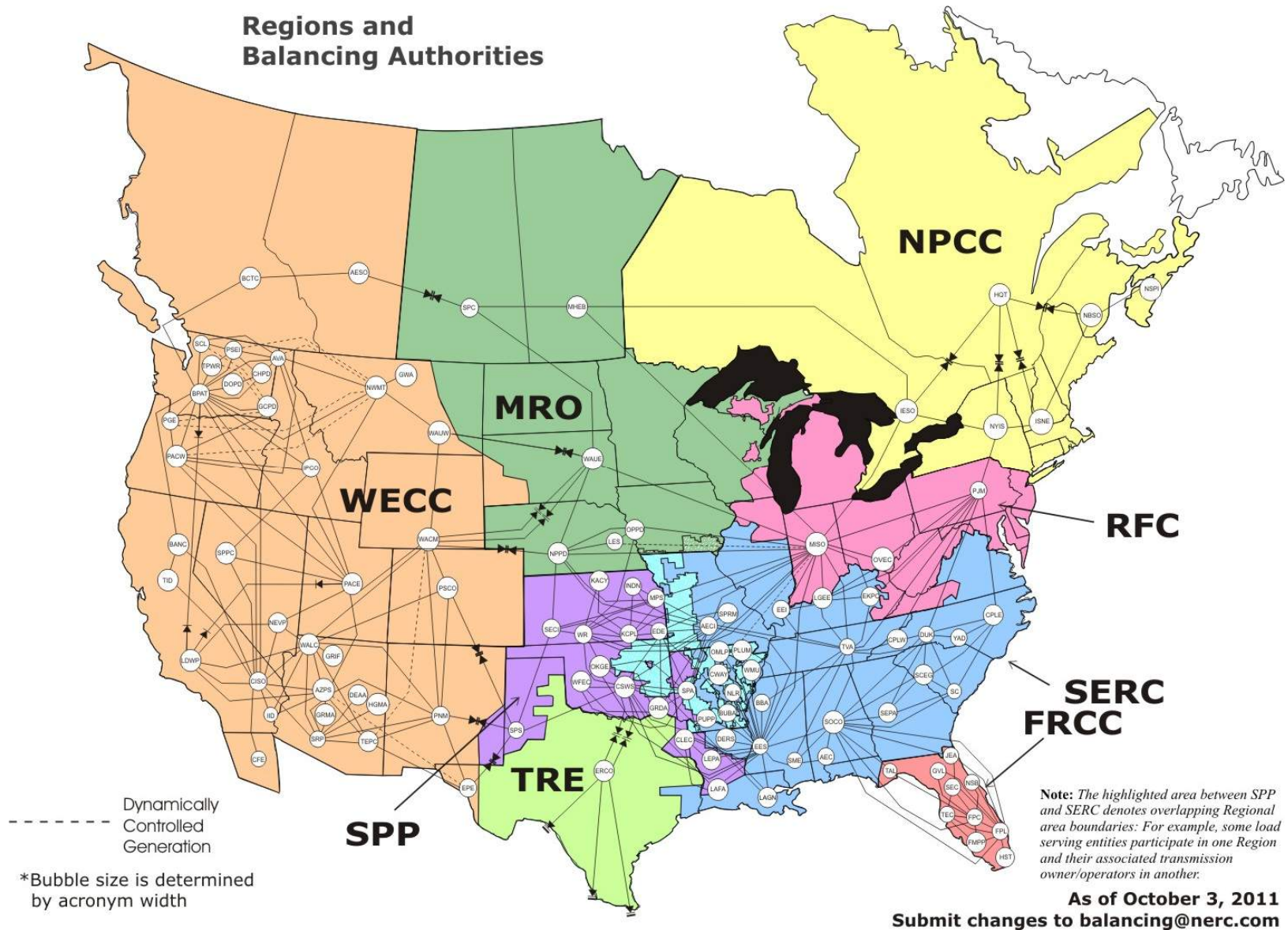


Sources: GE and Scott Engineering

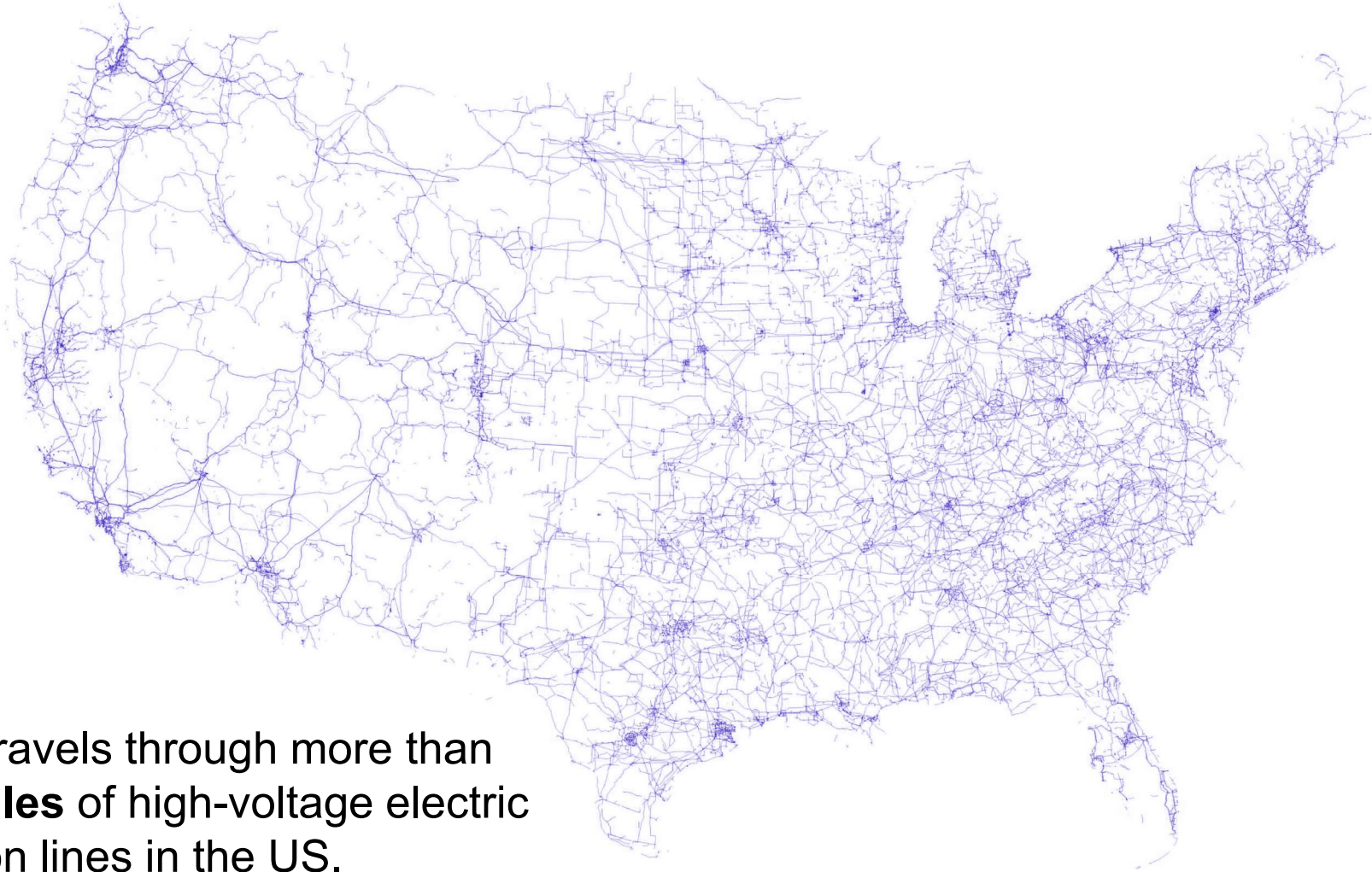
Conventional Power System



US = 3 Synchronous Grids



US Power System

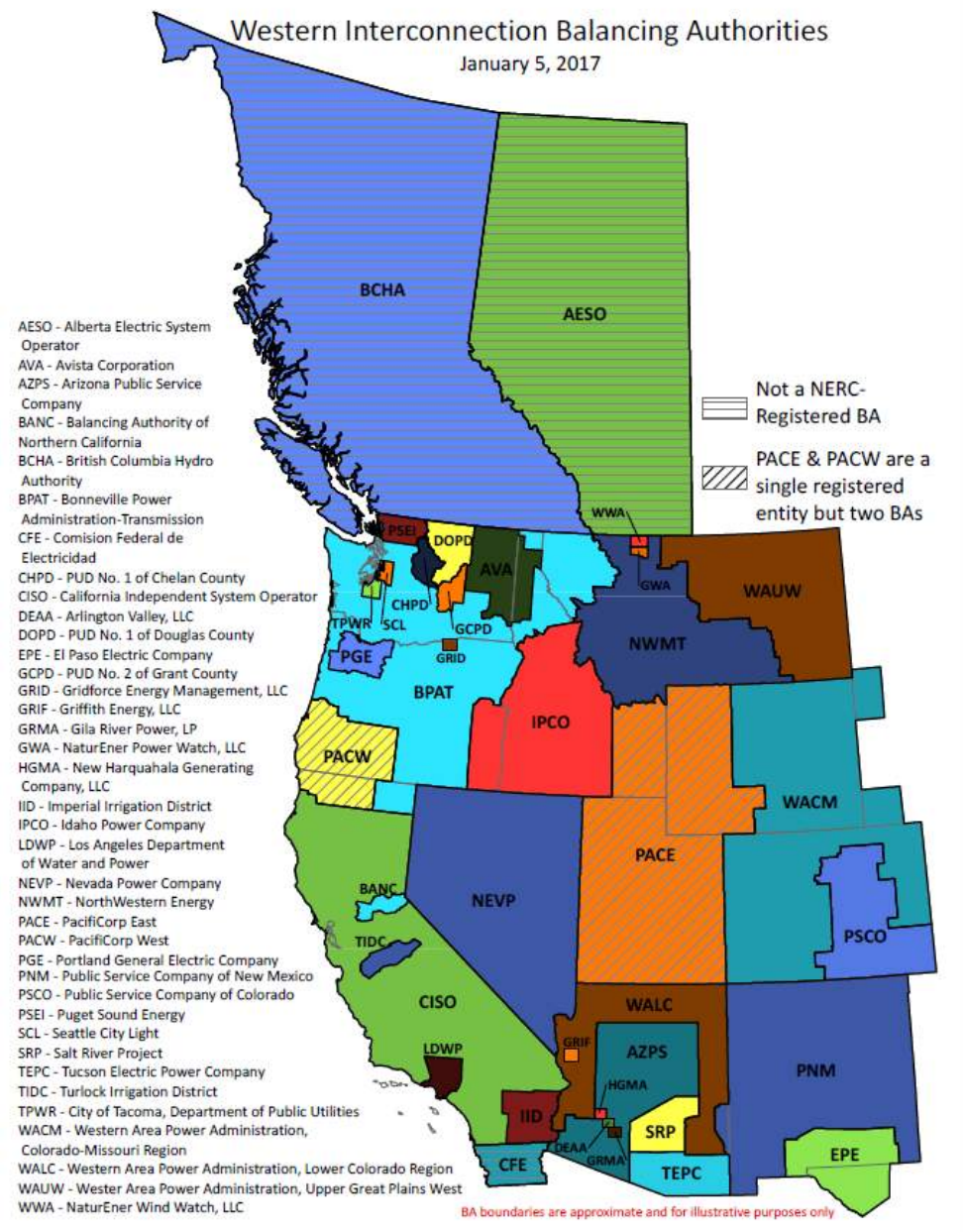


Electricity travels through more than **160,000 miles** of high-voltage electric transmission lines in the US.

Source: Washington Post

Balancing Authorities (BAs)

- **66 BAs** in the United States.
- The actual **operation of the electric system** is managed by BAs.
- Most (not all) balancing authorities are **electric utilities** that have taken on the balancing responsibilities for a portion of the power system.
- All of the **RTOs/ISOs** also function as BAs.
- A BA ensures, in real time, that power system **demand and supply** are finely **balanced** to maintain the safe and reliable operation of the power system. This includes managing **transfers** of electricity with other BAs.
- BAs are responsible for maintaining operating conditions under mandatory **reliability standards** issued by NERC and approved by FERC.

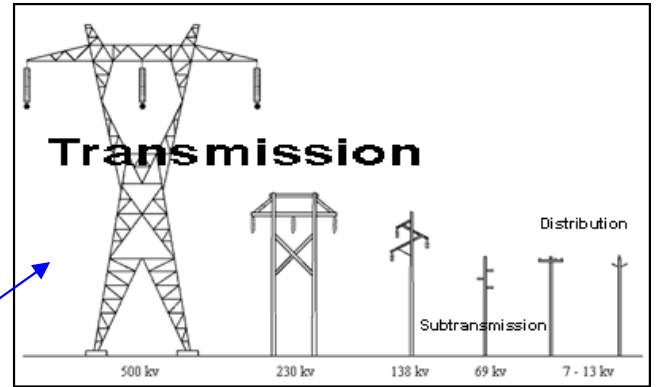
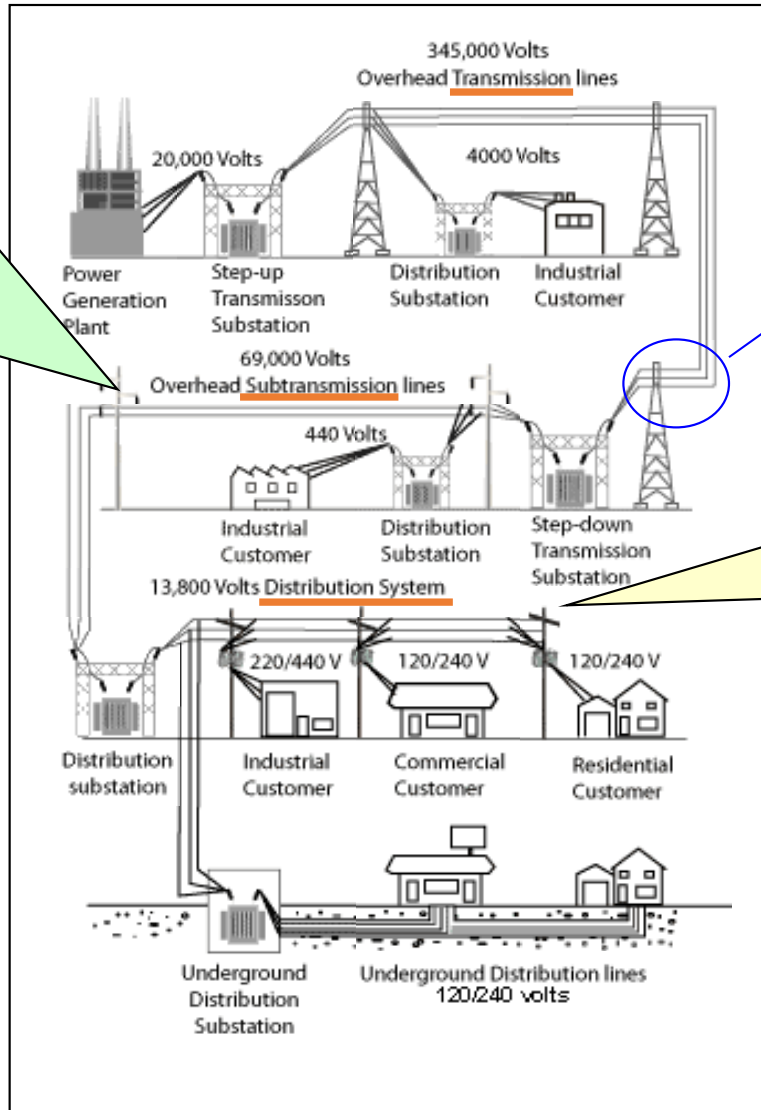


Renewable Energy Interconnection

Electric Power System

Central Station

Large wind farms, CSP, large PV, biopower, hydro, geothermal, hydrokinetic, interconnect at transmission and sub-transmission levels

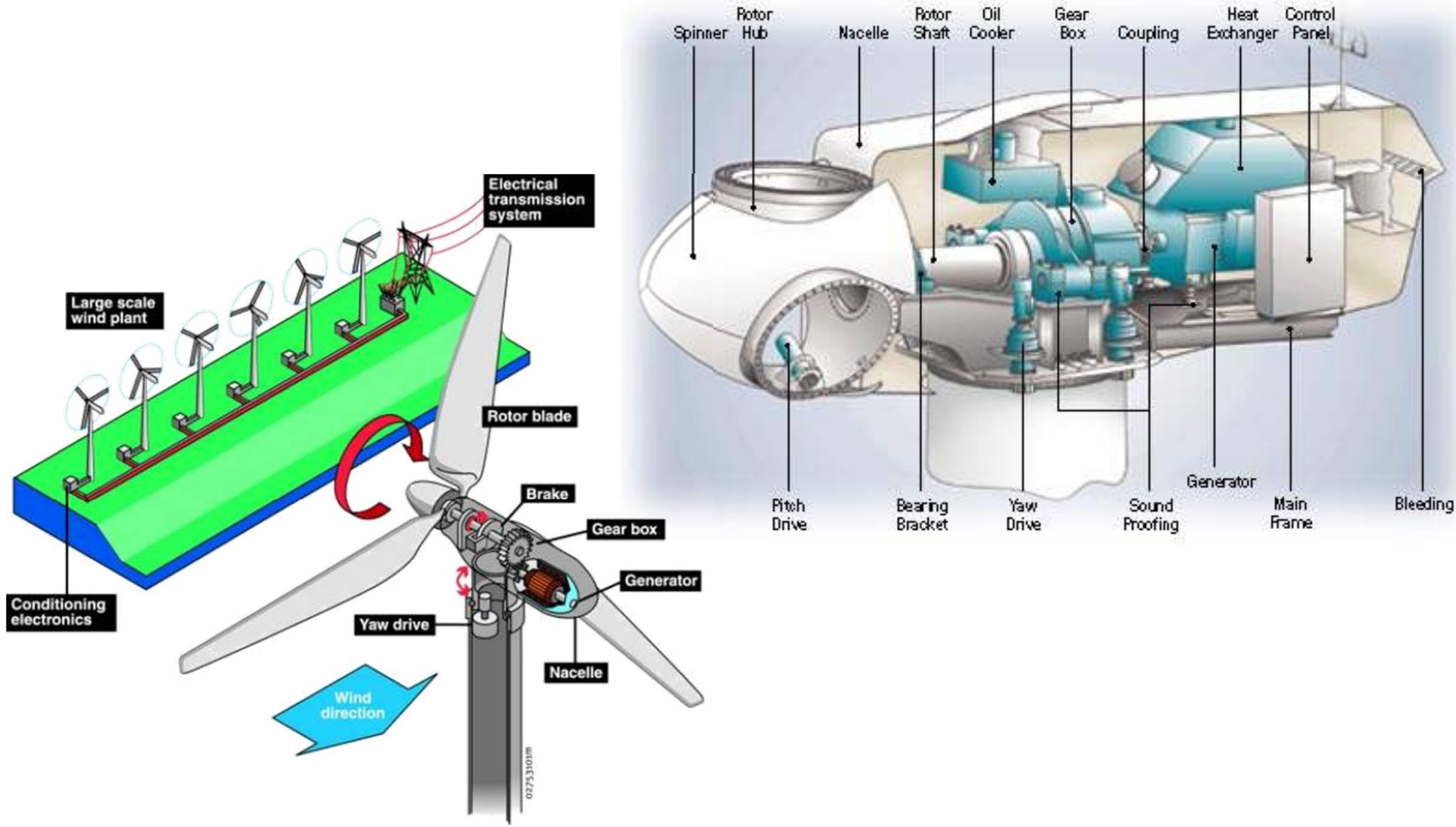


Distributed

PV, small wind, and fuel cells interconnect at the distribution level

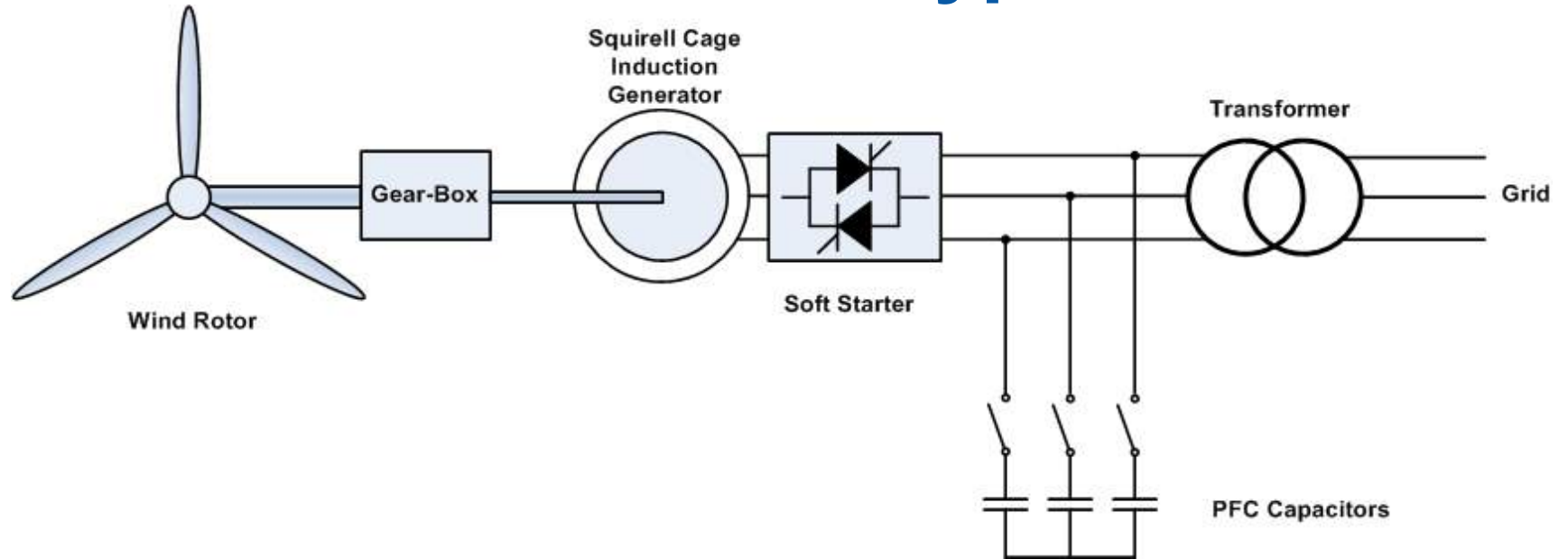


Parts of Modern Commercial Turbines

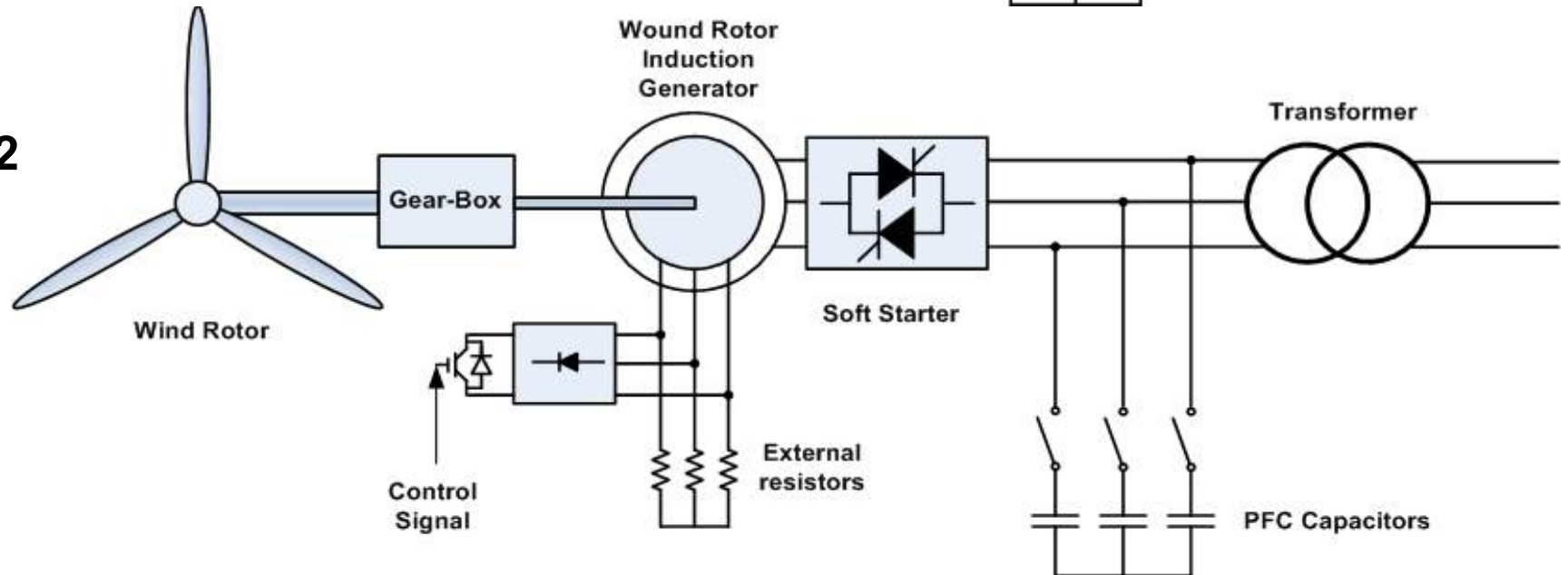


Wind Turbine Generator Types

Type 1

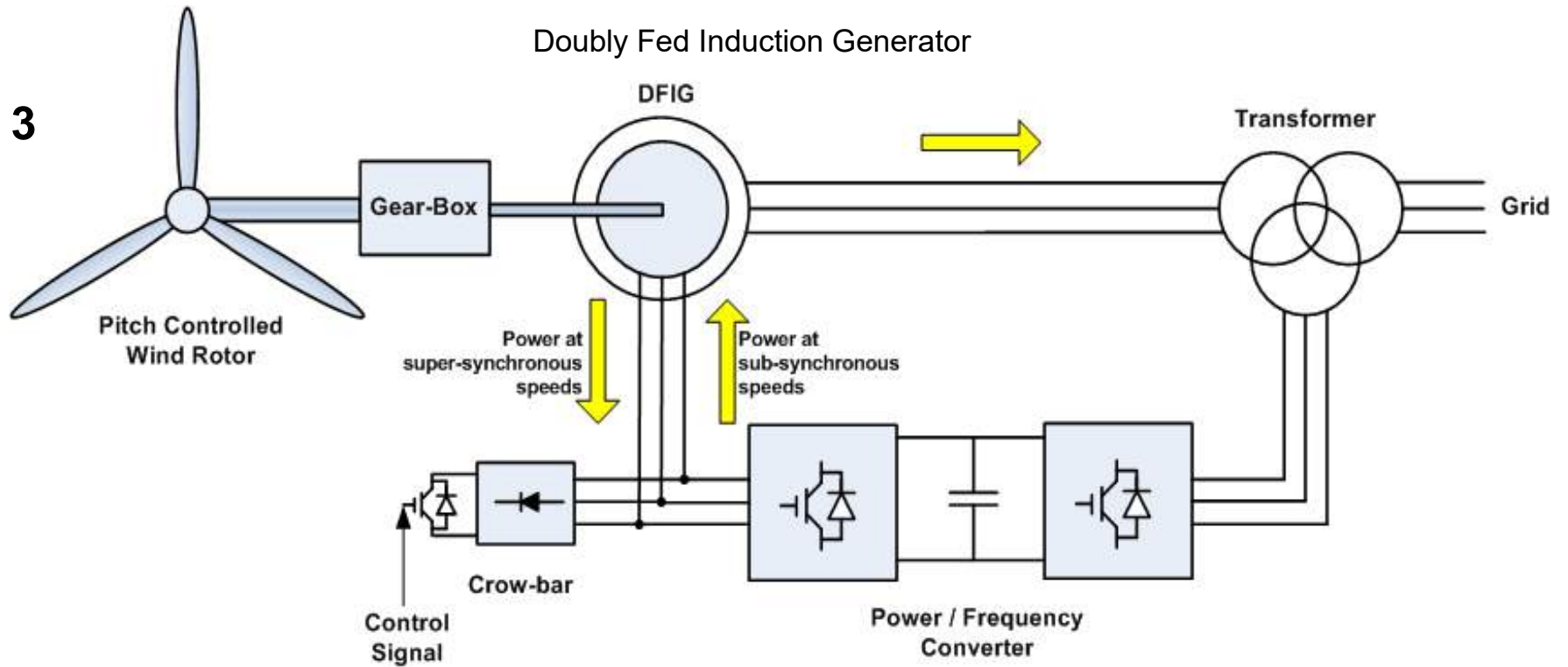


Type 2

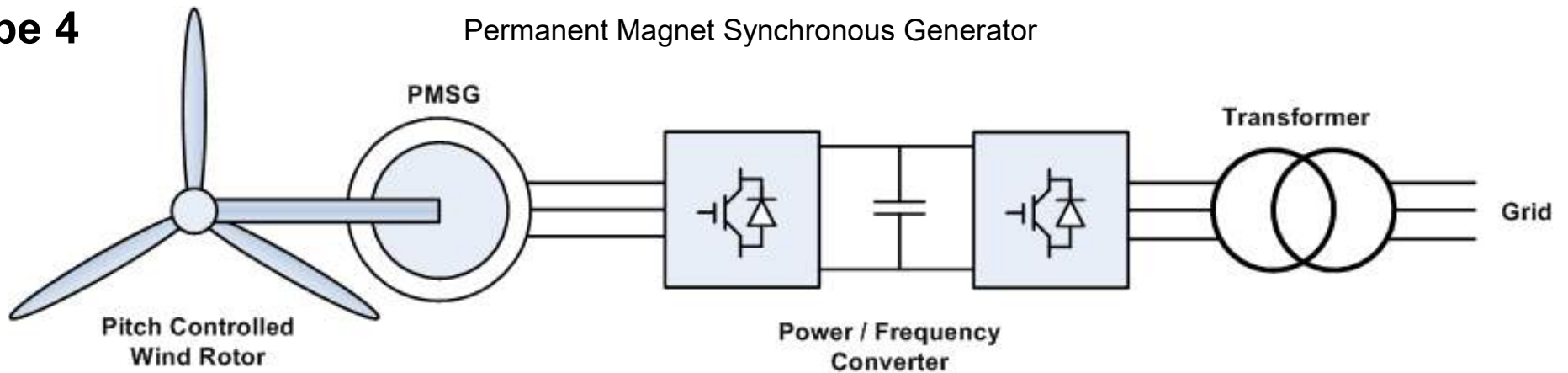


Wind Turbine Generator Types Continued

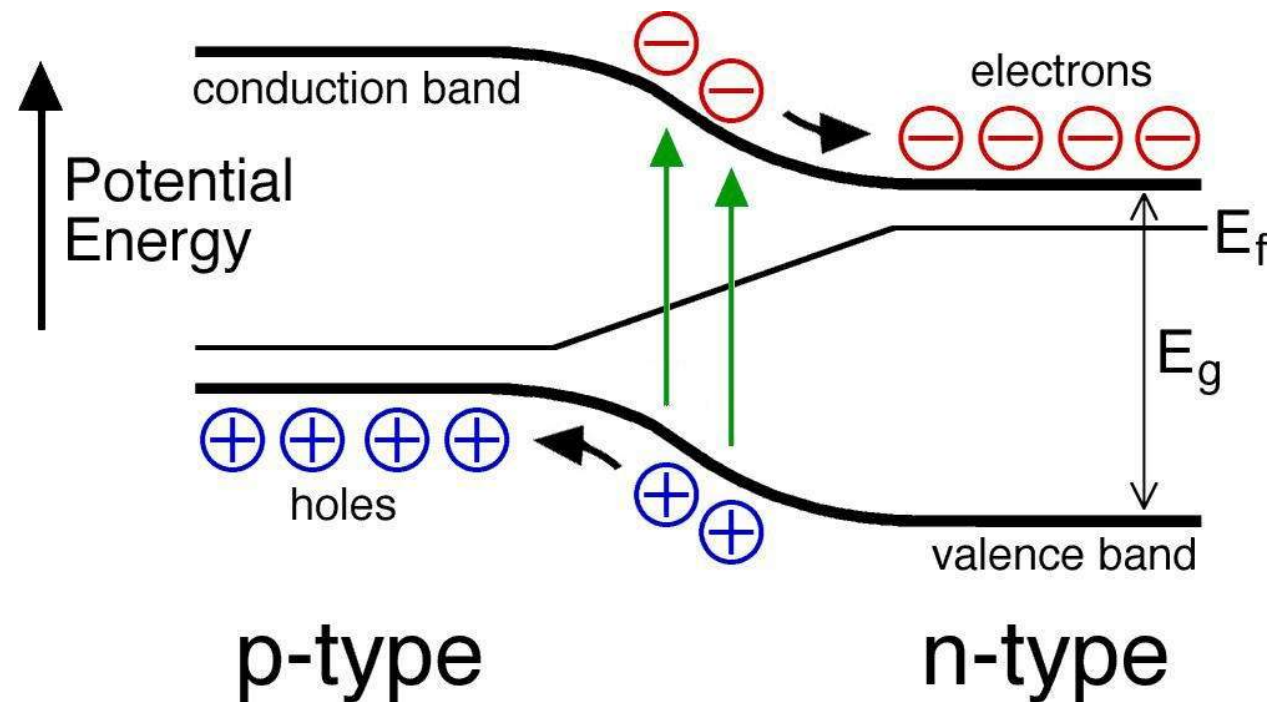
Type 3



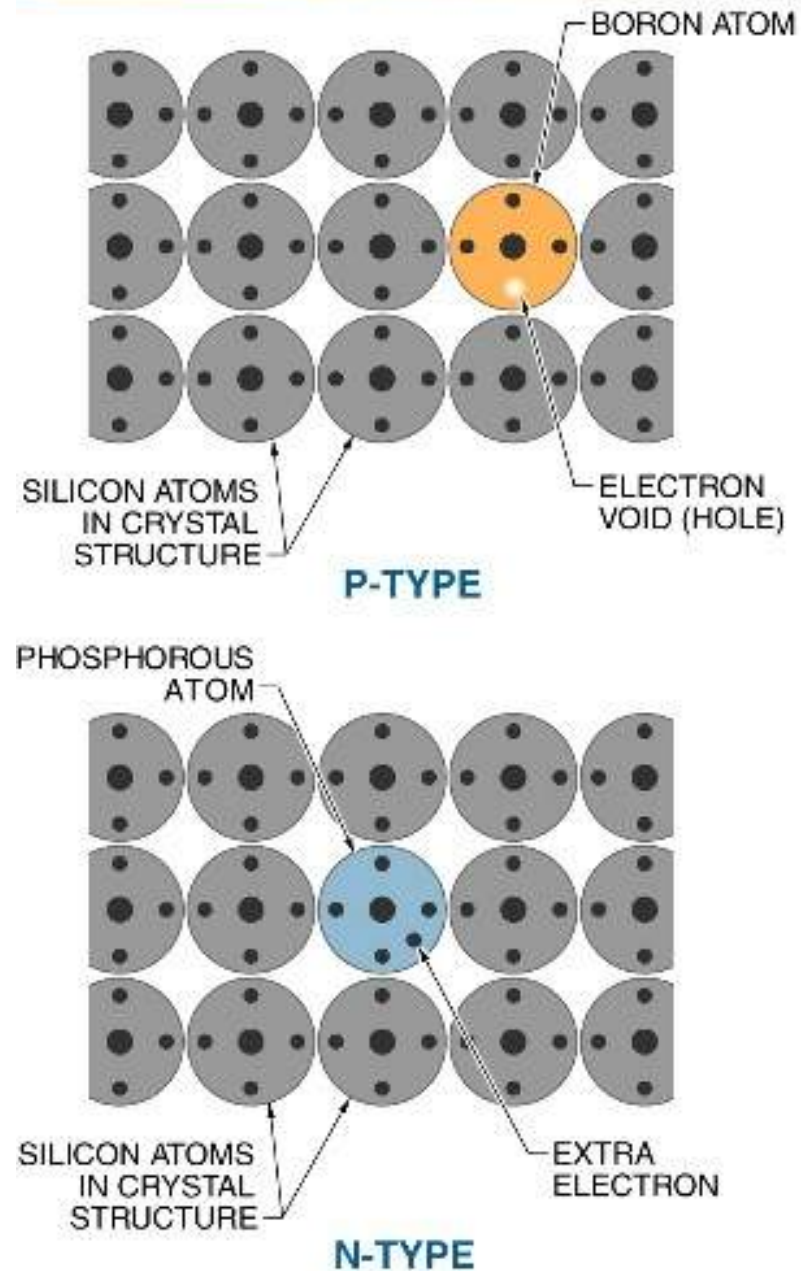
Type 4



PV Device Physics

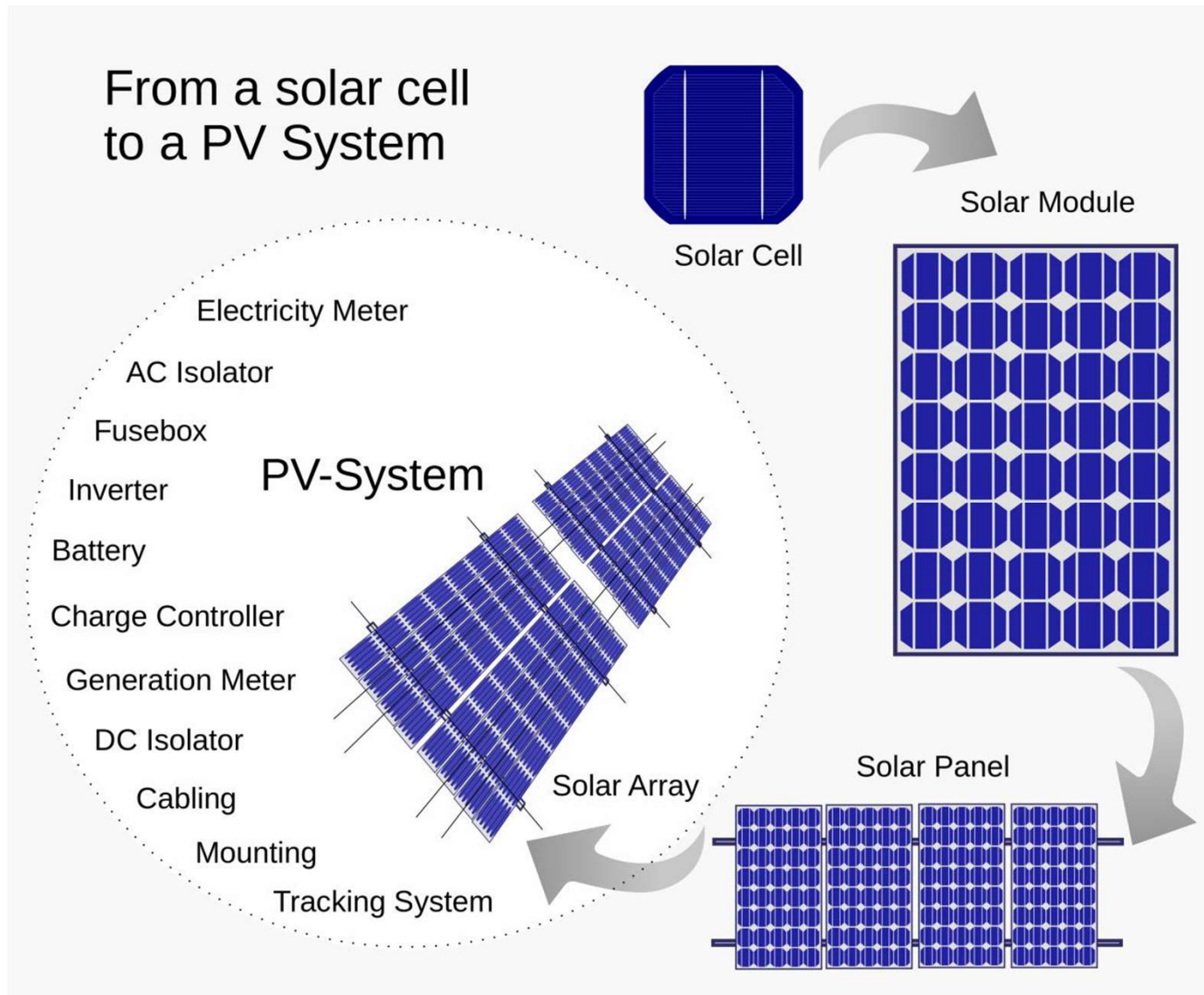


Semiconductors



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PV System



Levelized Cost of Energy

Levelized Cost of Energy Comparison—Unsubsidized Analysis

Selected renewable energy generation technologies are cost-competitive with conventional generation technologies under certain circumstances



Source: Lazard LCOE V14, 2020

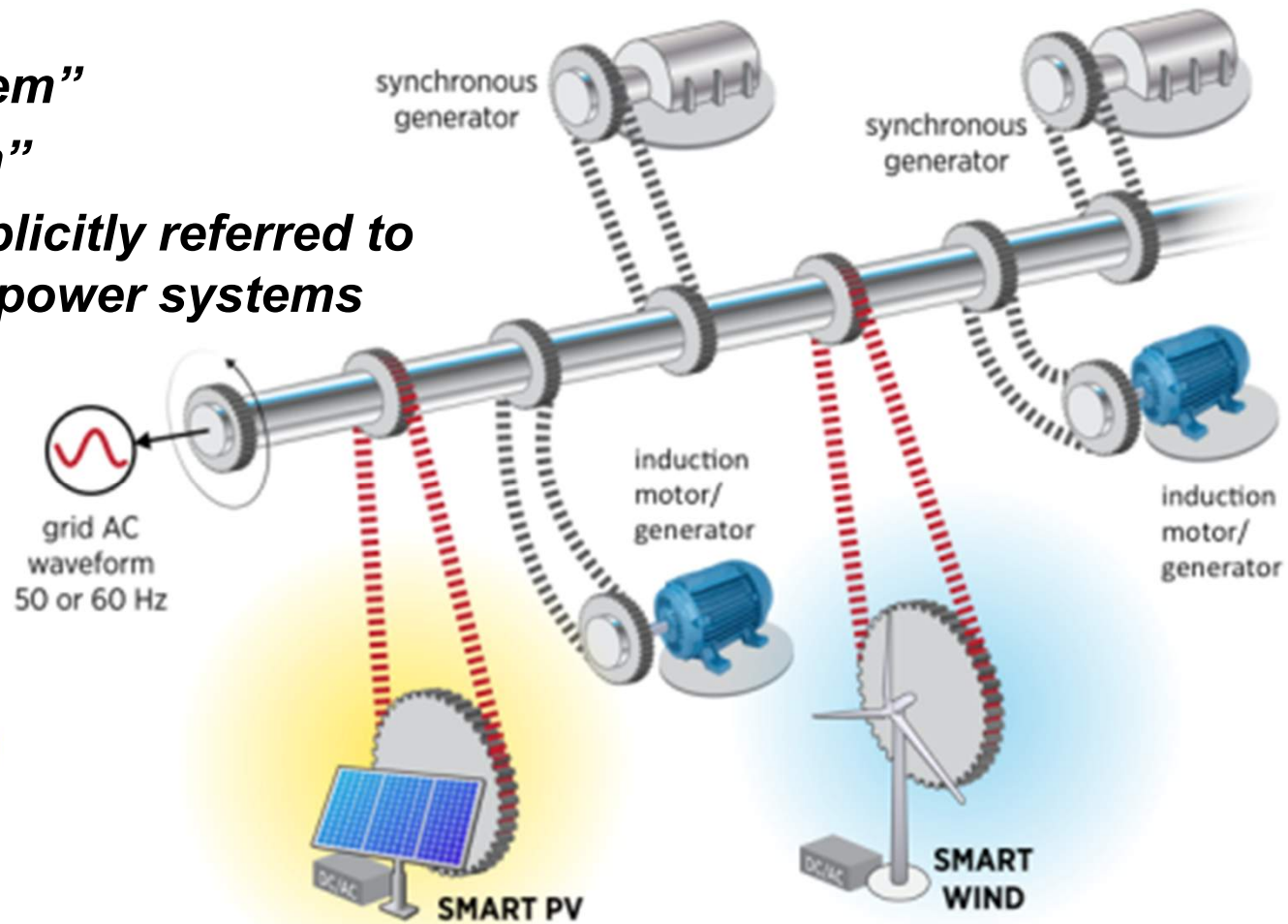
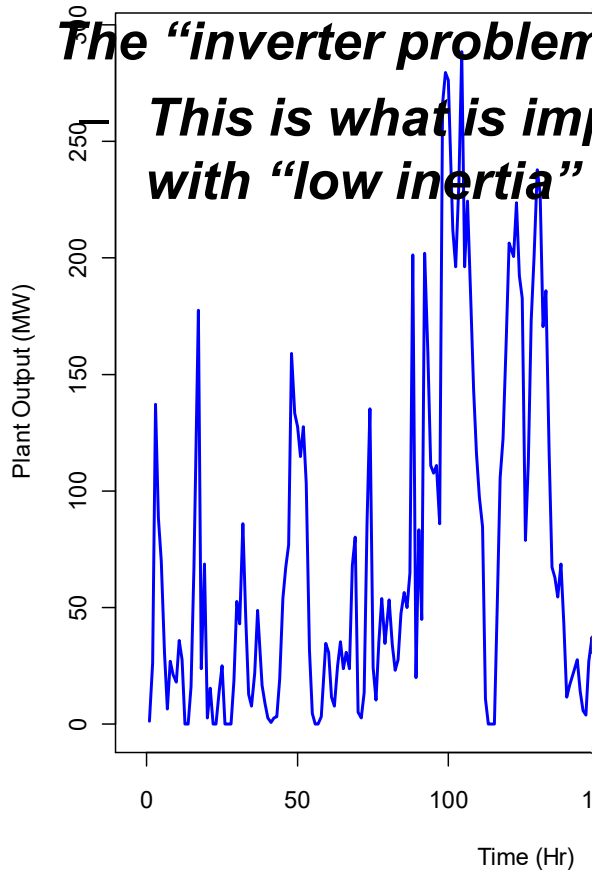
Wind and Solar Power are Variable, Uncertain, and Asynchronous

Wind Power

- **The “balancing problem”**

- **The “inverter problem”**

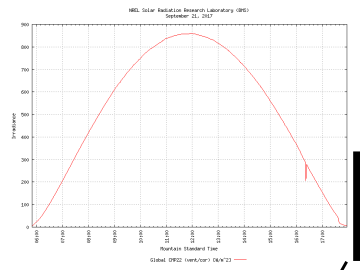
This is what is implicitly referred to with “low inertia” power systems



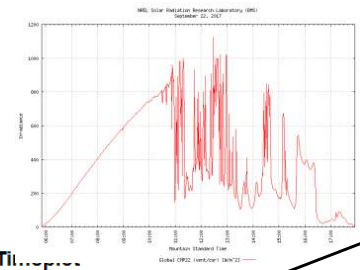
Real World Interlude: Voltage @ My House



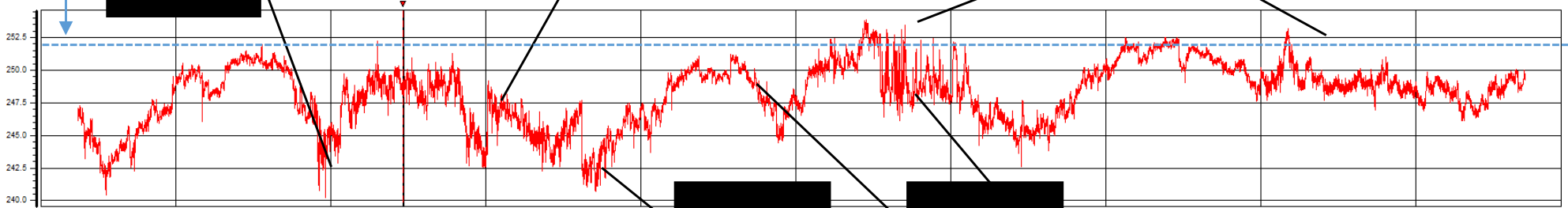
ANSI voltage limit:
1.05 p.u.



Tap/Cap?



Overtension



Cap?

Cap?

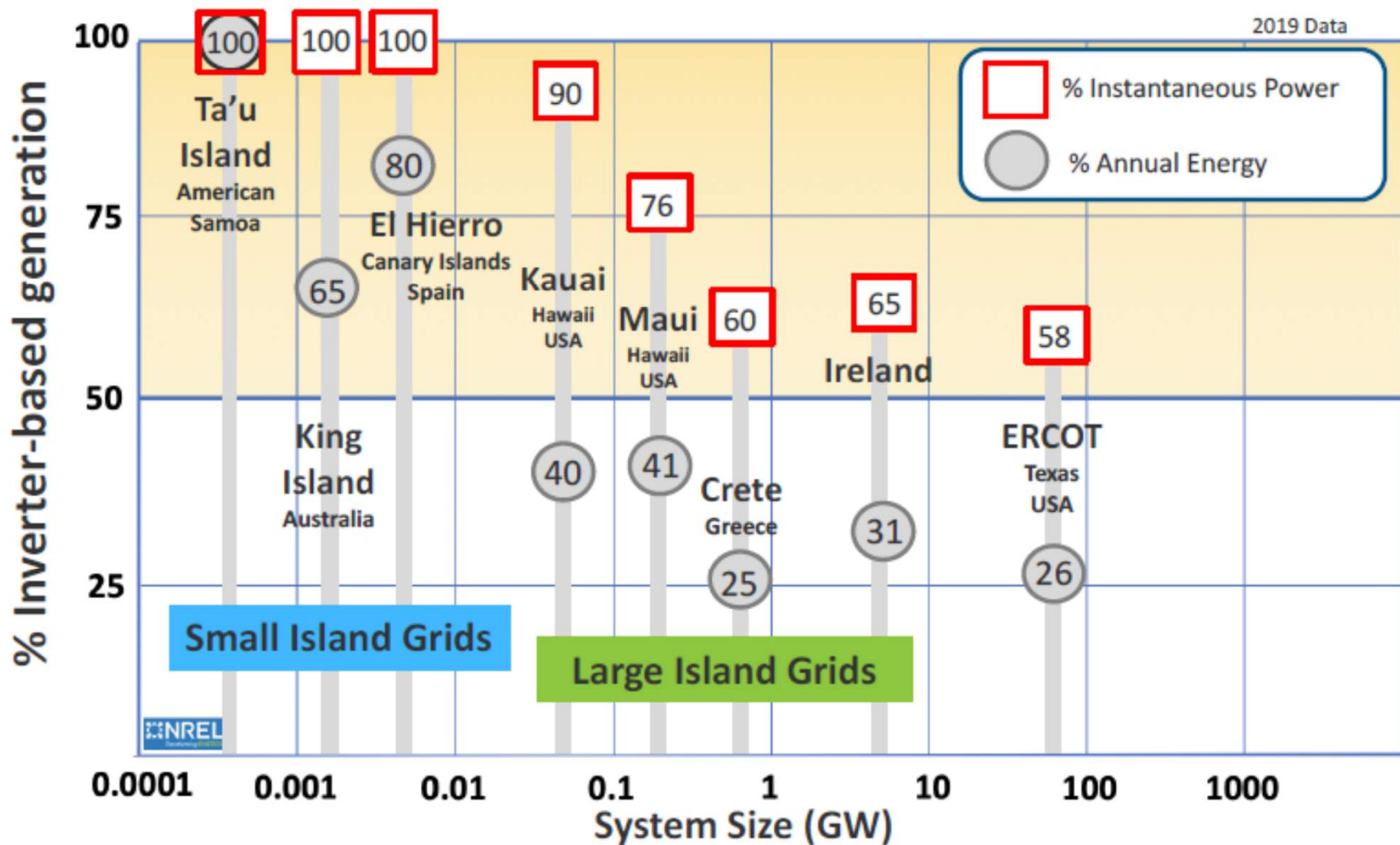
Tap?



PV Variability: ~ 5V
Model Prediction (without secondaries): ~ 2.16 V

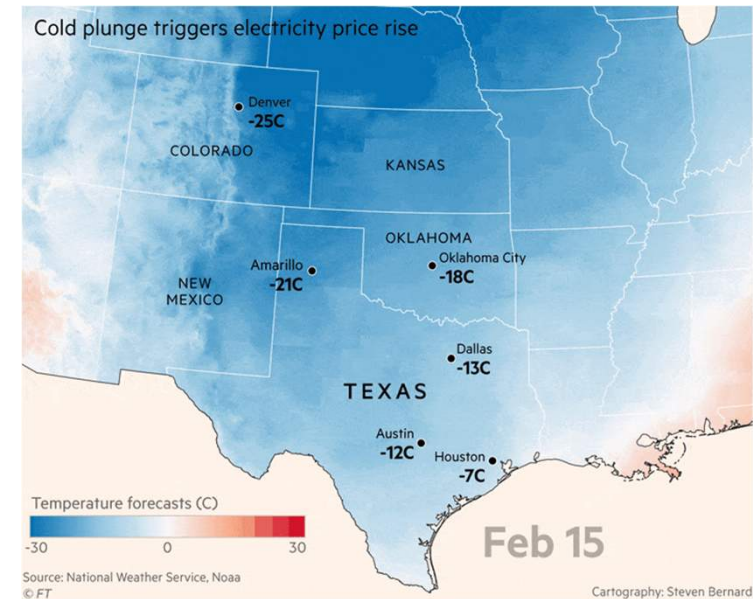
Event #2100 at 09/21/2017 11:43:29.800
Timed

Power Systems with High Instantaneous Shares of VIBRES



The Need for Power and Energy Systems Simulation

- The power system is becoming even more:
 - Complex with variable and distributed generators
 - Integrated with other energy systems
- The system has stringent reliability standards
- Changes to the system require massive investments with long timescales

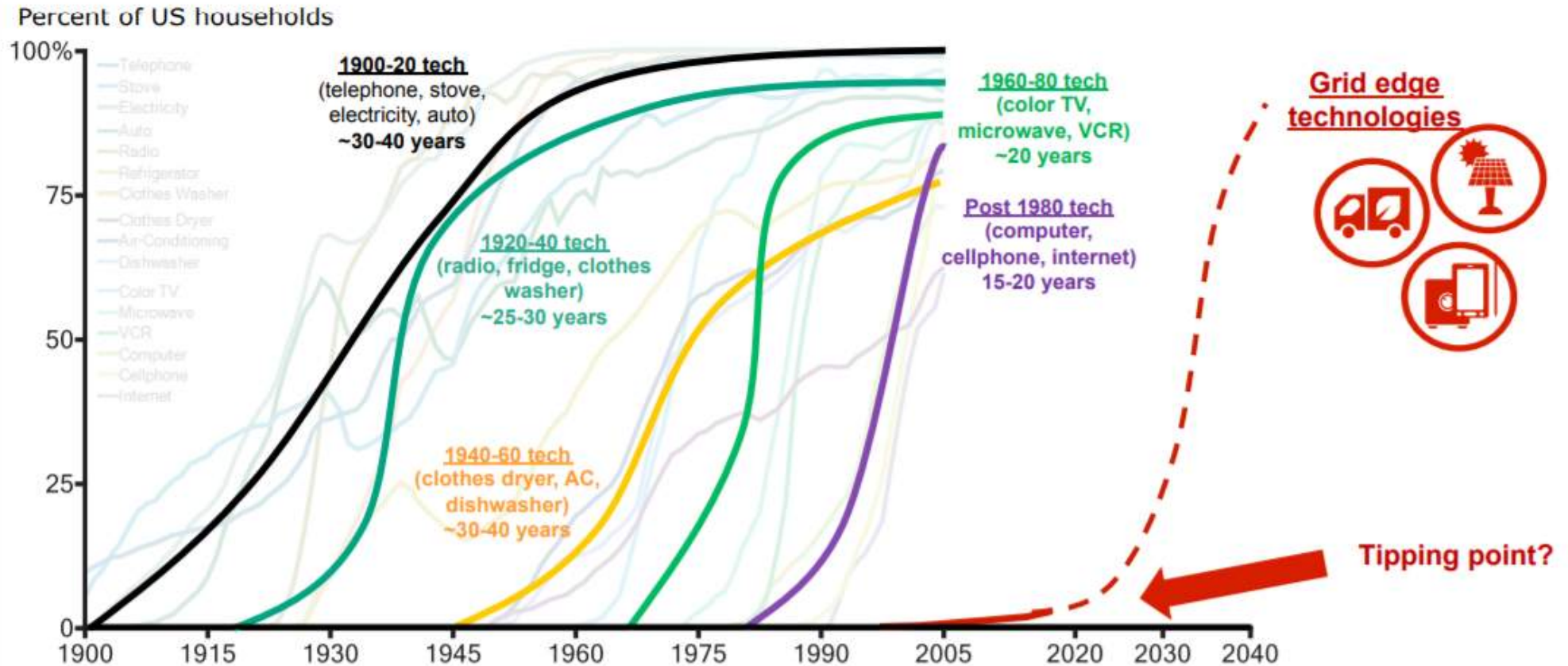


Therefore, we need computational models and high-quality data that can predict the impacts of new technologies before they are implemented in practice.

Grid Edge Technologies

- Renewable Sources
- Storage
- Electrification of Transportation
- Electrification of Comfort
- Smart Devices

TIME FOR TECHNOLOGIES TO REACH 80% PENETRATION



Source: World Economic Forum and New York Times

Prosumer Friendly Grid Edge Technologies



Distributed PV



Electric Vehicle



Home Battery
Energy Storage



HVAC Load



Electric Water
Heater Load

Understanding EV Impacts

- Vehicle type (battery size)
- Charging type and location
 - Level I, II, III?
 - Home charging only?
 - Public charging infrastructure?
 - *Dynamic wireless charging?*
- Driving patterns and timing
 - Urban or rural
 - Weather conditions
 - Weekend or weekday?
 - Multiple drivers?
- Charging timing
 - Unconstrained?
 - Utility controlled?
 - Incentivized? (Time of use or off-peak pricing?)

Vehicle Usage

- Trip distances
 - Weekend vs. weekday
 - Daily trips vs. special trips
- Number of trips
 - Weekend vs. weekday
- Chained trips?

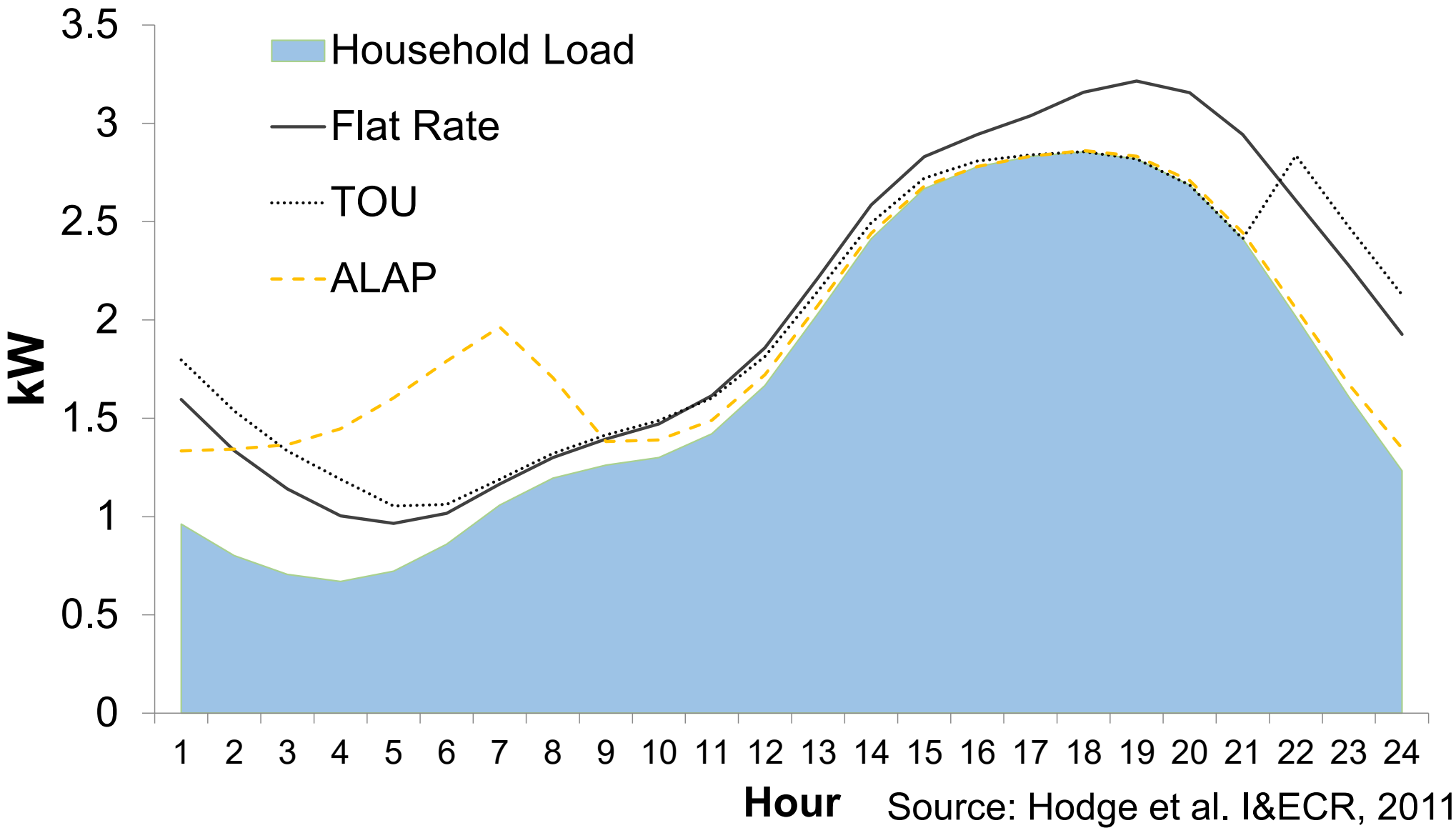
EV Charging Levels

- Level 1 (120 V):
 - 3-5 mph charge speed
 - 8-12 hours for a full charge
- Level 2 (240 V):
 - 12-80 mph charge speed
 - 4-6 hours for a full charge
- Level 3 (480V DC):
 - 3-20 miles per *minute*
 - 80% charge in 30 minutes;
 - not standardized with all vehicles



[Source: Forbes Wheels](#)

Vehicle Charging Patterns



Hour Source: Hodge et al. I&ECR, 2011

Vehicle Impacts of Charging

Table 1. Details on the Vehicle Use Differences for the Three Charging Patterns

	flat rate	TOU	ALAP
total distance traveled (miles)	28.70	28.50	28.34
gasoline miles (miles)	2.81	4.96	7.20
percent of miles on gasoline	9.80%	17.41%	25.41%
electricity consumed (kWh)	7.78	7.05	6.30
gasoline consumed (gallons)	0.06	0.10	0.14
cost of gasoline (cents)	12.26	21.63	31.41

Source: Hodge et al. I&ECR, 2011

Household Impacts

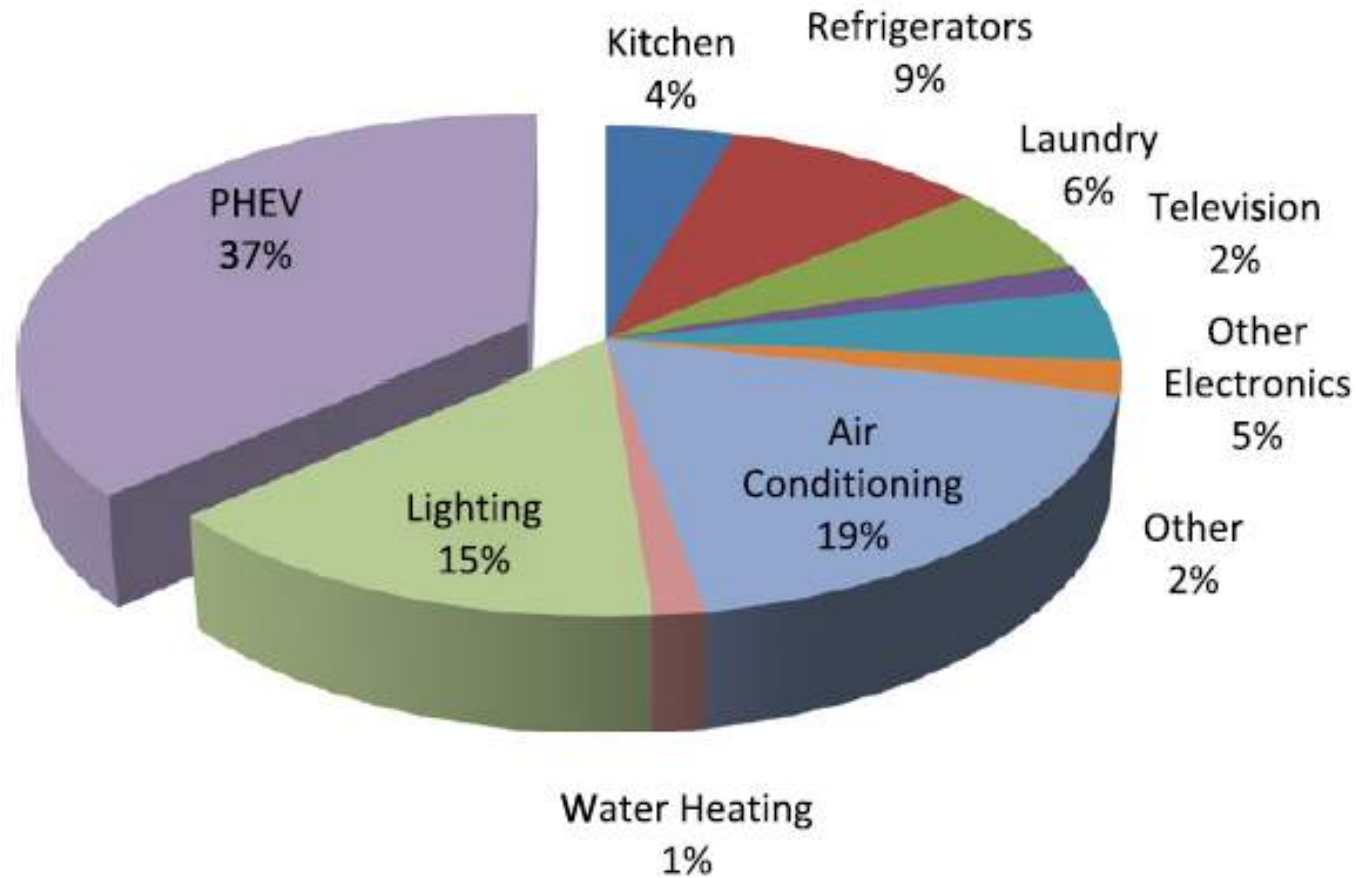
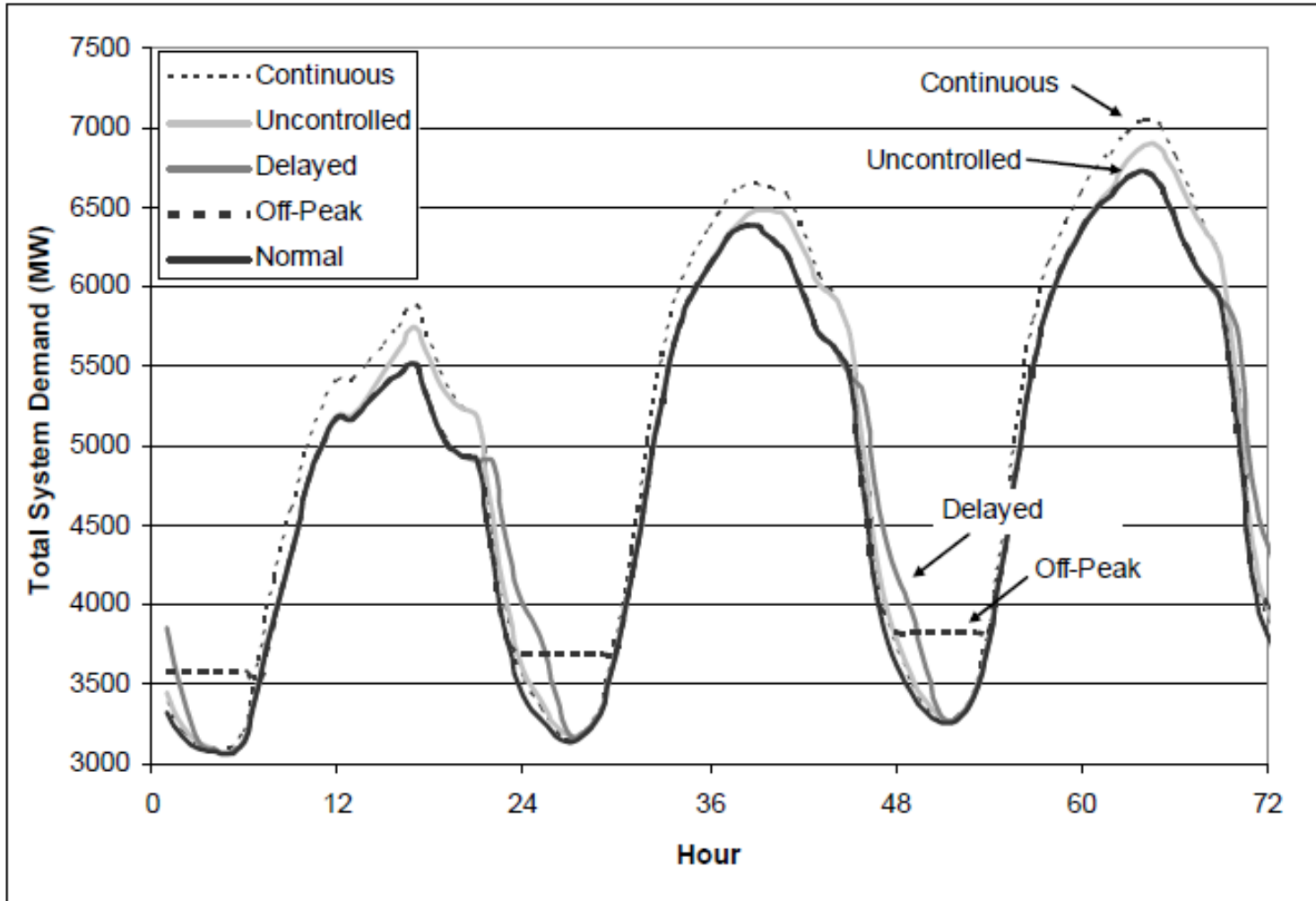


Fig. 4. Breakdown of electricity consumption of an average Californian household in summer with the addition of PHEVs.

Source: Huang et al. Energy Policy, 2011

Bulk Impacts – Xcel Case

- 500,000 EVs in Xcel Colorado territory (1/3 vehicle fleet)
- Summer conditions shown at right



Source: Parks et al., NREL 2007

Consumer Issues

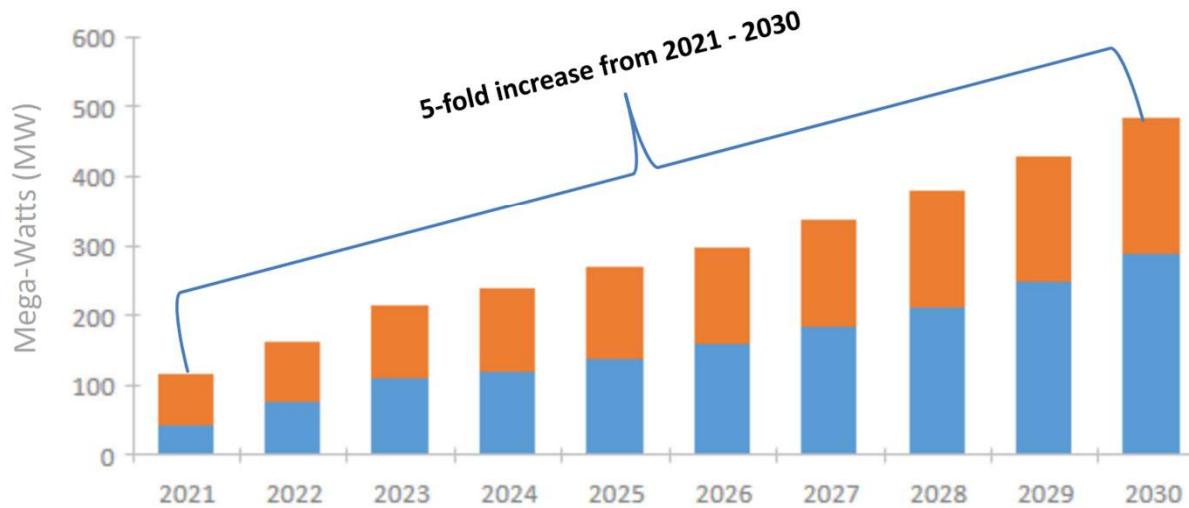
- Public charging station availability
- “Range anxiety”
- Additional capital costs
- Battery degradation from increased cycling
- “Full charge whenever I need it”
- Financial incentives

Power Distribution System Impacts

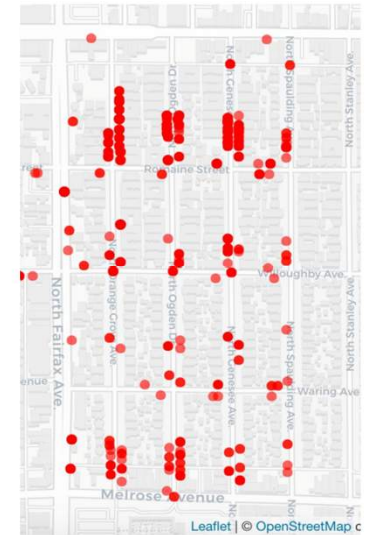
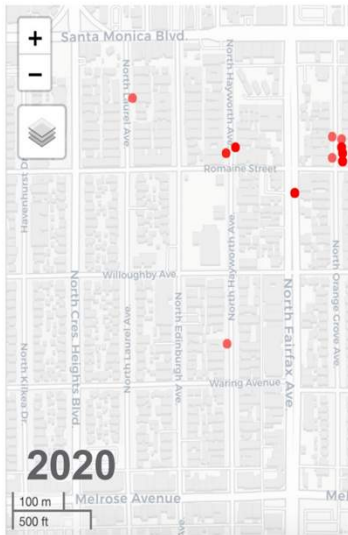
- Distribution challenges:
 - Headroom disappears
 - Lack of equitable adoption creates imbalance

Coincident EV Charging Peak Contribution by Voltage Class

■ 34.5kV EV Peak Contribution ■ 4.8kV EV Peak Contribution

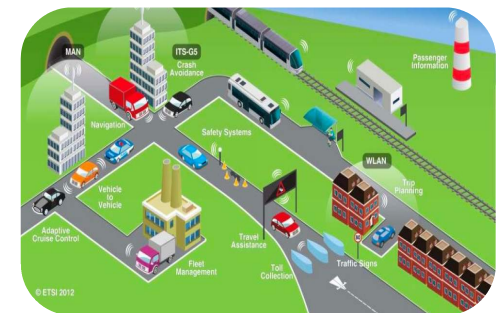


5-fold increase from 2021 - 2030

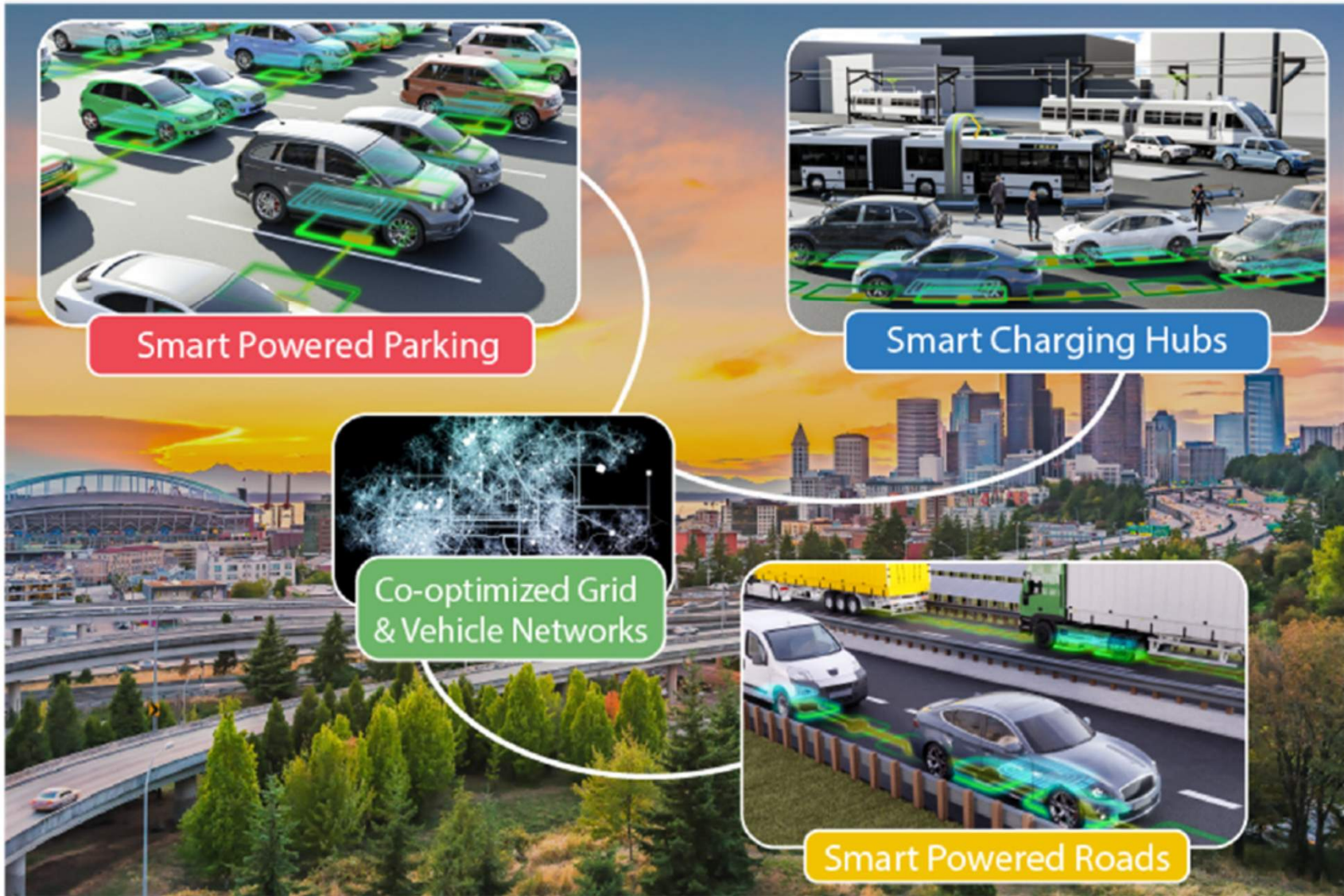


Source: LADWP EV Charging Peak – NASEM EV Workshop 2021
Source: PNNL LDV EV Adoption Model – Michael Kinter – NASEM EV Workshop 2021

ASPIRE Engineering Research Center



Future Transportation-Grid Interactions



Wireless Power Transfer (WPT)

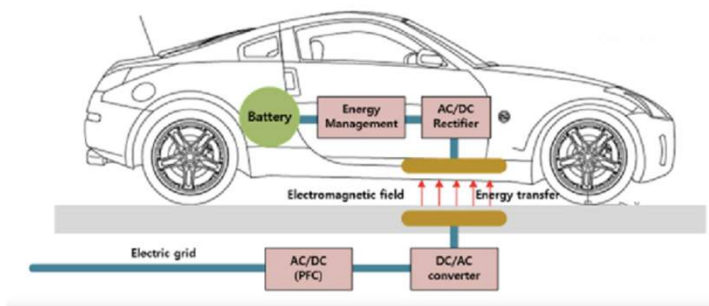


Figure 2.2: A Diagram of a 4kW Magnetic Resonance Wireless Power Transfer System taken from Choi et al. [5]

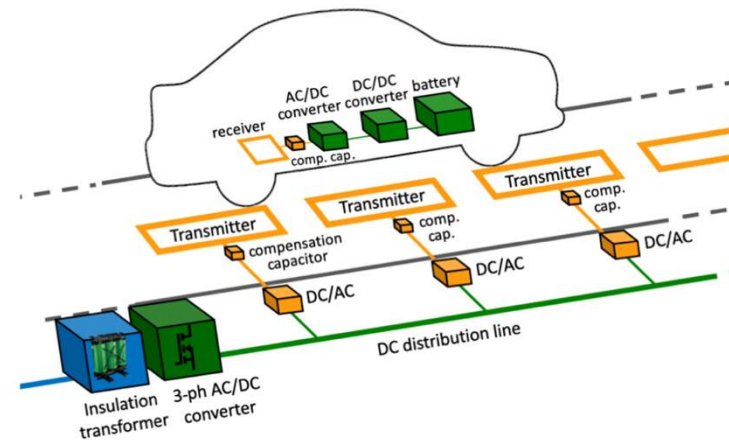
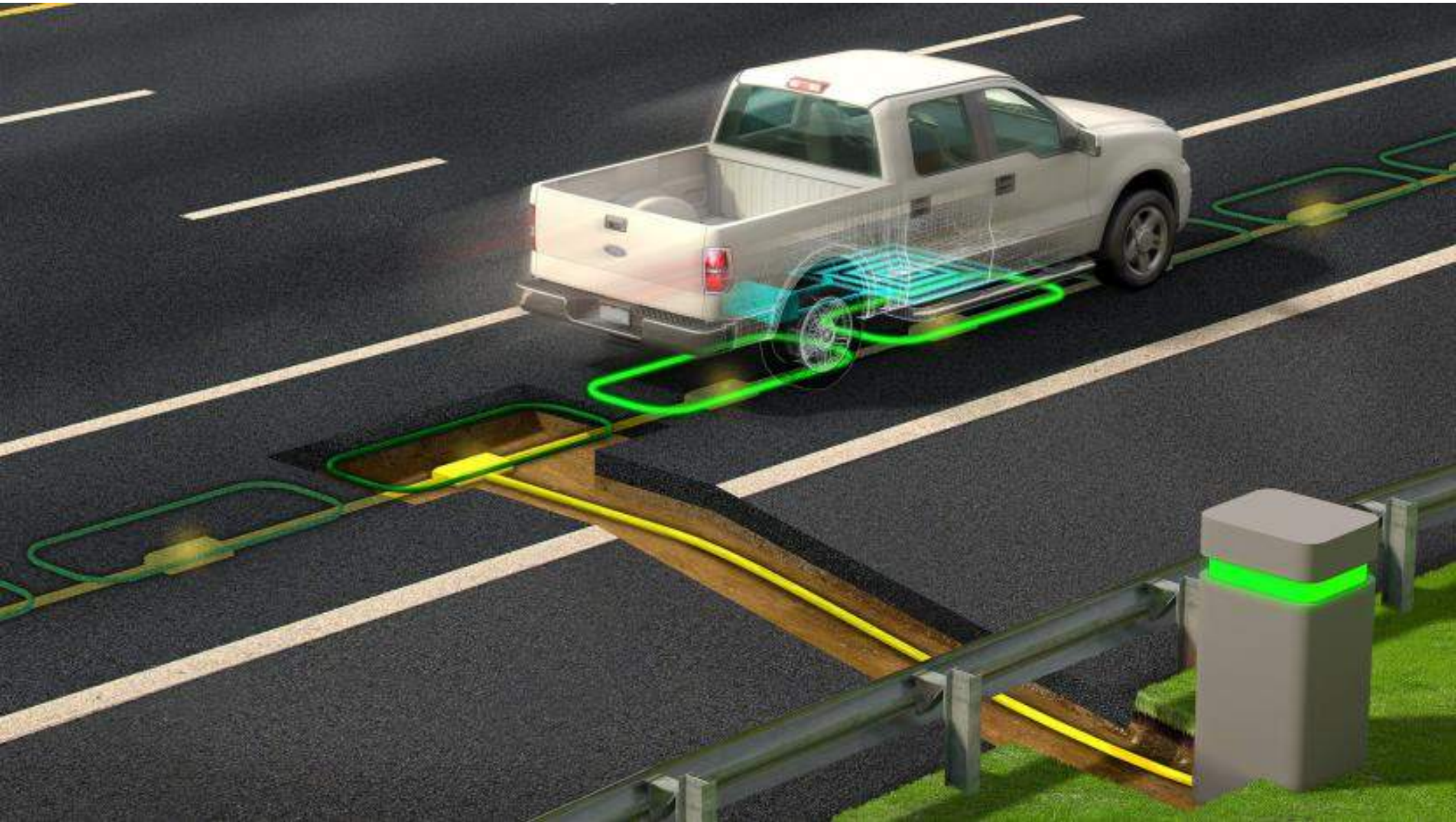
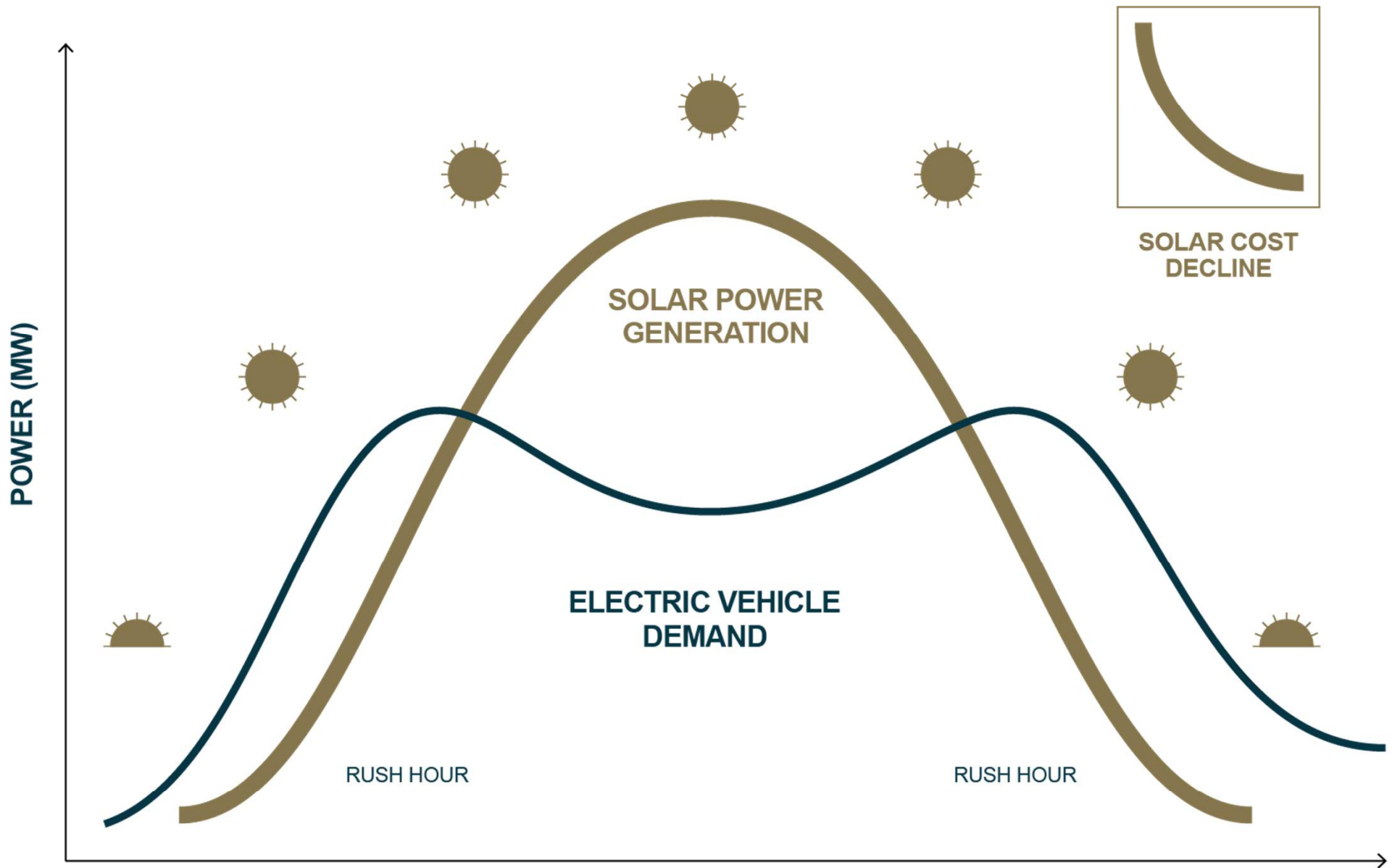


Figure 2.8: Electrical infrastructure of PoliTo DWPT charging lane [1]

Dynamic Wireless Vehicle Charging

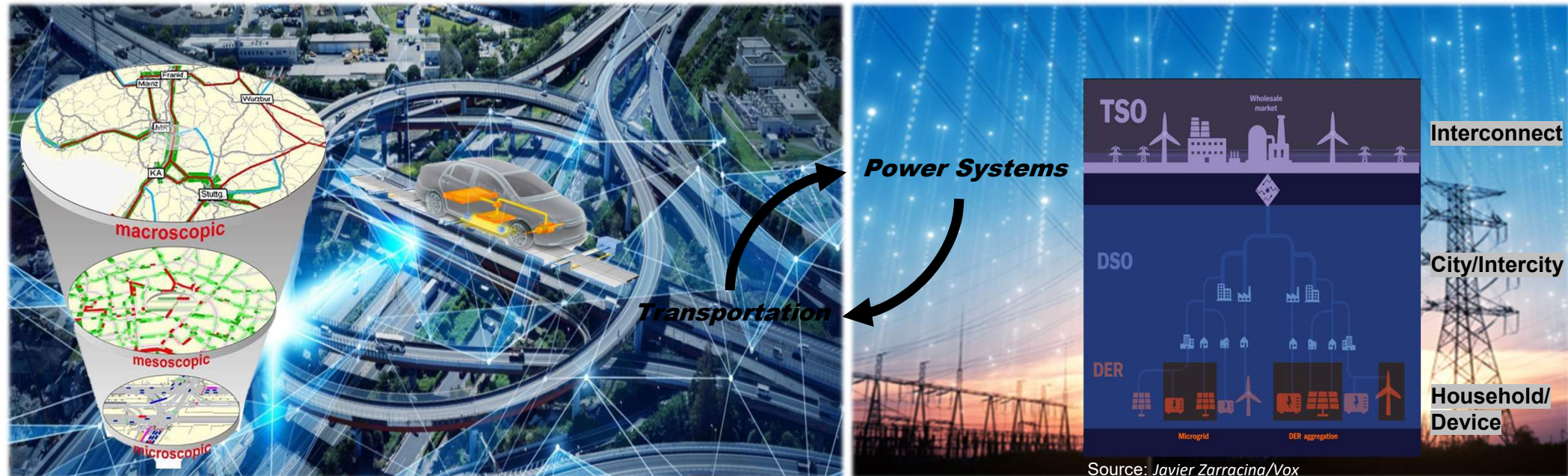


Wireless/Solar Timing



ASPIRE's Co-Simulator

The Impact of Dynamic Wireless Charging



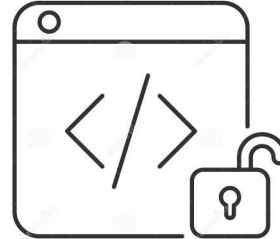
Driving Conditions



Electricity Prices



Open-Source



Energy Justice



Health & Air Quality



Regional Case Study

- PCM to evaluate regional impacts of DWPT
 - Establish relationship between in-transit EV charging and solar curtailment

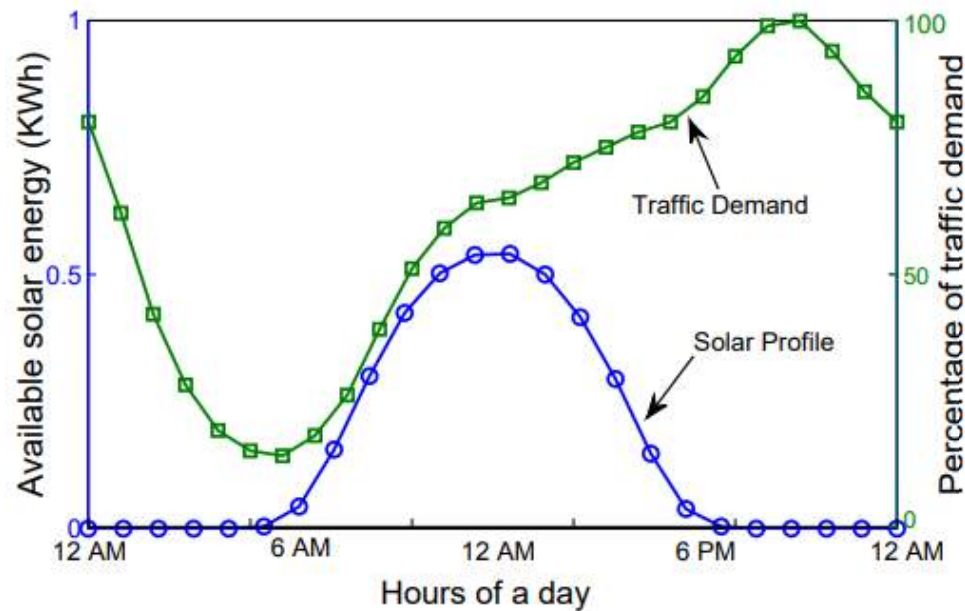
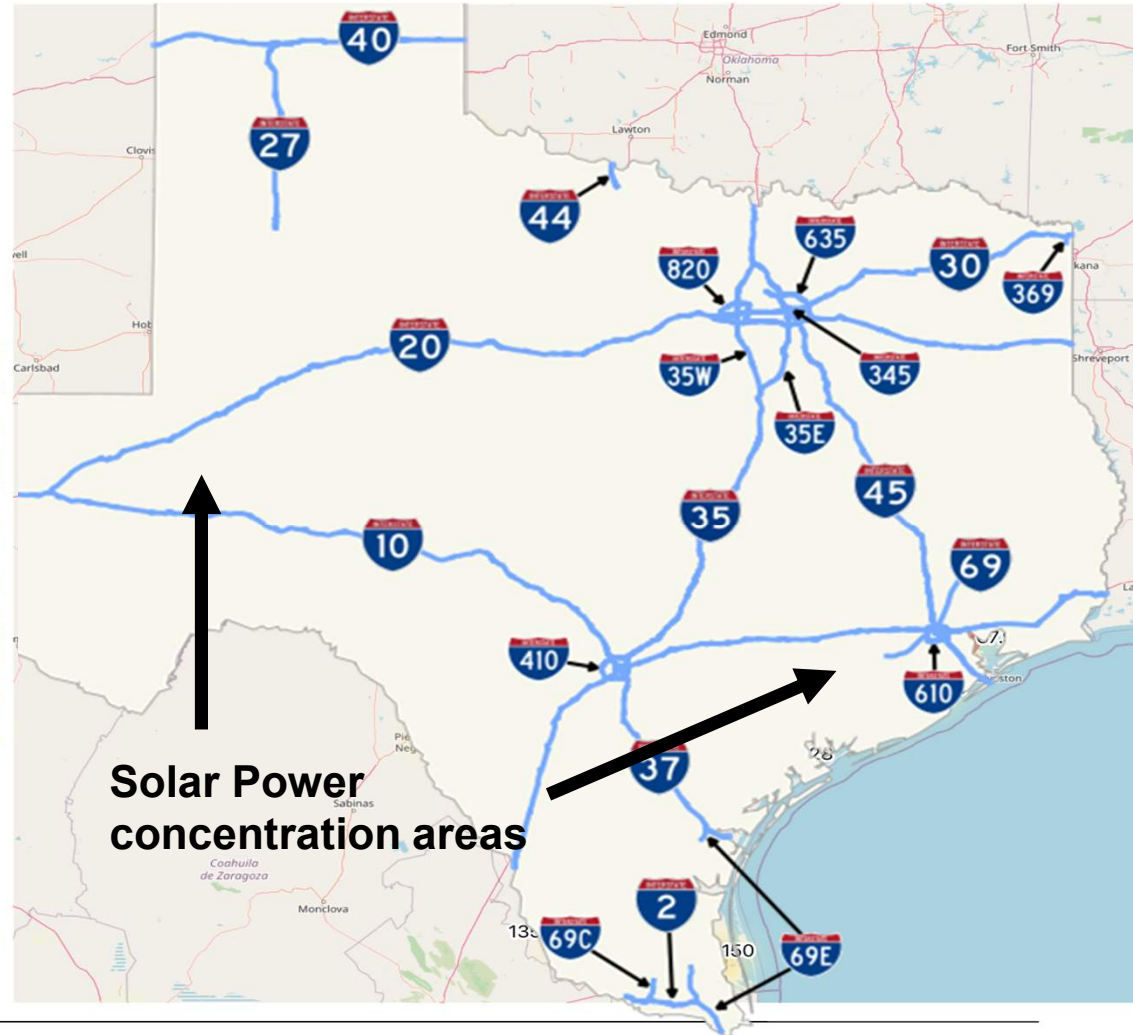
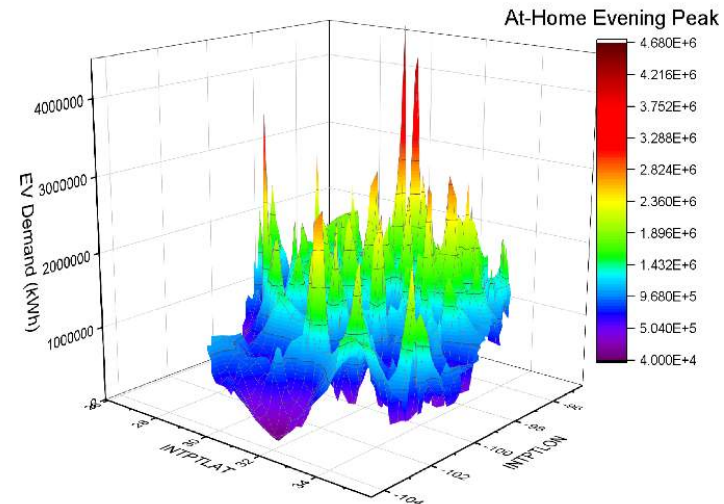
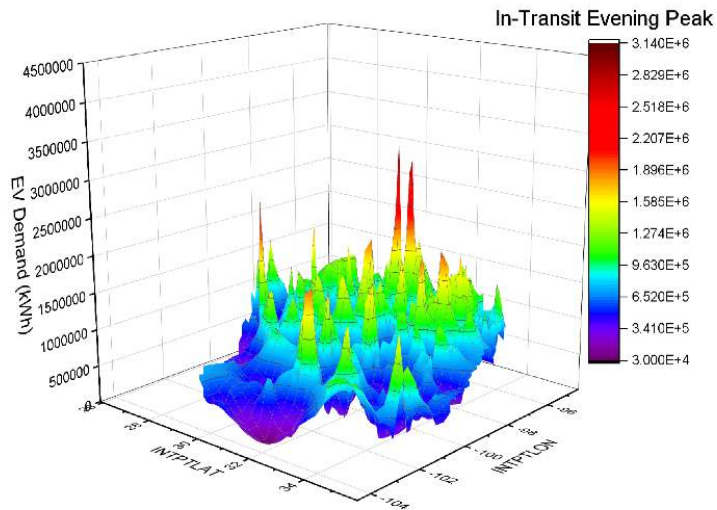
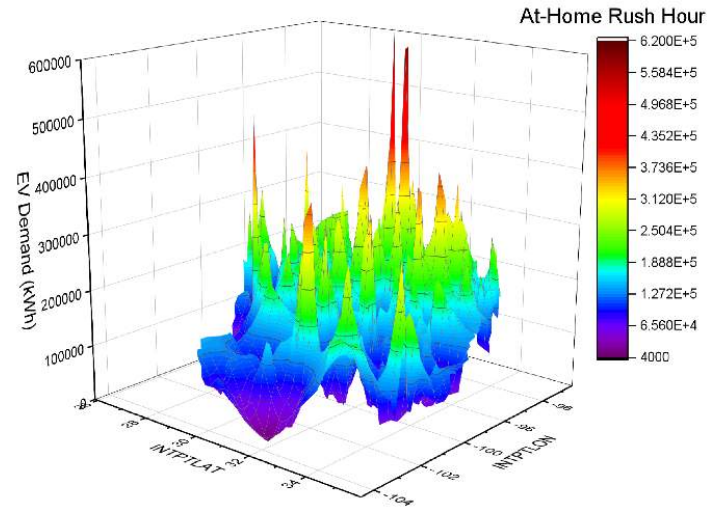
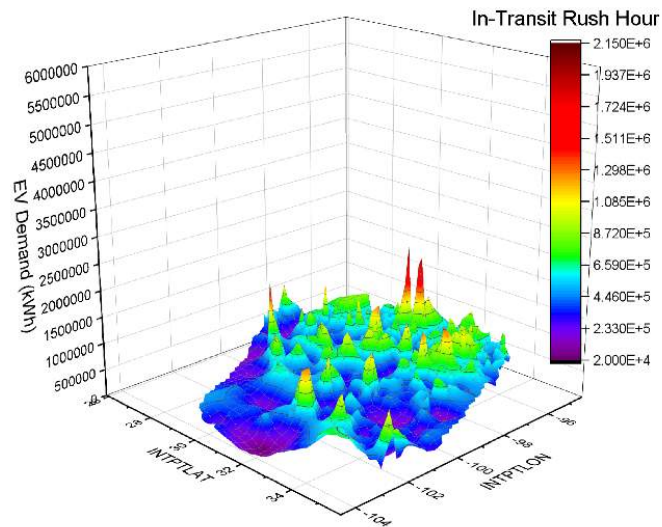


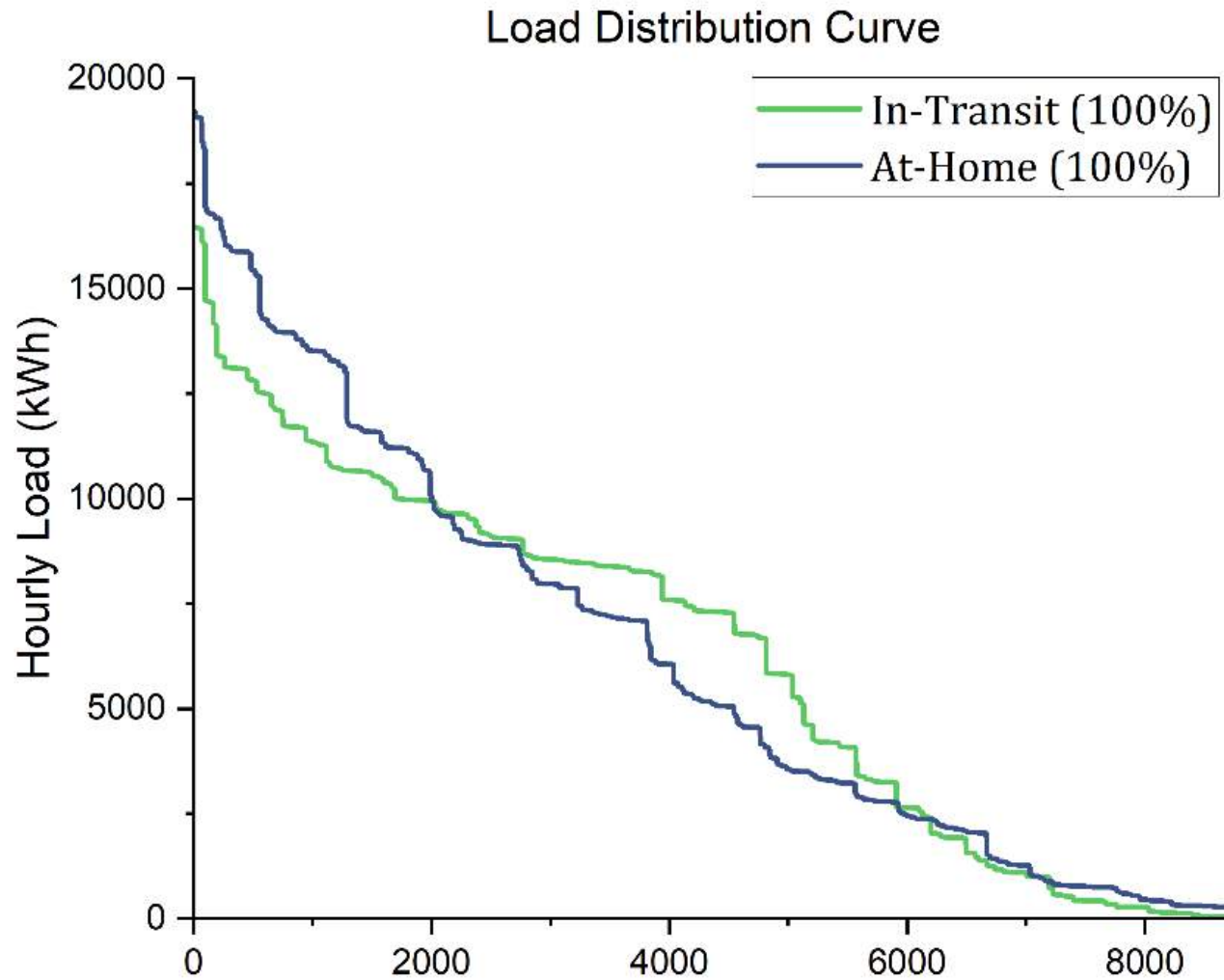
Fig. 2. Average hourly solar energy generation and daily traffic profile of a residential area.



In-Transit Charging

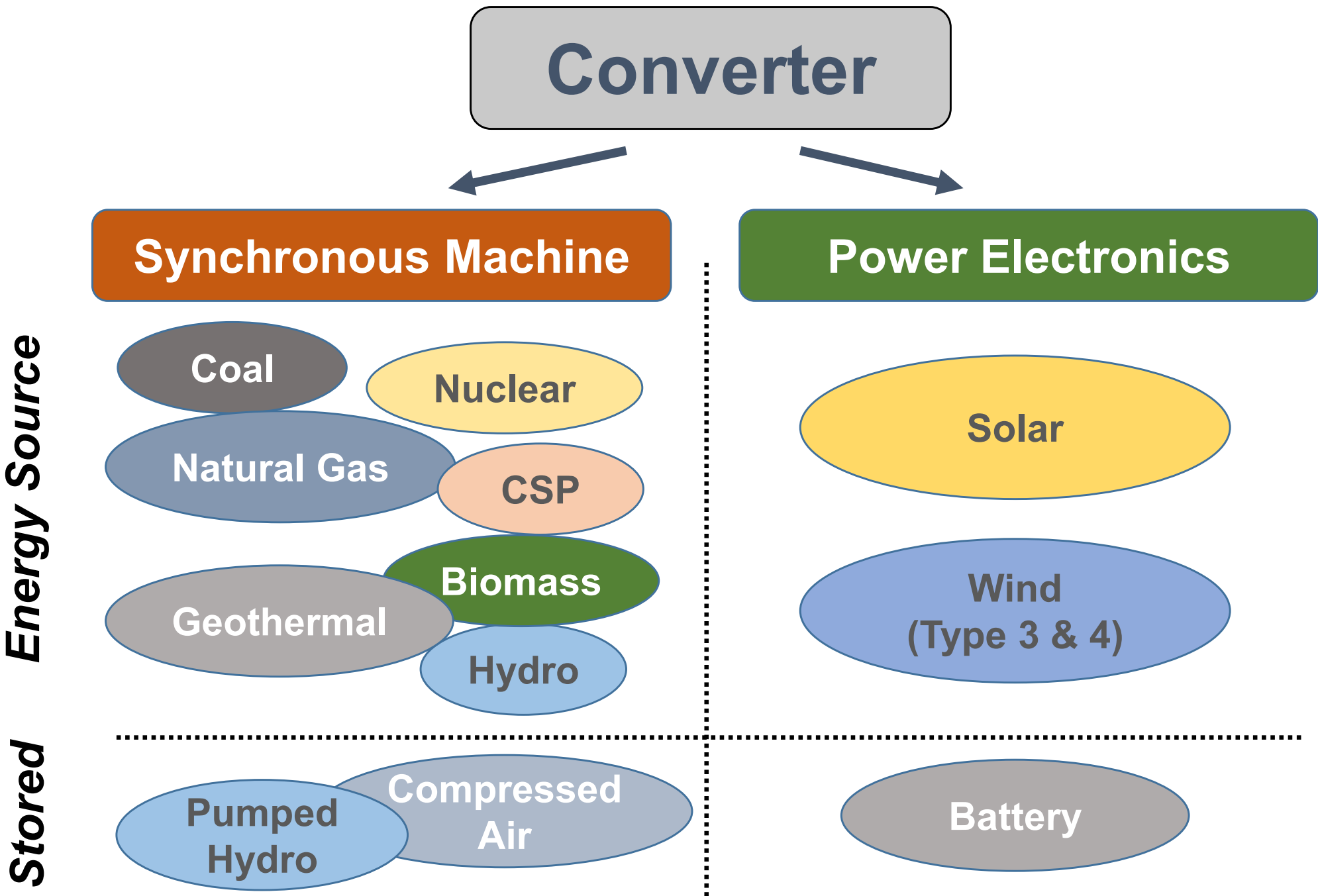


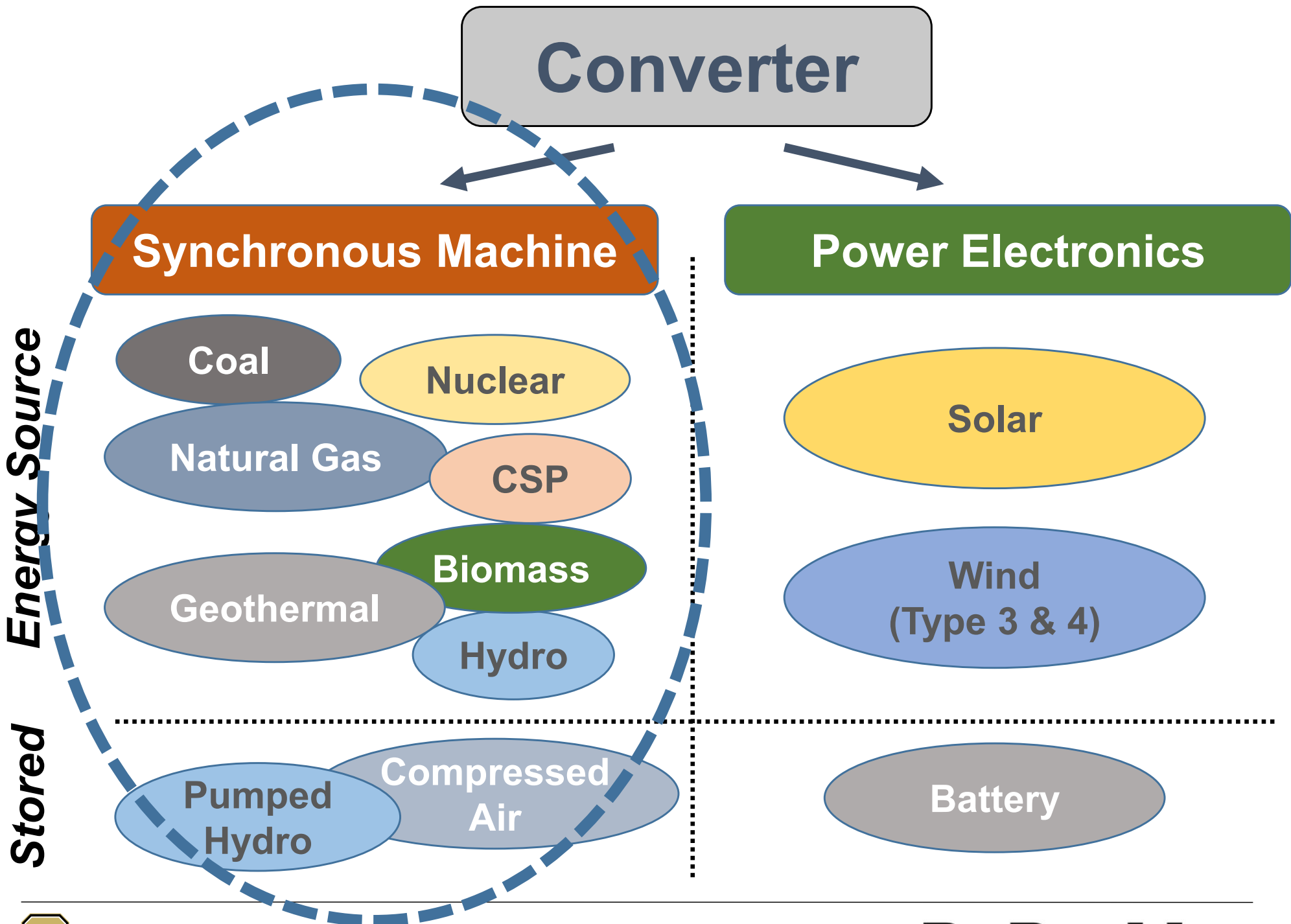
Additional ERCOT EV Load



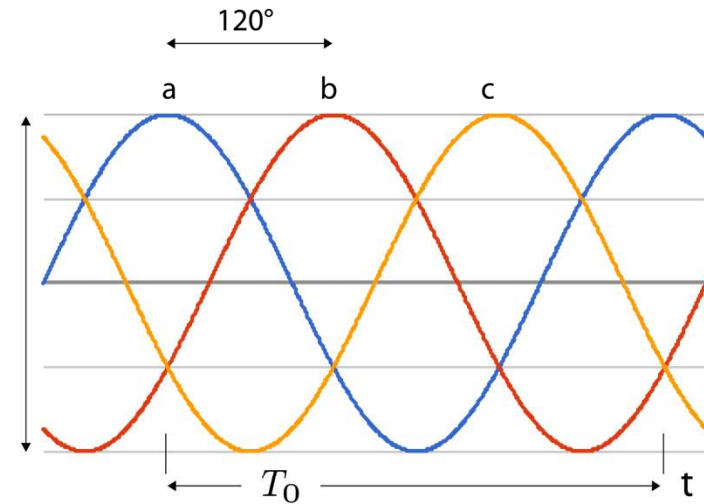
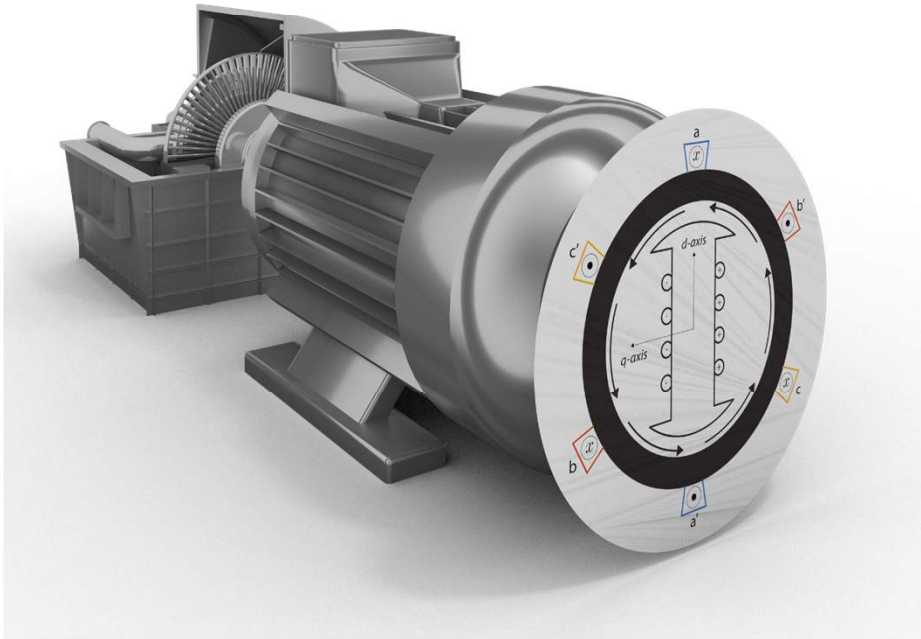
EV Impacts Summary

- Rapid adoption of EV's will strain the bulk-electric and distribution grid systems
- Innovative charging technology such as DWPT can alleviate peak loads
- Co-simulation models highlight system-level impacts to both transportation and power





Synchronous Machine Converters (Generators)



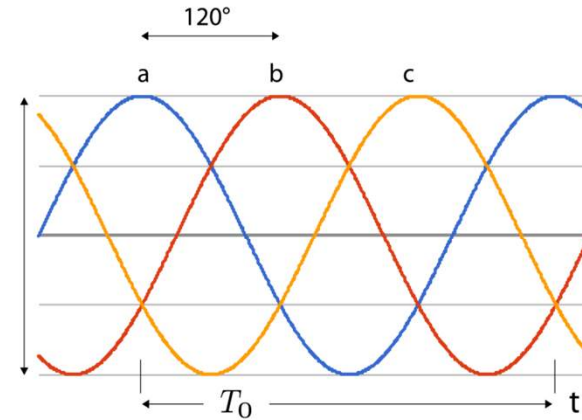
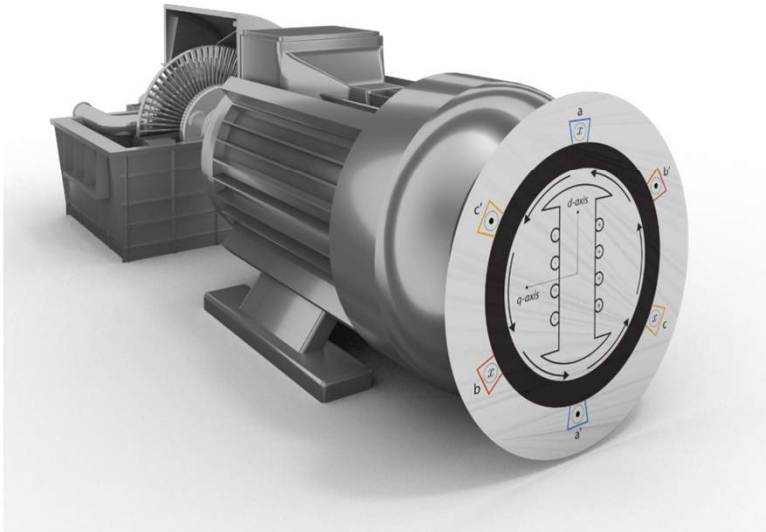
T_0 = one rotor revolution if single pole pair

Create steam or hot air by
burning or fissioning fuel, use
this fluid to rotate a generator

$$\omega_0 = \frac{2\pi}{T_0} = \frac{P}{2} \omega_{shaft}$$

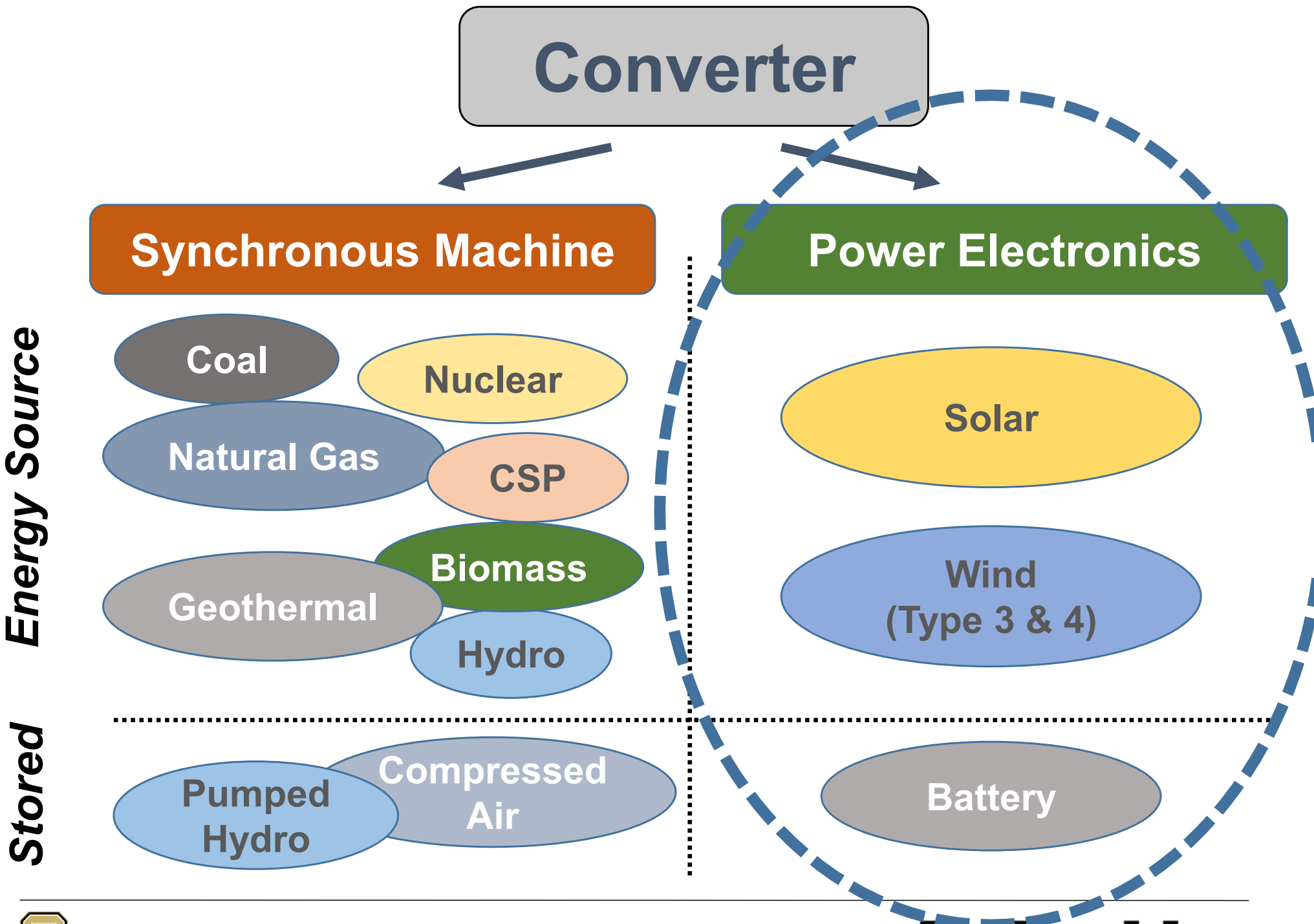
... hence, synchronous

Synchronous Machine Converters (Generators)



T_0 = one rotor revolution if single pole pair

- Large mass is electromagnetically coupled to AC power system
 - Embeds inertial characteristics in power system
 - ***Naturally forms a sinusoidal output***
- Governors are relatively slow (> 0.5 second response time)
 - Means a load disturbance is initially met by inertial energy
- Large, transient overcurrents in faulted conditions (4 – 7 times rated)
 - Basis for many protection systems



Two Terminal: *diodes*



indiamart.com

Three Terminal: *MOSFETs, BJT, IGBTs*



digikey.com

Four Terminal: *thyristors*



electricsoftstarter.com



extreme-ltd.com

Renewable Interfacing Devices

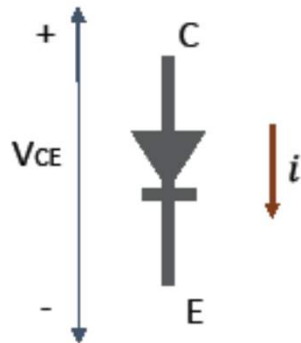


ABB.com

Historically: HVDC Applications

Diode Operation:

2 Terminal



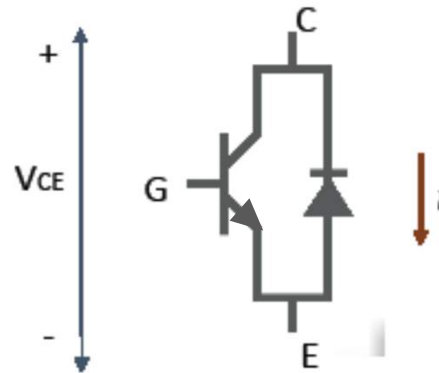
In General

$i > 0$; if $V_{CE} > 0$

$i = 0$; if $V_{CE} < 0$

Transistor Operation:

3 Terminal



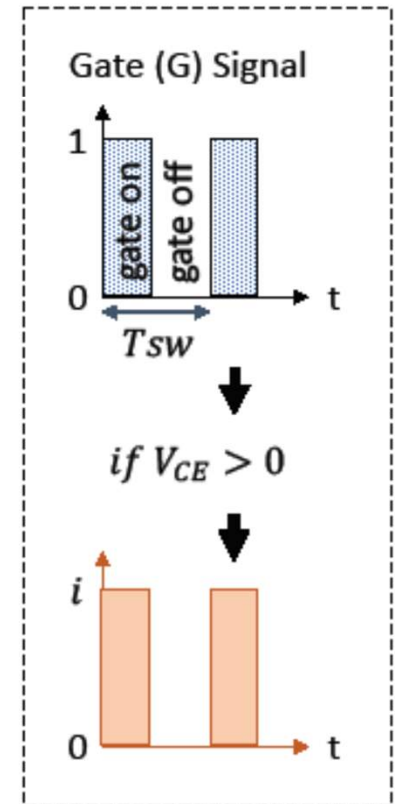
In General

$i > 0$; if $V_{CE} > 0$, & $G > 0$ (i.e. on)

$i = 0$; if $V_{CE} > 0$, & $G = 0$ (i.e. off)

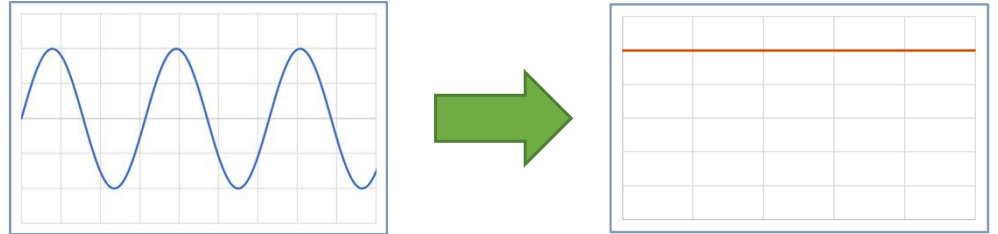
$i < 0$; if $V_{CE} < 0$ (due to body diode)

Digital Control

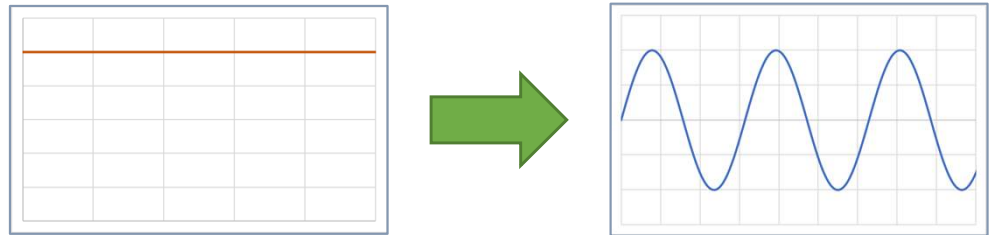


Four Basic Topologies

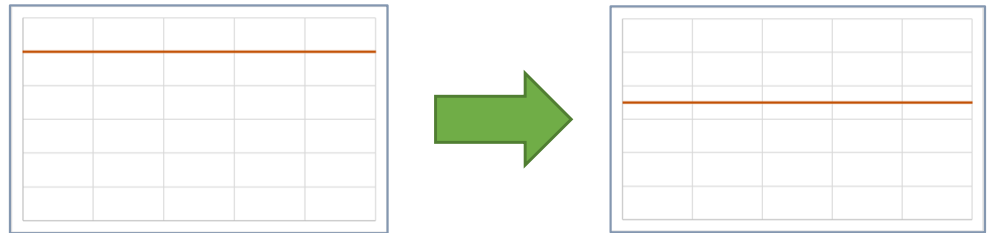
- **Rectifier (AC to DC):**



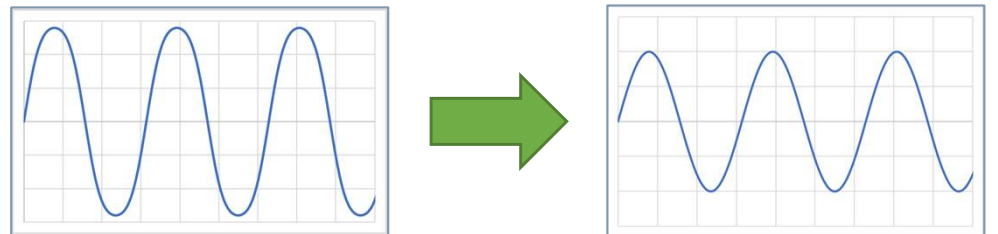
- **Inverter (DC to AC):**



- **Converter (DC to DC):**



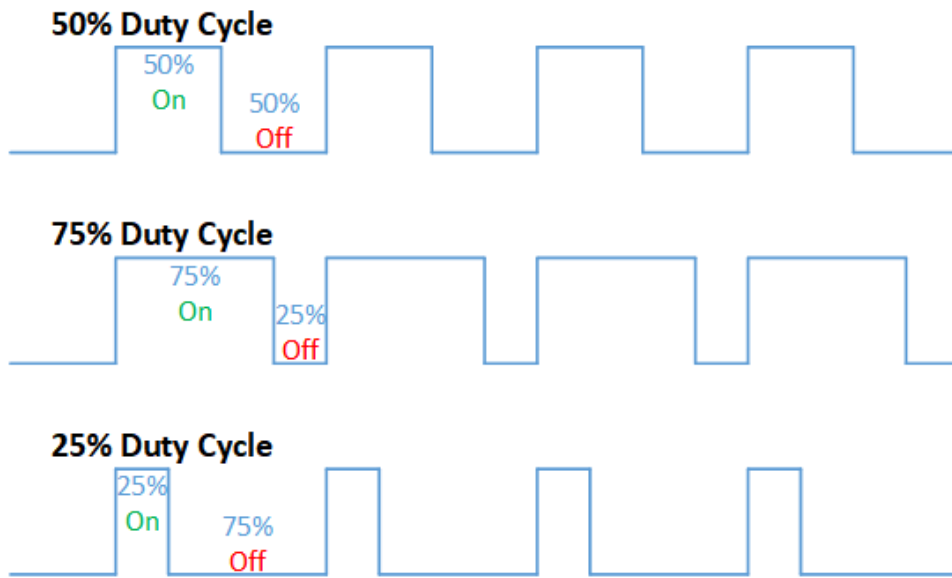
- **Cycloconverter (AC to AC):**



Rapid Switching:

Duty Cycle: time 'on' per cycle

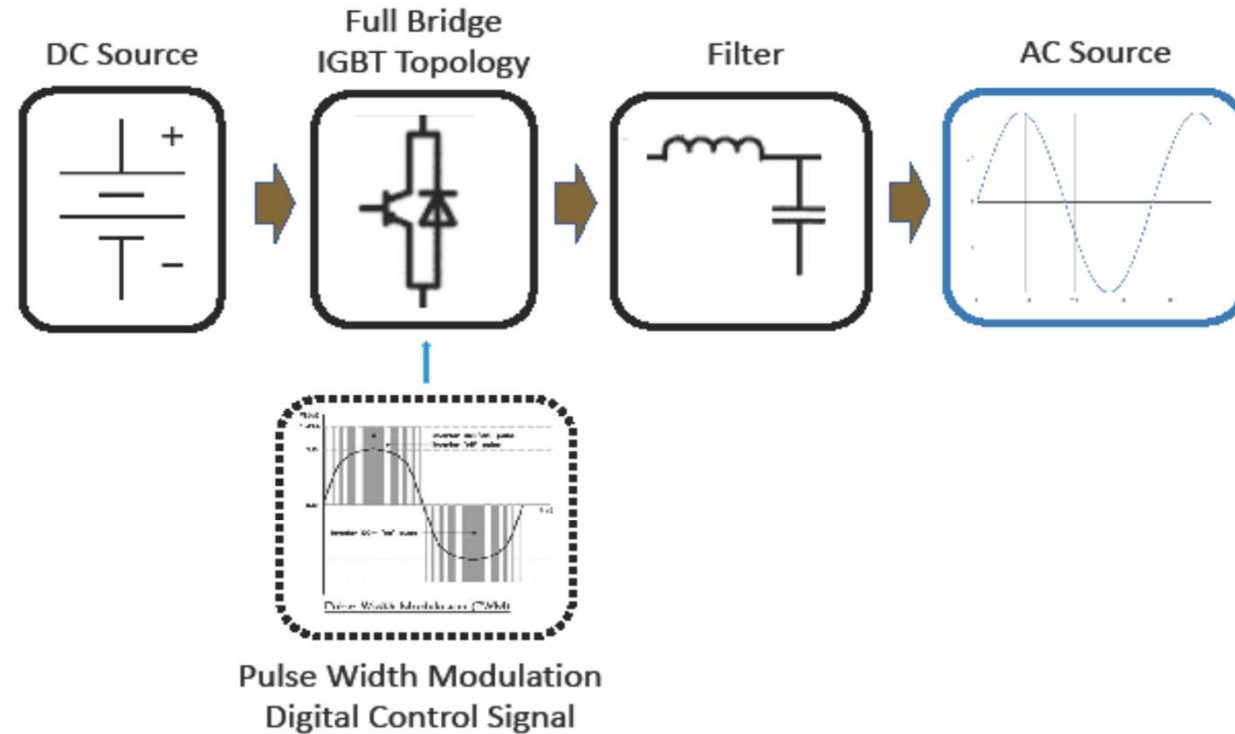
$$D = \frac{T_{on}}{T_{switch}}$$



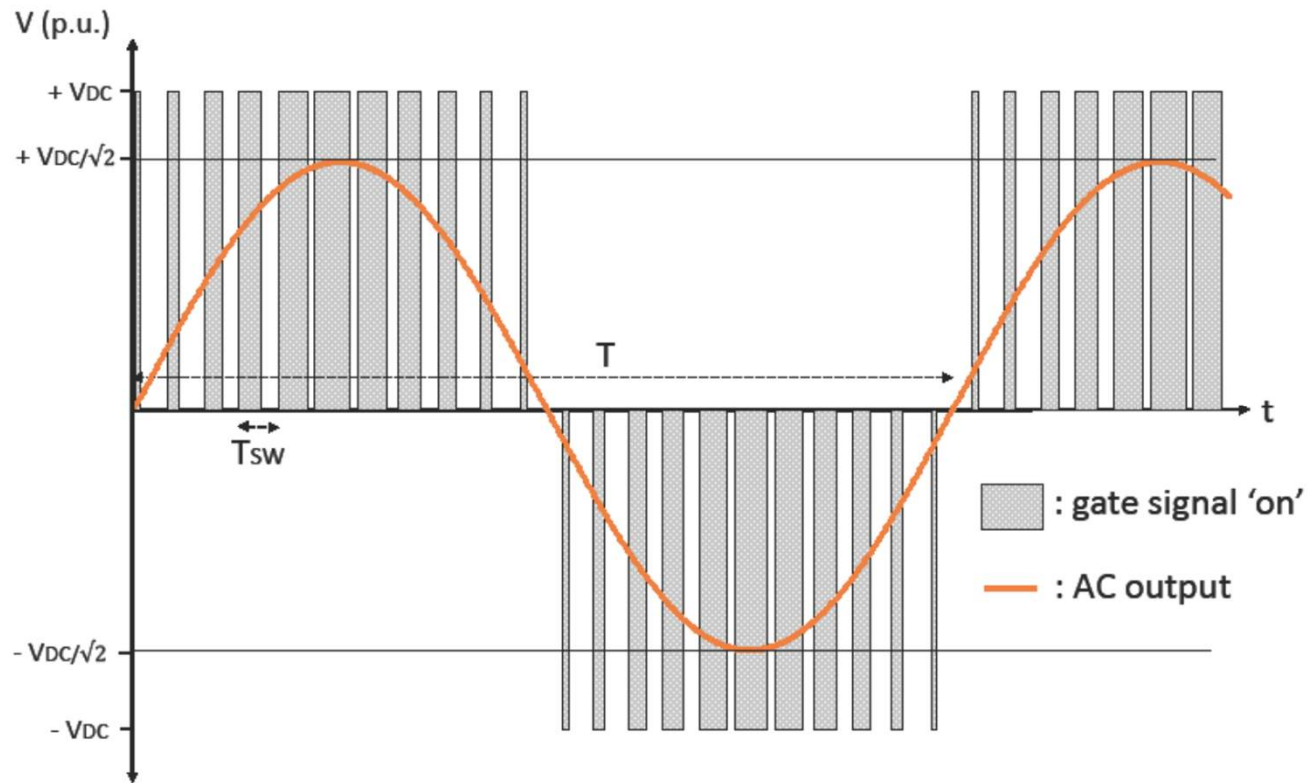
wikipedia.com

- Very rapid switching;
 - $f_s = 1 - 1,000 \text{ kHz}$
- In general, larger f_s yields a larger bandwidth; i.e. greater control
- But some non-ideal switching losses occur per cycle
 - proportional to switching frequency, f_s
- A trade off; higher power devices with smaller switching frequencies ($f_s = 1 - 5 \text{ kHz}$) -> less control, smaller losses

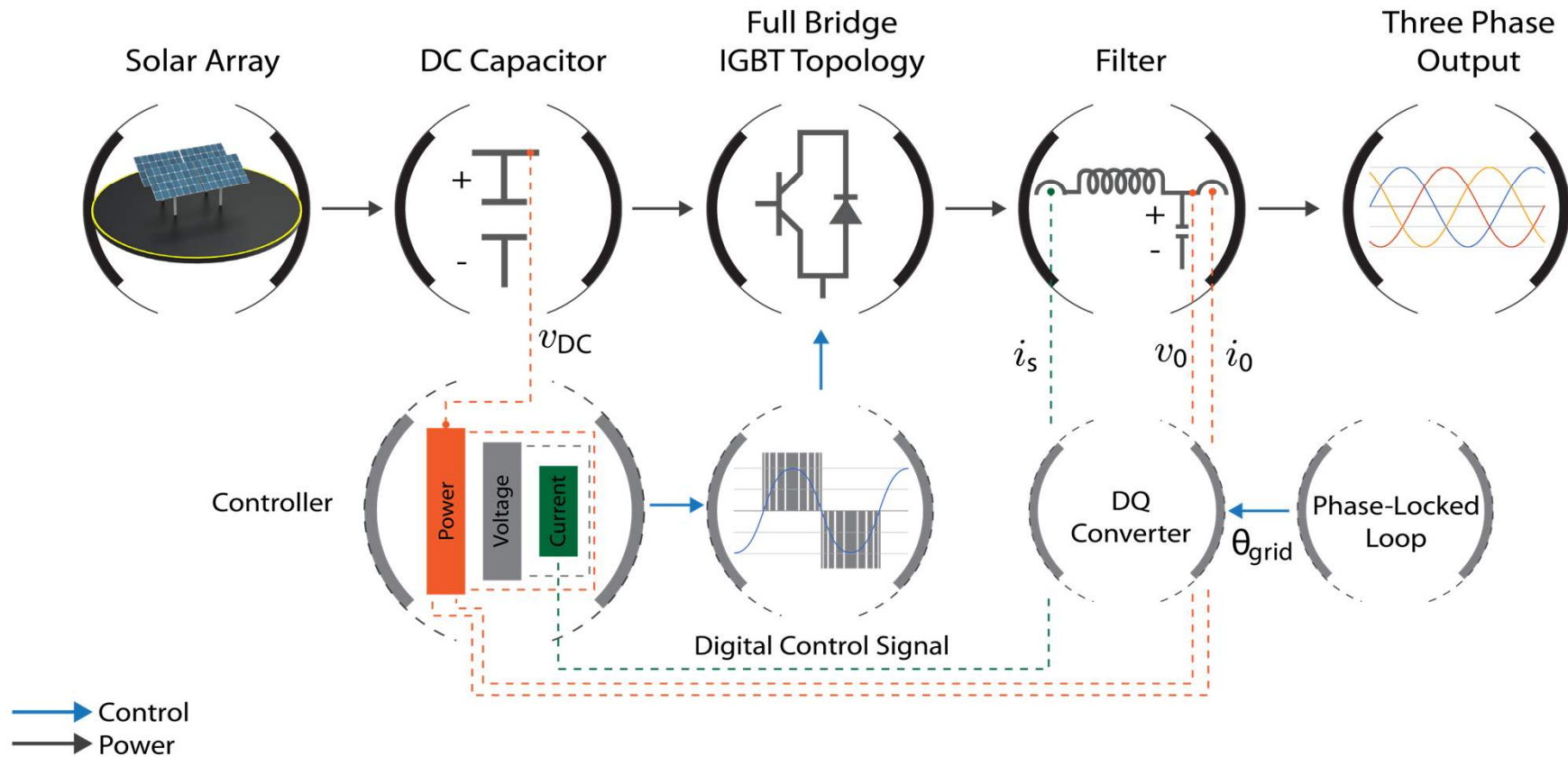
The Ubiquitous Inverter:



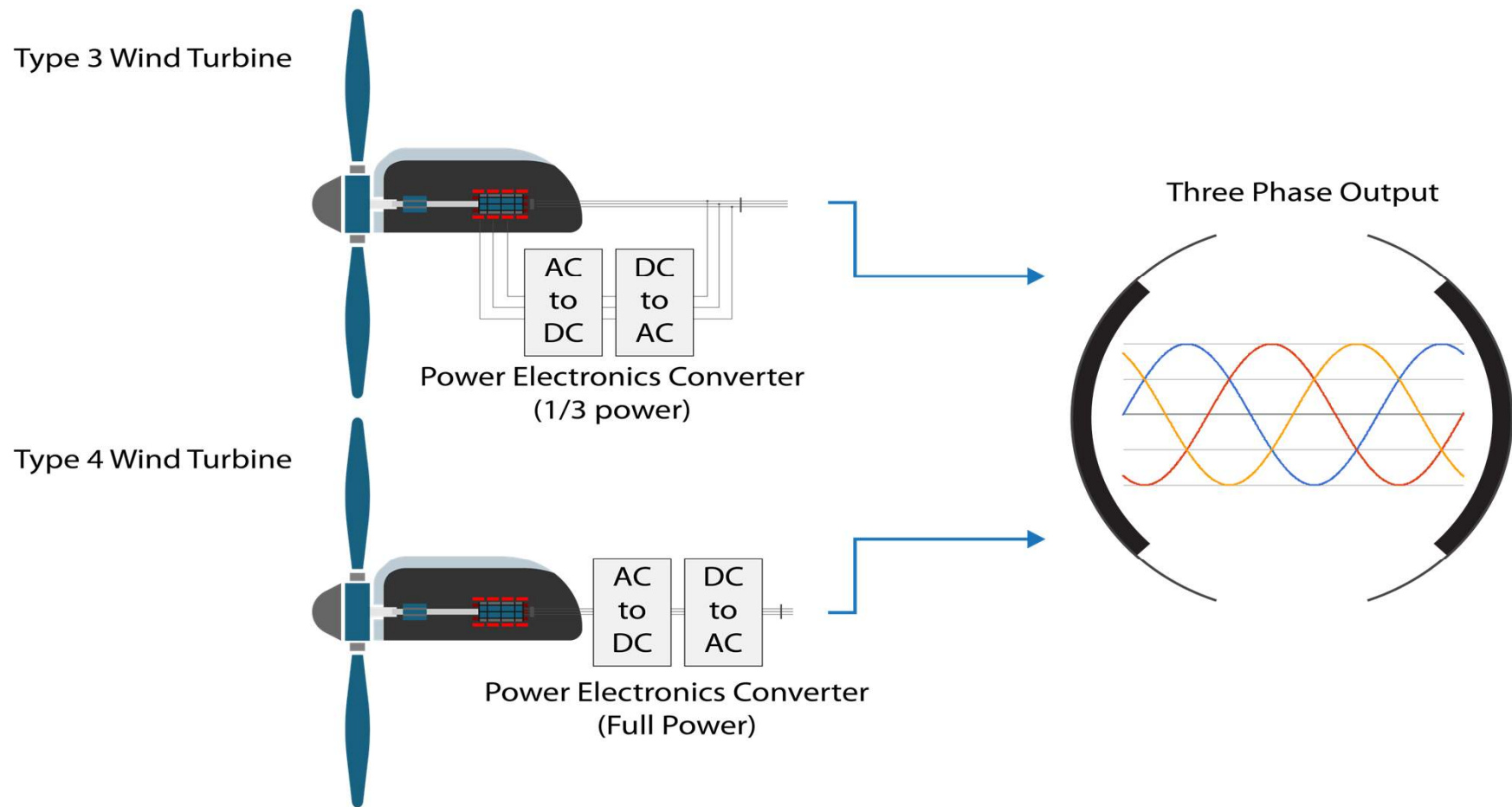
Pulse Width Modulation:



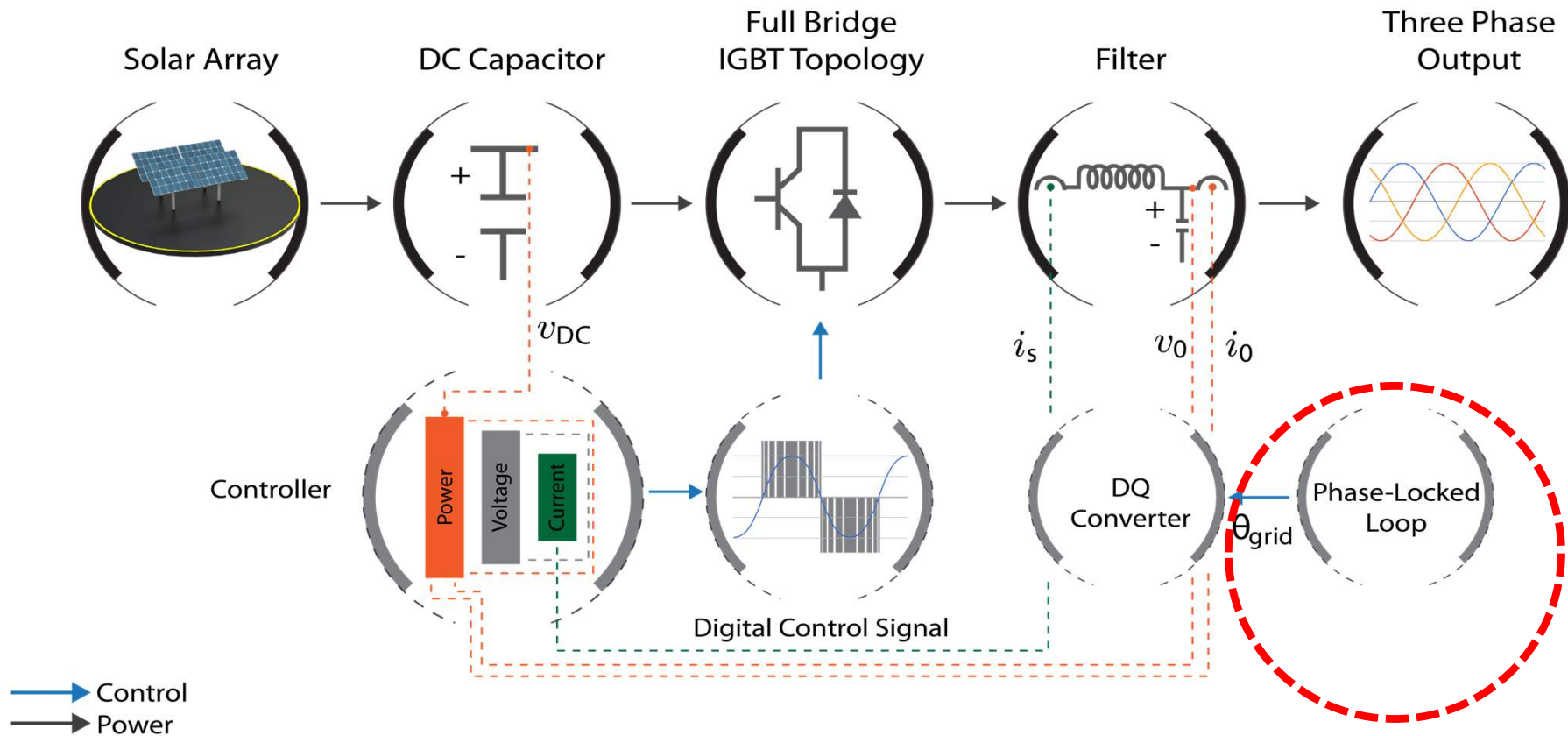
3-Phase Grid Following Power Electronic Converter



Wind Turbines Use PECs Also



3-Phase Grid Following Power Electronic Converter



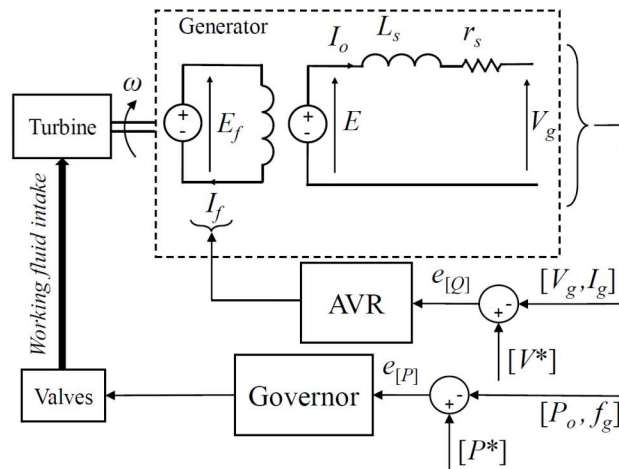
- Operation anticipates an existing power system (i.e. a sinusoidal voltage at the connection point), historically created by synchronous converters

An Emerging Problem

- Except for very small, electrically isolated systems (i.e. nano/micro grids), all contemporary PECs operate as **grid following**.
- But, if these grid following resources displace the grid forming SMCs, what is forming the sinusoidal waveforms of the power system?

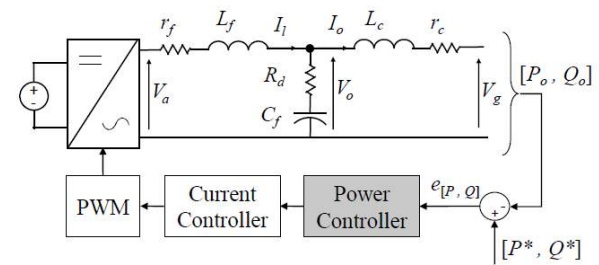
What's Changing?

Synchronous-machine

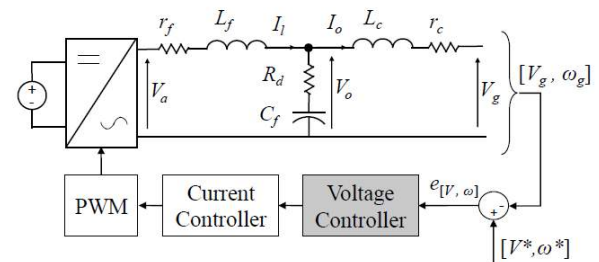


Mechanical
Deterministic

Inverter-based (IBR)



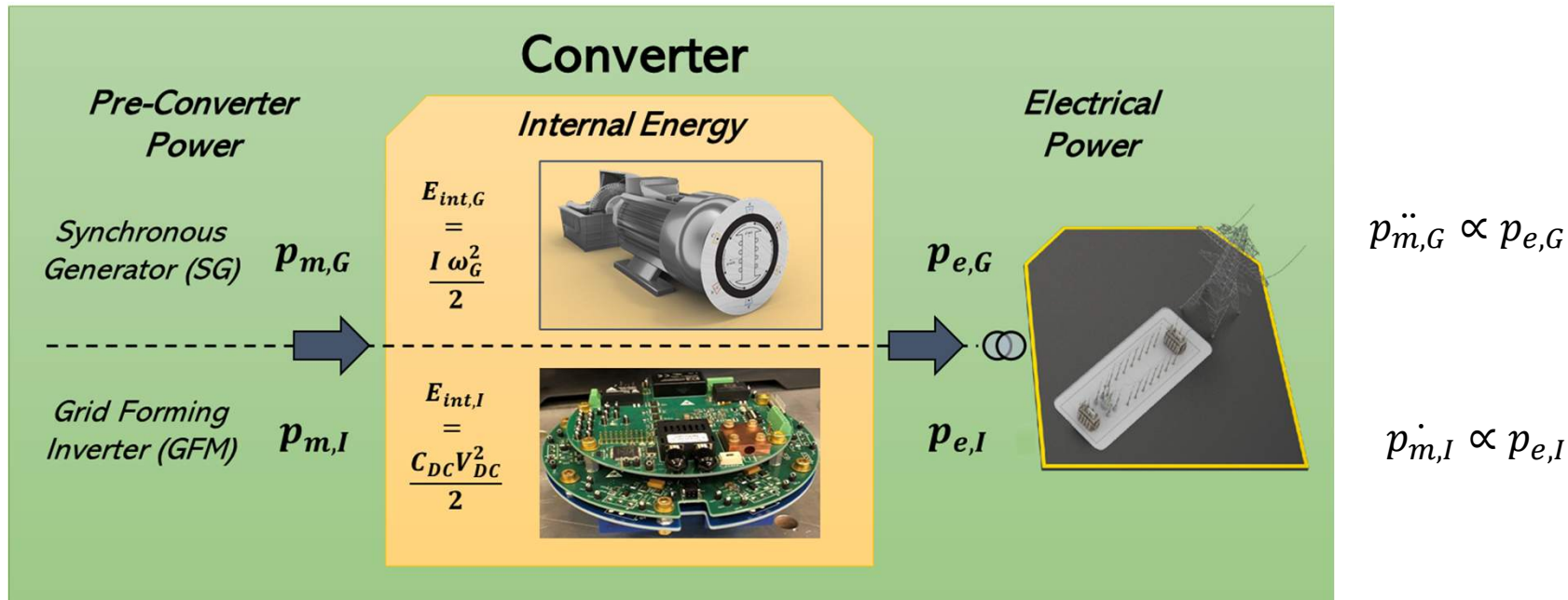
(a) GFL



(b) GFM

Digital
Stochastic

Device Level Power Mismatch



- A multi-loop droop GFM inverter has a lower order relation between pre-converter power and electrical power, as compared to an SG. A GFM device makes a first order exchange of energy with the system; there is no second order transfer of energy as in a SG, which is the source of substantial overshoot and oscillations.
- An SG only modifies pre-converter power after a change in frequency is registered; a GFM modifies frequency after changing pre-converter power. They are inverses of each other.

Why is this distinction important?



Grid Forming



Grid Following



Power



100% Grid Forming
0% Grid Following



75% Grid Forming
25% Grid Following



25% Grid Forming
75% Grid Following

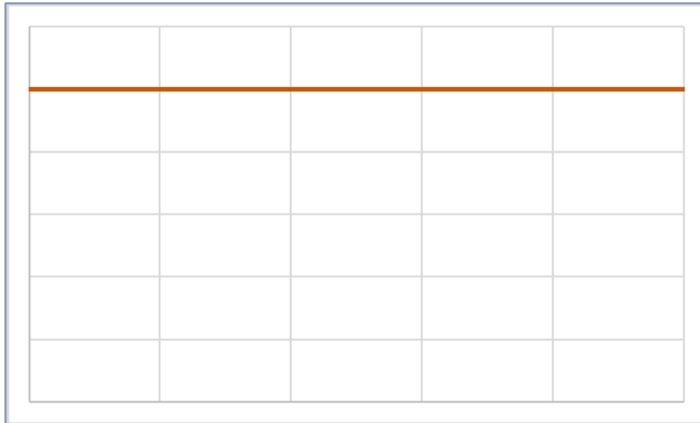


0% Grid Forming
100% Grid Following

Need to use Different Simulation Tools

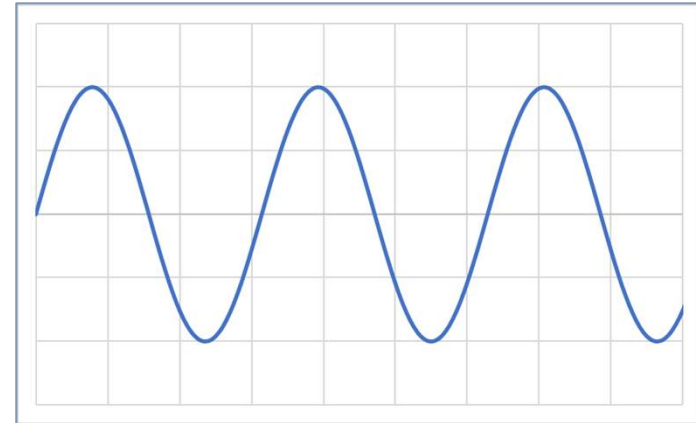
Positive Sequence:

Voltage as RMS (Phasor Domain)



Electromagnetic Transient:

Voltage as Sinusoid (Full Time)

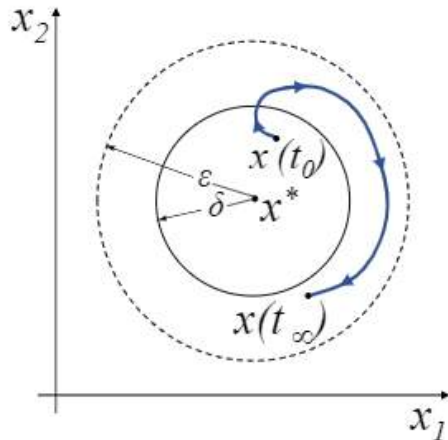


- Most dynamic simulation software is positive sequence (PSLF, PSSE)
 - Treats the network algebraically (as opposed to differentially)
 - But allows larger simulations with low computational cost...
- This is fine for synchronous generator dominated systems
 - They don't react within network transient settling times
 - Inverters do!
- Modeling in electromagnetic transient (EMT) domain?

Small Signal Stability

For small-perturbations:

Consider an equilibrium point x^* of a system $\dot{x}(t) = \varphi(x(t))$ is said to be locally stable for each $\varepsilon > 0$ if there exists a $\delta > 0$ such that $\|x(0) - x^*\| < \delta$ for $t > t_0$ and every solution of $x = \varphi(t)$ of the system which at $t = t_0$ satisfies $\|\varphi(t_0) - x^*\| < \delta$.



Phase portrait of a locally stable system: A locally stable system refers to a condition under which any trajectory that starts within a distance δ of x^* remains within the circle of ε of x^* for all positive time.

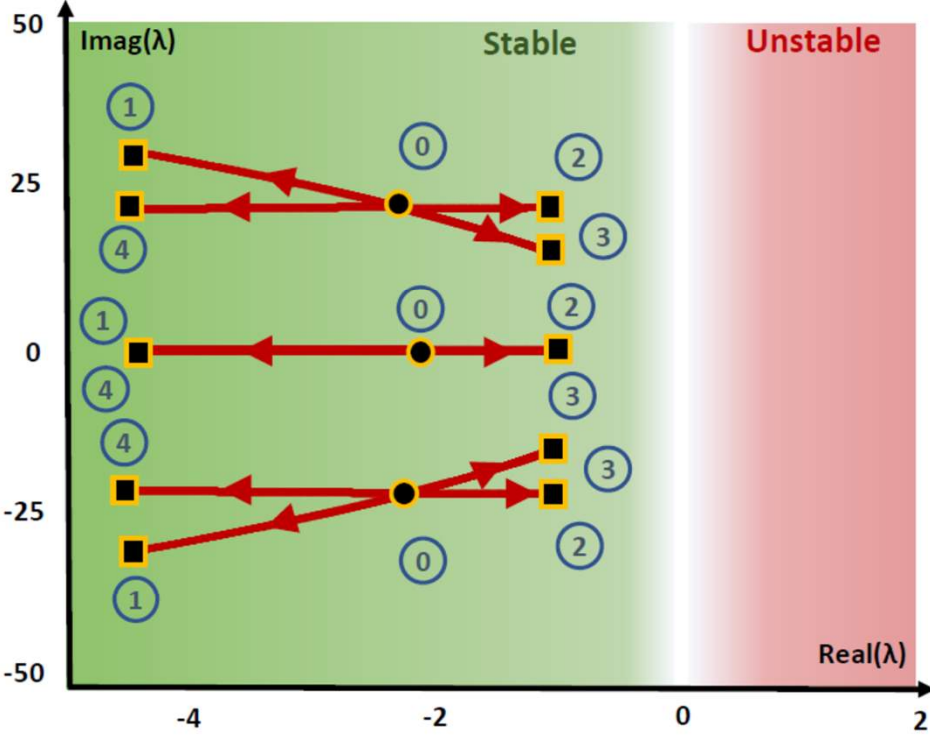
- The formal expression of the solution for the characteristic equation $p(\lambda)$ can be written in the form of

$$p(\lambda) = \prod_{i=1}^{(n-1)} \underbrace{(\lambda^2 + 2\zeta_i\omega_{n_i}\lambda + \omega_{n_i}^2)}_{\text{internal modes}} \cdot \underbrace{(\lambda + k_d)}_{\text{coupling mode}} = 0$$

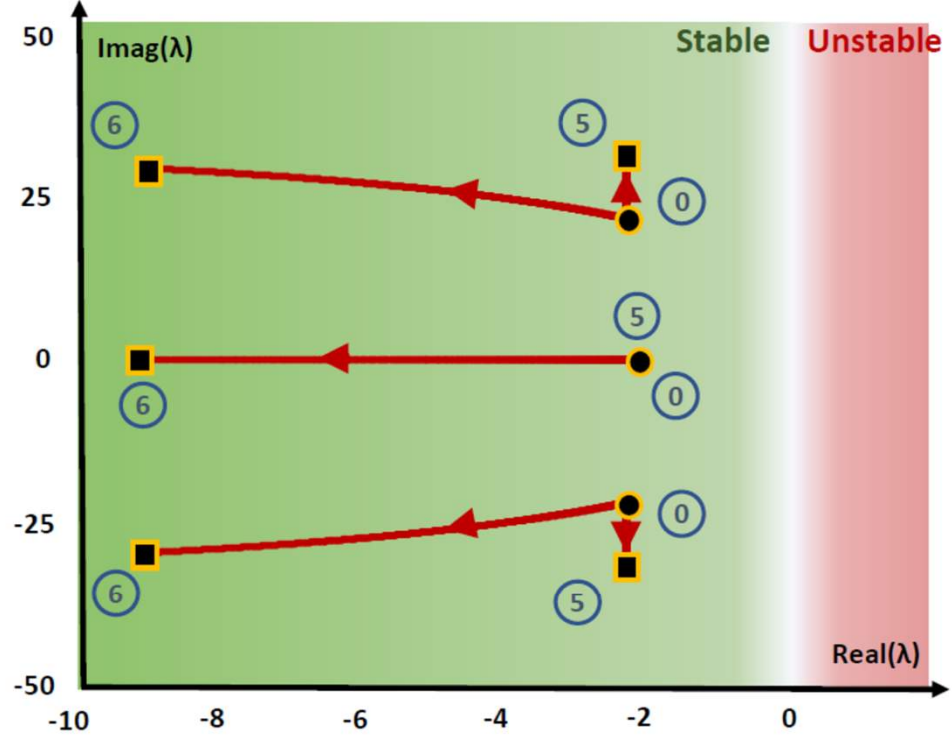
- The first part is the generators' internal modes involving the electric angle and speed of the generators, which presents a pair of complex conjugate eigenvalues.
- The second part is the system's coupling mode and presents as a real eigenvalue whose value is a function of the generators damping coefficient.

Eigenvalue Analysis

For a 3-generator, 9-bus system (commonly known as the WSCC system)

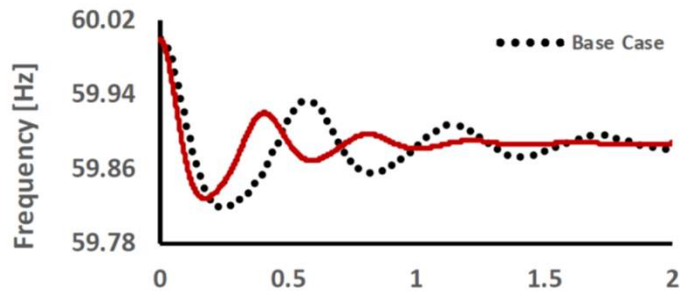


- (0) Base Case
- (1) Reduced Inertia
- (3) Increased Inertia
- (2) Reduced Damping
- (4) Increased Damping

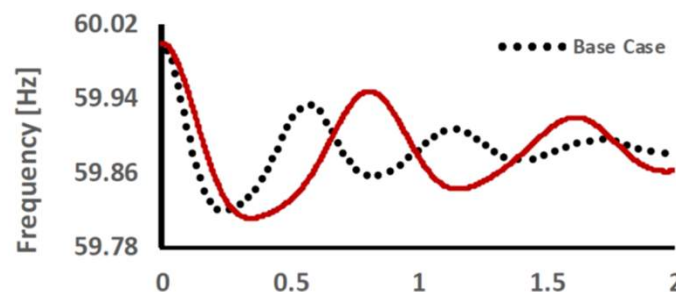


- (0) Base Case
- (5) Reduced Inertia, Reduced Damping
- (6) Reduced Inertia, Increased Damping

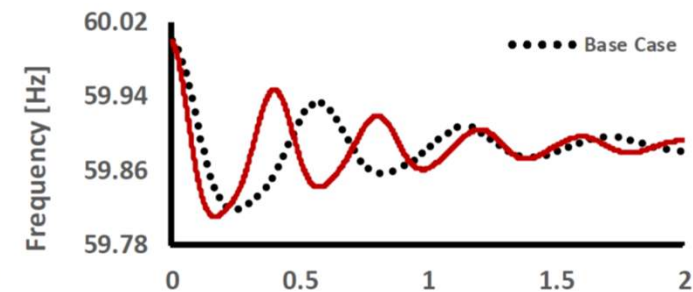
Frequency Impact in the Time Domain



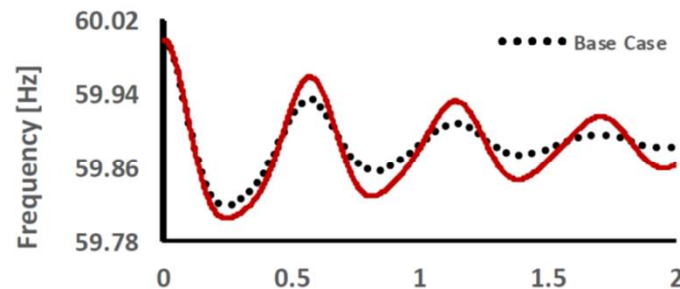
① Reduced Inertia



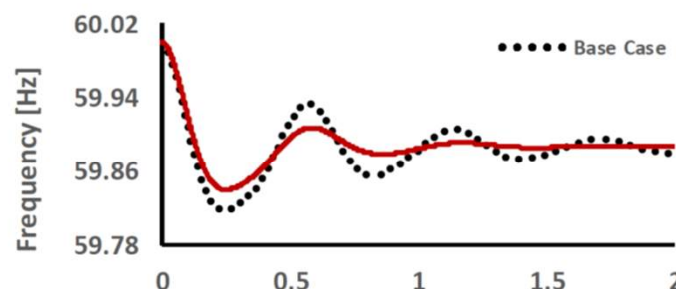
③ Increased Inertia



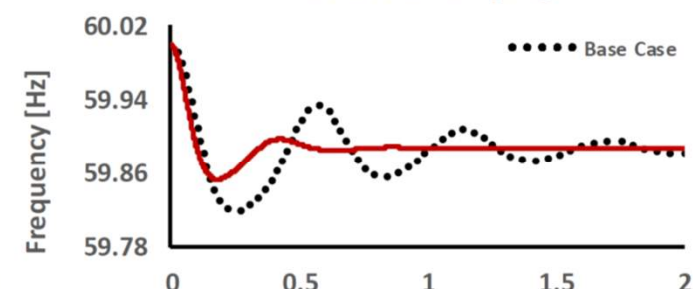
⑤ Reduced Inertia,
Reduced Damping



② Reduced Damping

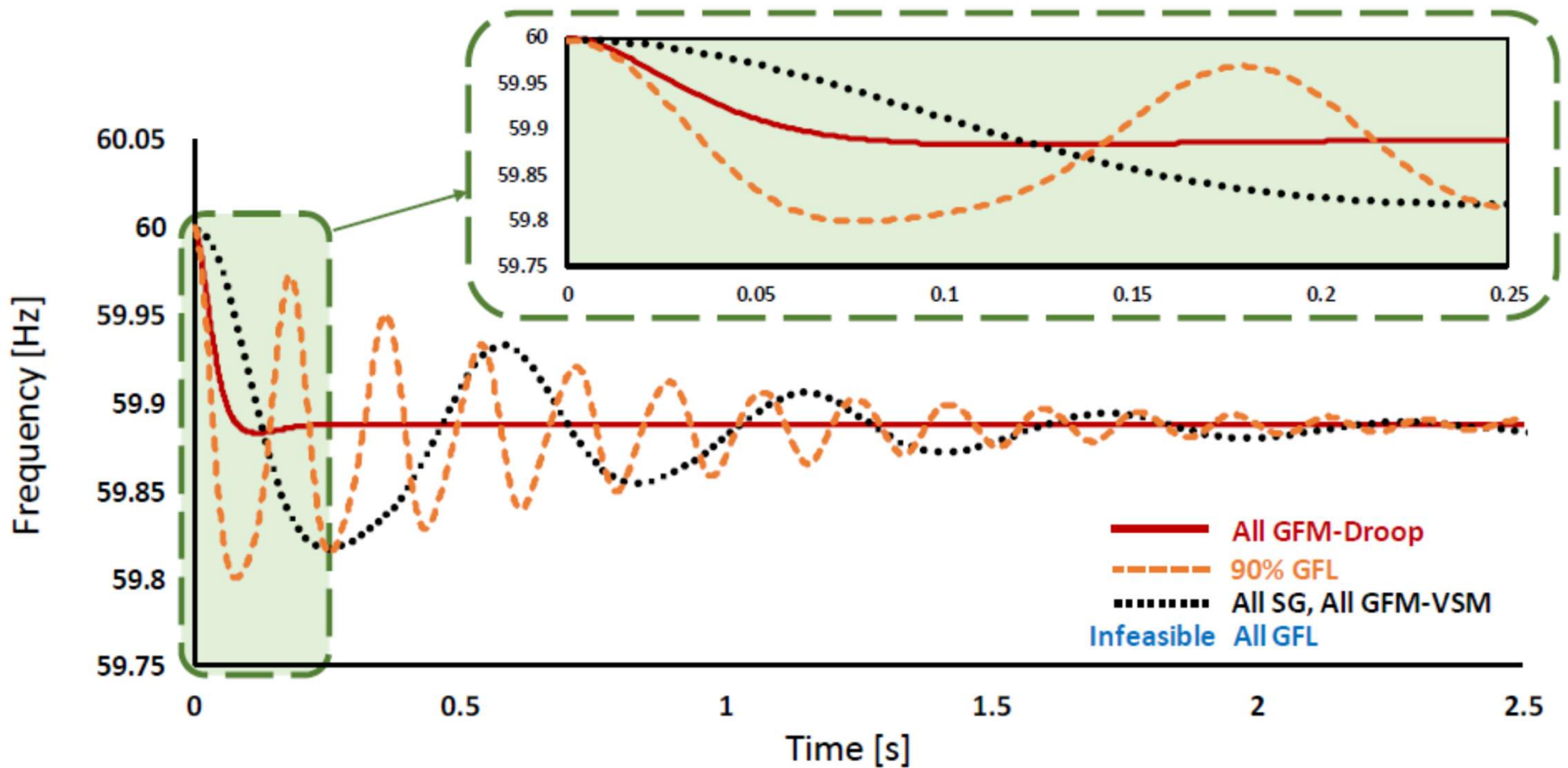


④ Increased Damping



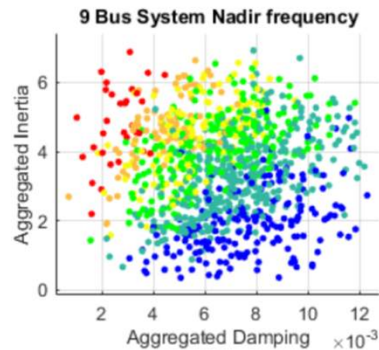
⑥ Reduced Inertia,
Increased Damping

New Frequency Dynamics

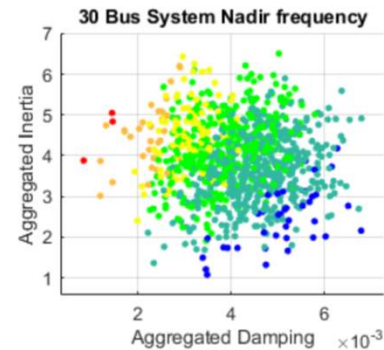


Stochastic Analysis

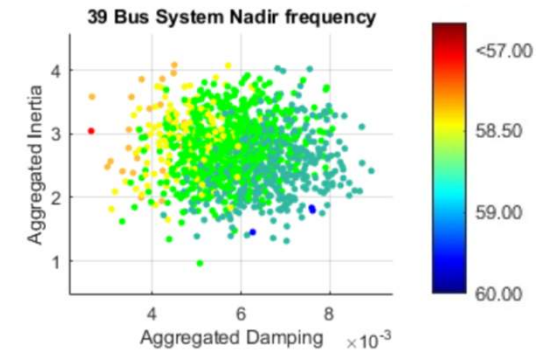
- 1,000 random parameters and system conditions
- 6 different power systems
- The randomness of generator inertia and damping coefficients represents technological variations to include both conventional and renewable generation
- The randomness of loading condition resembles the loading variations which determines node voltages and flow of power across the power lines in a power system and, therefore, represents the varying system dynamic states



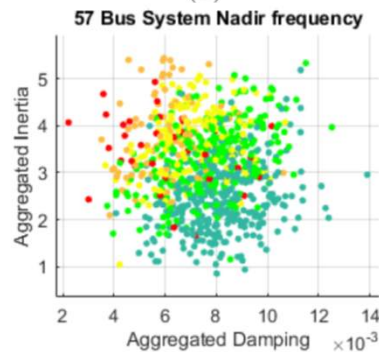
(a)



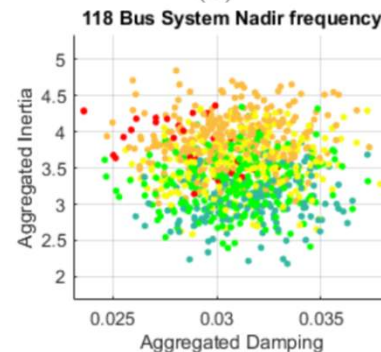
(b)



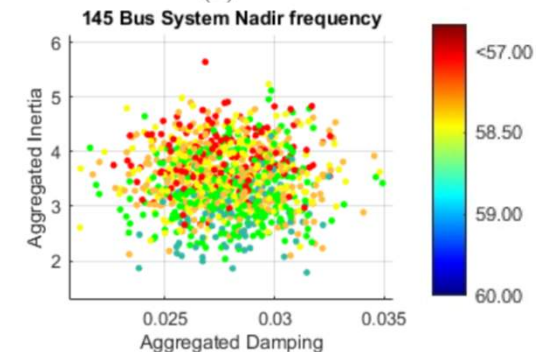
(c)



(d)



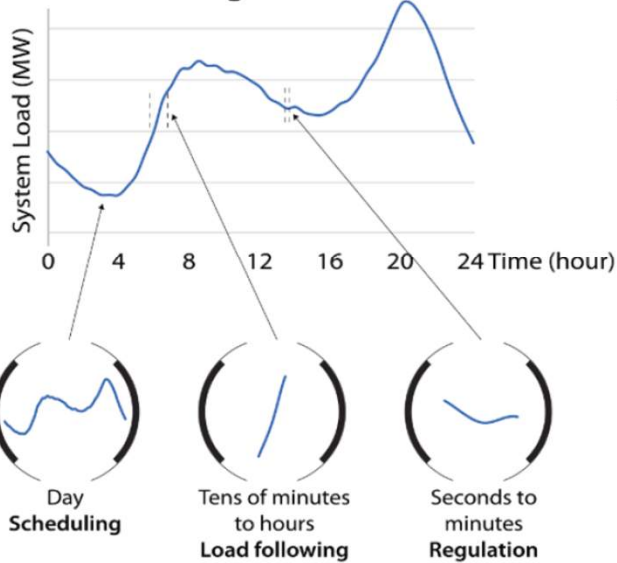
(e)



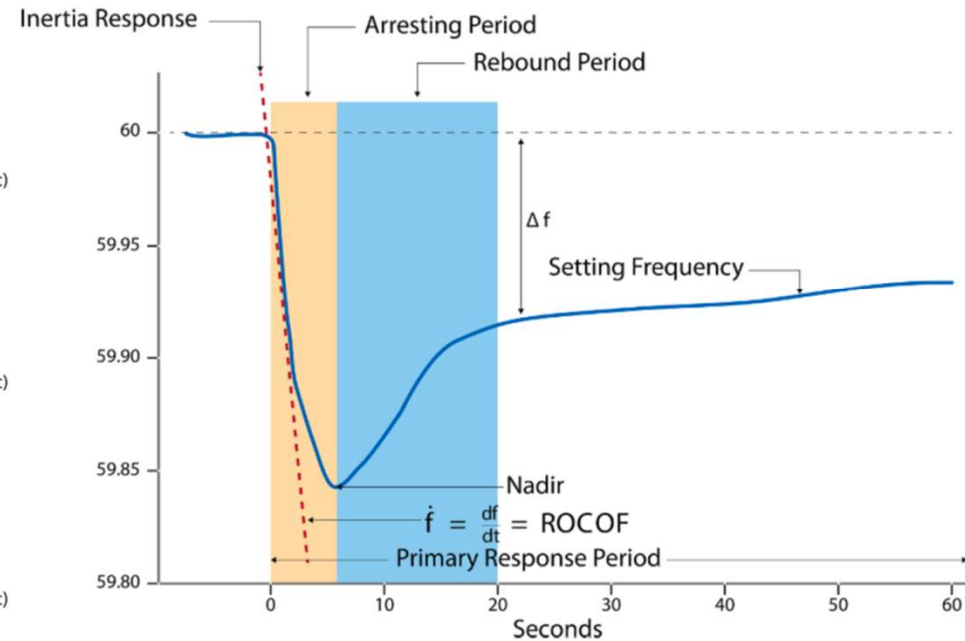
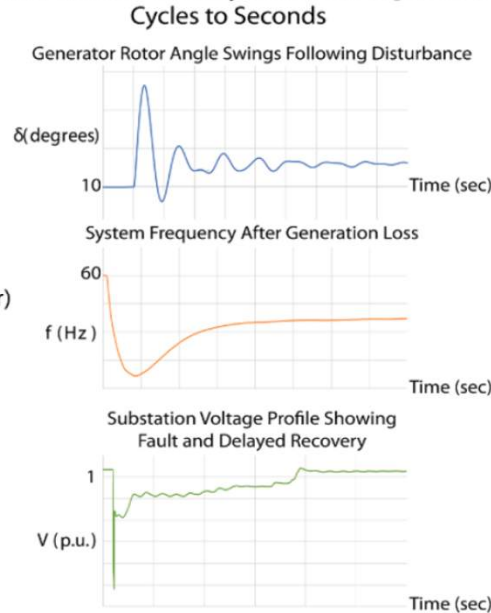
(f)

Power System Transient Stability

Load-Generation Balancing: Timescales



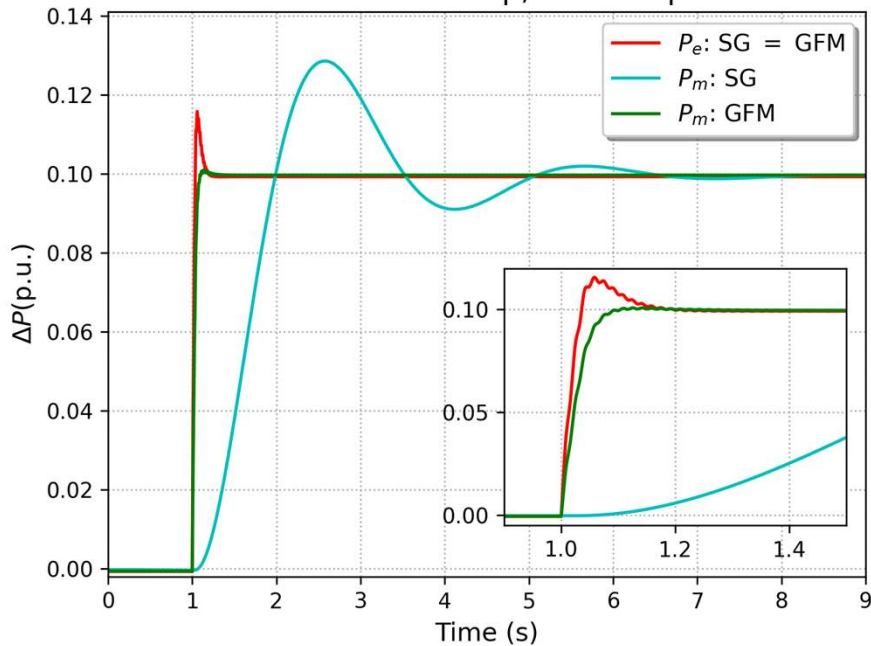
Abnormal Event Dynamic Responses



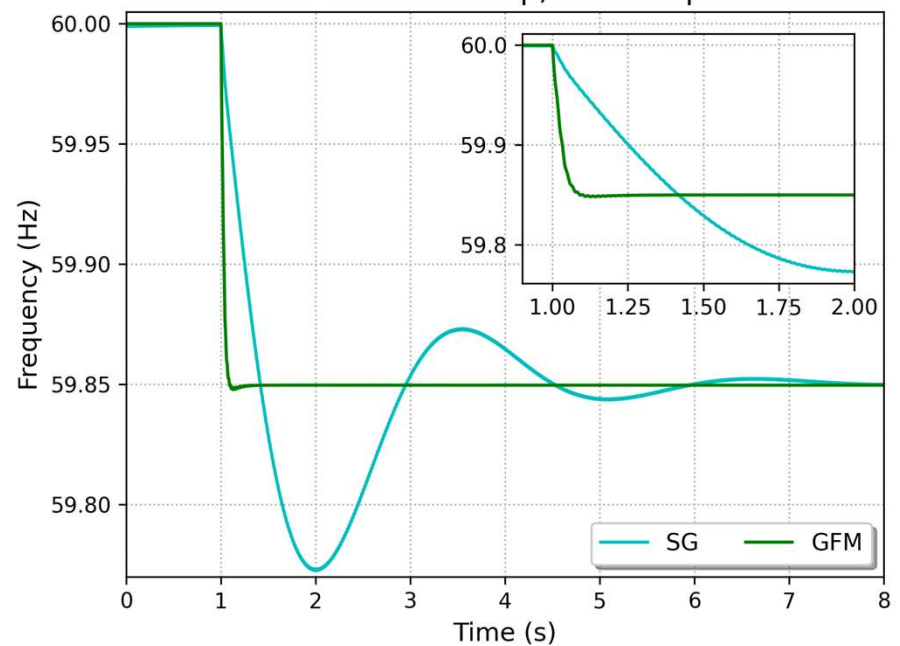
Individual Step Response

- Isolated device; 50% steady state dispatch

Power Reponse for Isolated Devices
10% Load Step, 5% Droop

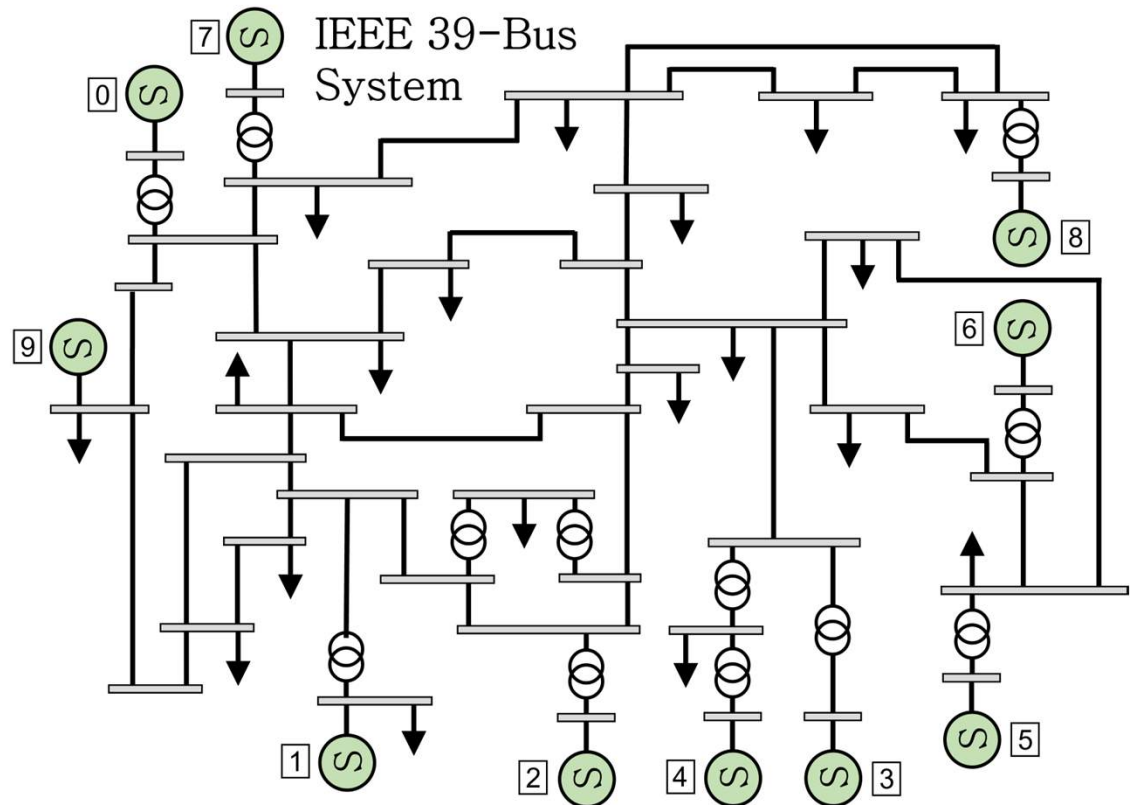
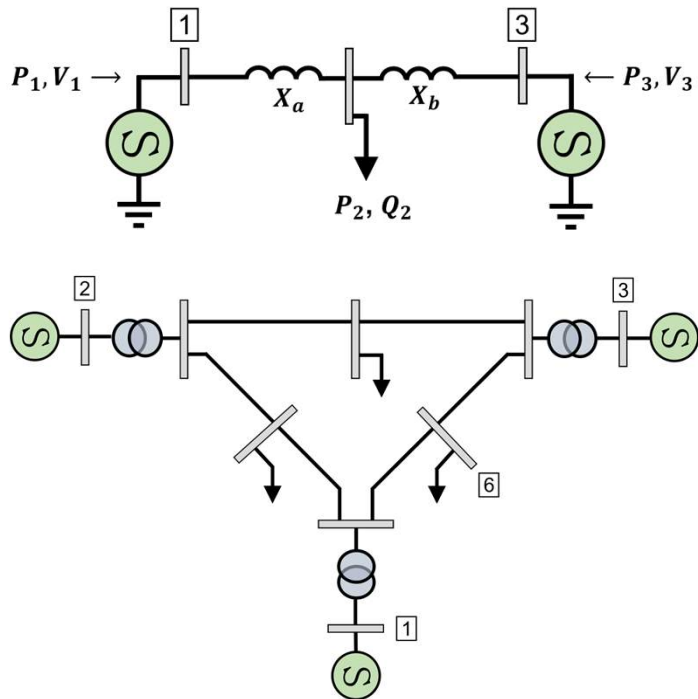


Frequency Response of Isolated Devices
10% Load Step, 5% Droop



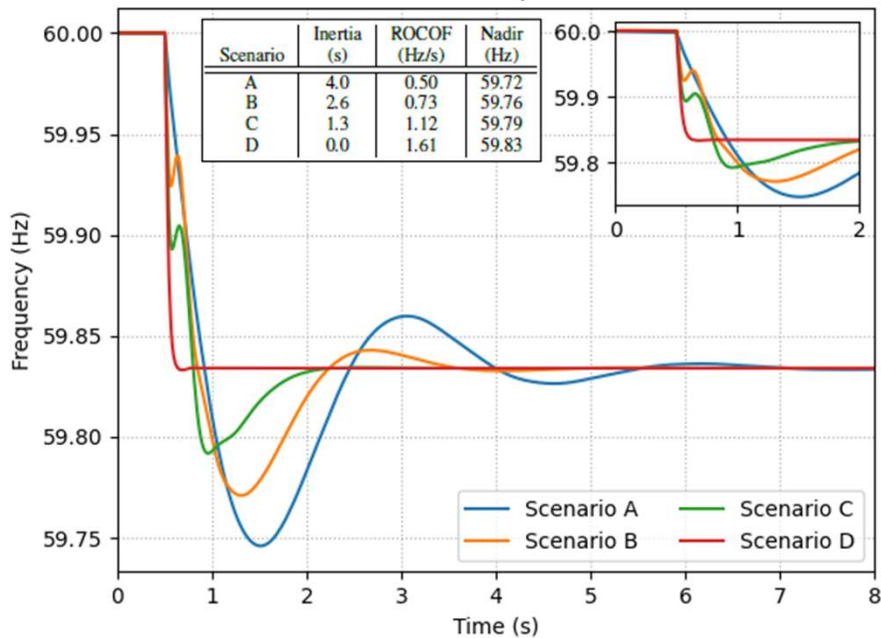
Grid-Forming Inverters vs. Synchronous Generators: Disparate Power Conversion Processes

3, 9, and 39 Bus Systems

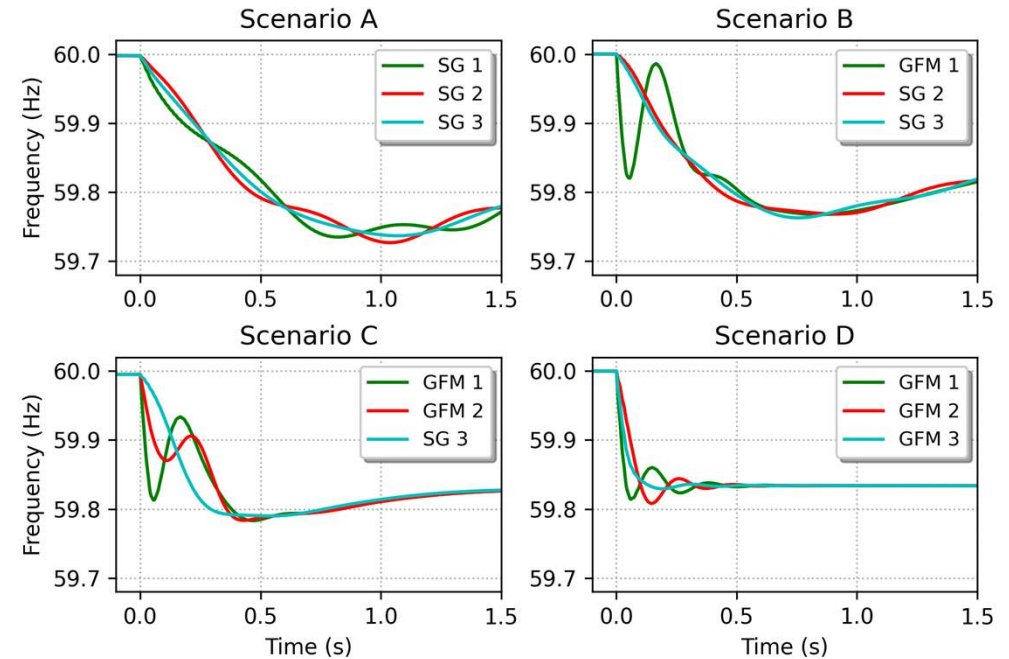


10% Load Step on IEEE 9 Bus System

IEEE 9 Bus Average Frequency by Scenario
10% Load Step at Bus 6



Frequency Response of Each Device
IEEE 9 Bus System, 10% Load Step at Bus 6

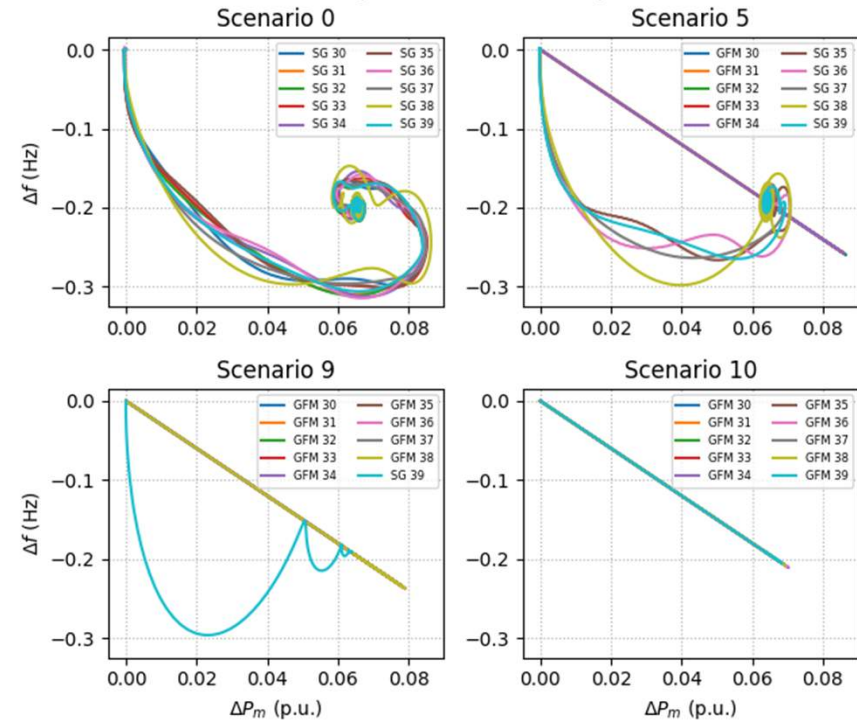


- All simulations in PSCAD with full order GFM inverter models (12+ states), and full order SG models.
- Scenarios A to D are a consecutive changeover of SGs to GFMs at the three generation buses.
- Inertia is aggregate, and only contributed by SGs. Larger ROCOFs with GFMs, but lower nadirs.
- Lower order frequency response with all GFM is evident

10% Load Step on IEEE 39 Bus System

Scenario	GFM at Buses	Inertia (s)	ROCOF (Hz/s)	Nadir (Hz)
0	n/a	4.0	0.567	59.690
1	30	3.6	0.587	59.712
2	30–31	3.2	0.669	59.717
3	30–32	2.8	0.808	59.724
4	30–33	2.4	0.930	59.730
5	30–34	2.0	1.071	59.738
6	30–35	1.6	1.225	59.748
7	30–36	1.2	1.396	59.748
8	30–37	0.8	1.525	59.756
9	30–38	0.4	1.648	59.772
10	All GFM	0.0	1.852	59.808

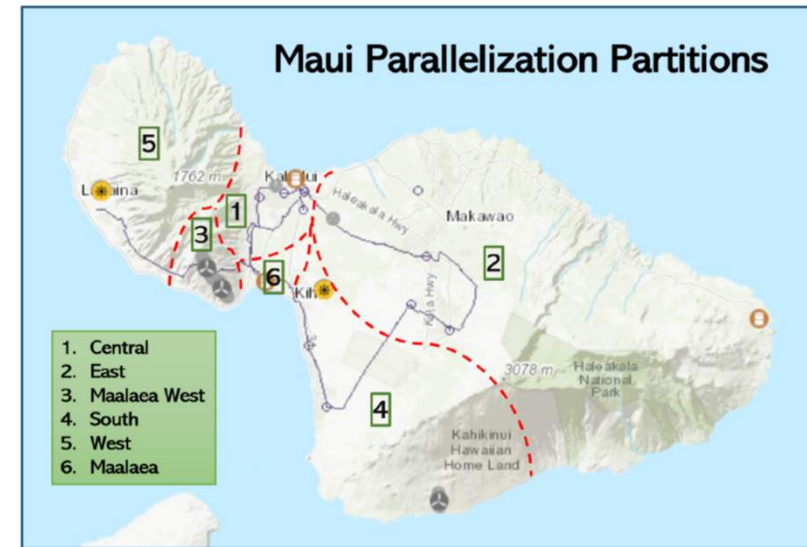
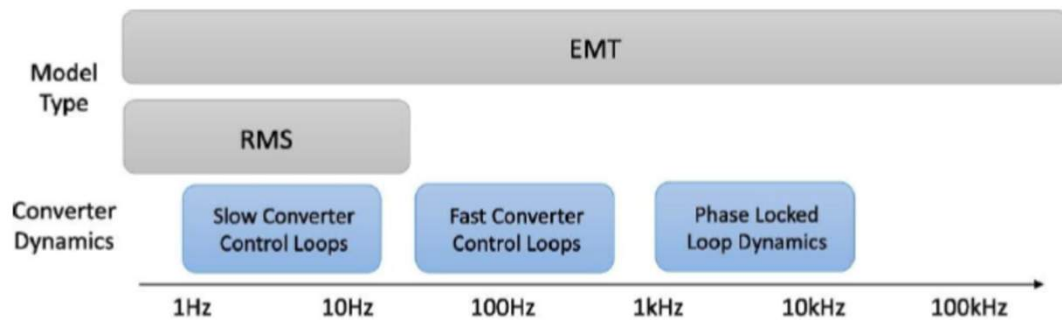
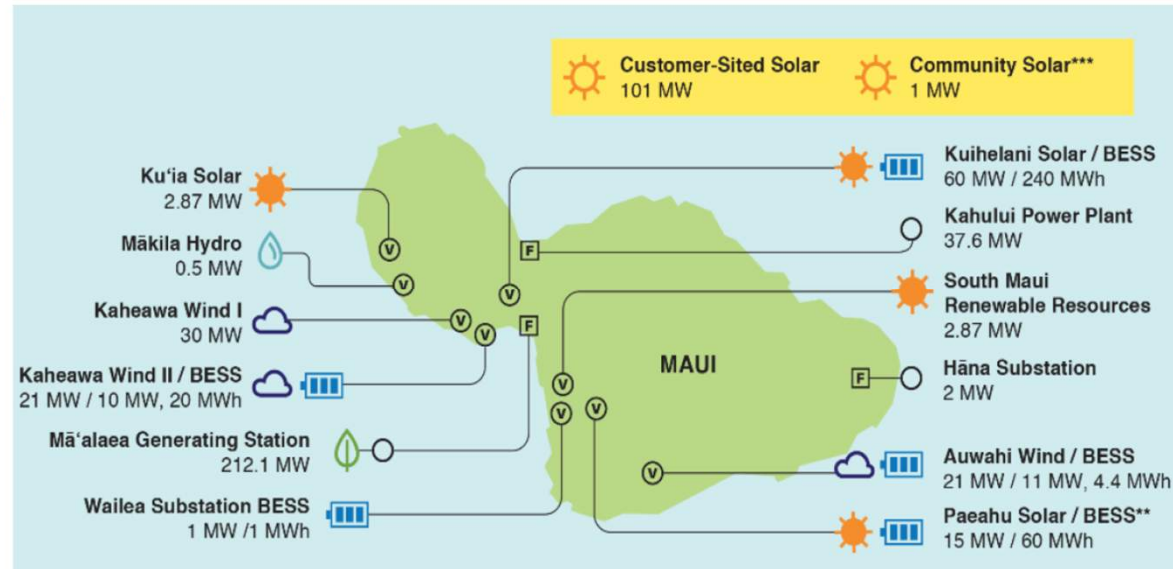
Frequency vs. Pre-Converter Power Deviations of Each Device
IEEE 39 Bus Test System, 10% Load Step at Bus 15



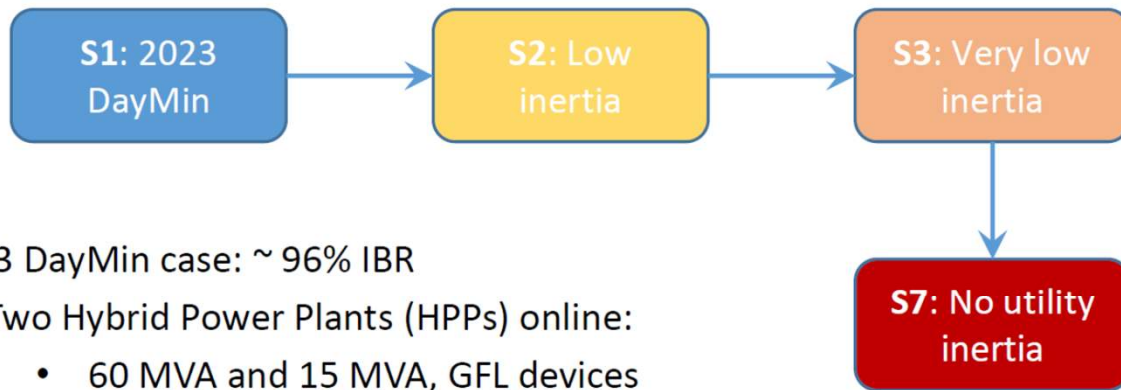
- All simulations in PSCAD with full order GFM inverter models (12+ states), and full order SG models.
- Very similar story to 9 bus system. Reduced nadir, larger ROCOF.
 - **Note: in a SG dominated system a larger ROCOF generally yields a lower nadir due to the reactive nature of SG governors to a change in frequency.**

Maui Background

- Hawaiian Electric expects Maui to be the first large island capable of operating with 100% inverter-based power resources, possibly by 2023
 - 2020 peak: ~89.5% IBR (DER and wind)
 - interconnected power system (~200 MW peak)
 - highly distributed utility-scale generation
 - 69 kV voltage levels

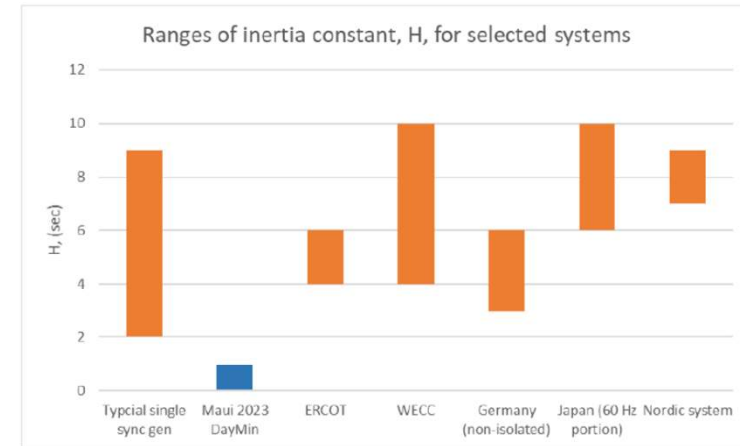


Simulation Base Case



2023 DayMin case: ~ 96% IBR

- Two Hybrid Power Plants (HPPs) online:
 - 60 MVA and 15 MVA, GFL devices
- Inertia: 370 MVA·s; Inertia constant $H = 0.97$ s (~1 order of magnitude below typical systems)
 - ~ 75% is sourced via 6 synchronous condensers
- Will compare results of PSSE and PSCAD



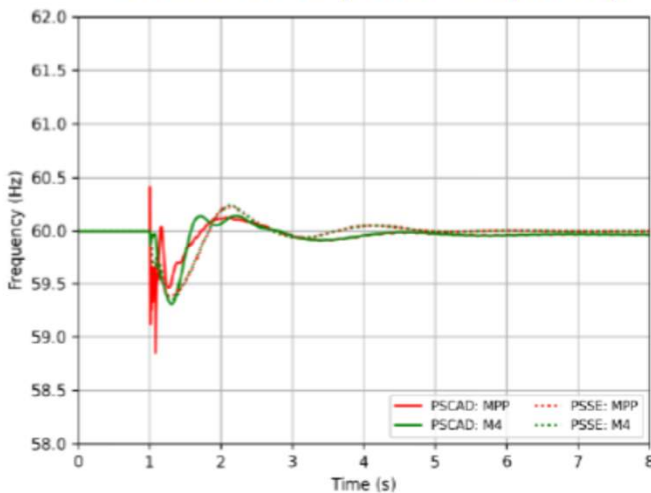
Note: We use “inertia” as a proxy metric for online synchronous machines

Dispatch, MW

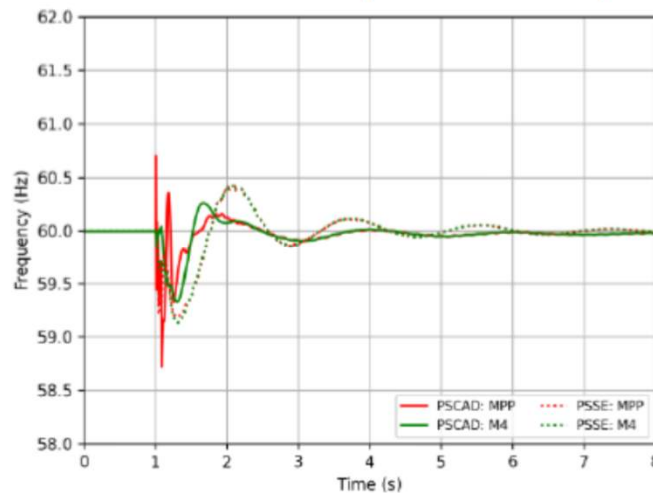
Total Load	Total Gen	Dist. PV “rooftop”	Existing large PV 2 plants	Wind 4 plants	Paeahu PV-BESS HPP	Kuihelani PV-BESS HPP	Sync Gens 3 generators
144.6	146.0	104.3	5.3	24.9	0	5.7	5.7

Event: Fault at low Short Circuit Ratio (Weak) Bus

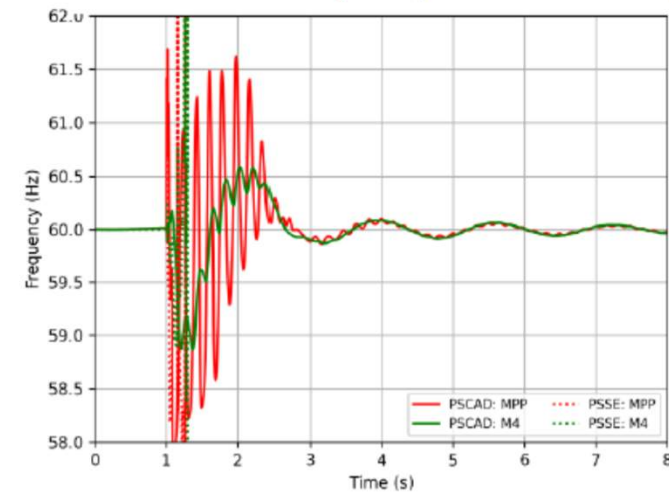
Scenario 1 (Base DayMin)



Scenario 2 (Low Inertia)



Scenario 3 (Very Low Inertia)

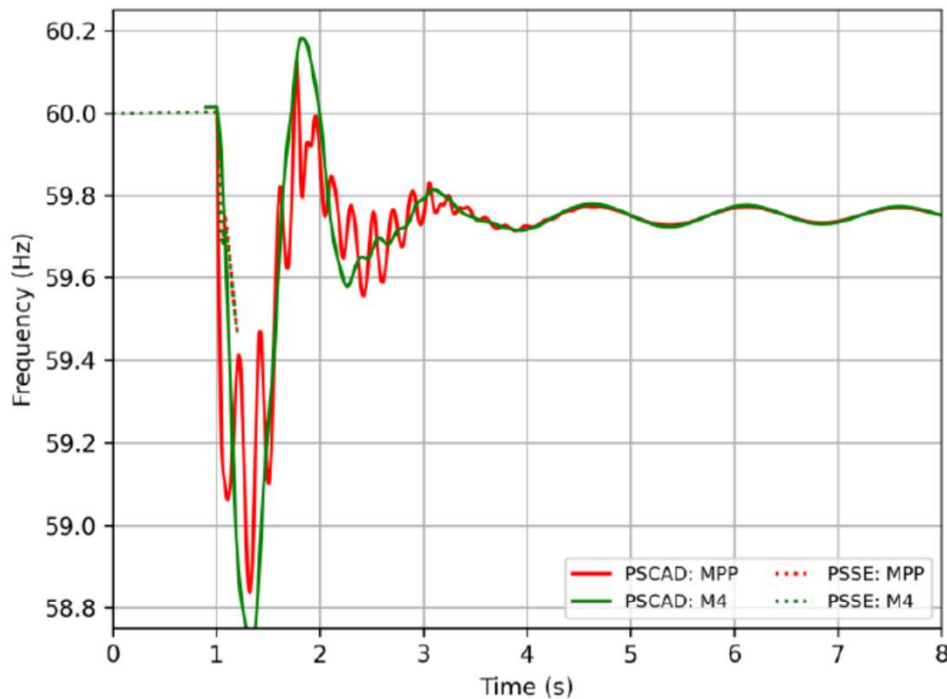


PSCAD: MPP is a PLL-measured frequency. PSCAD: M4 is a generator shaft rotation speed-derived frequency

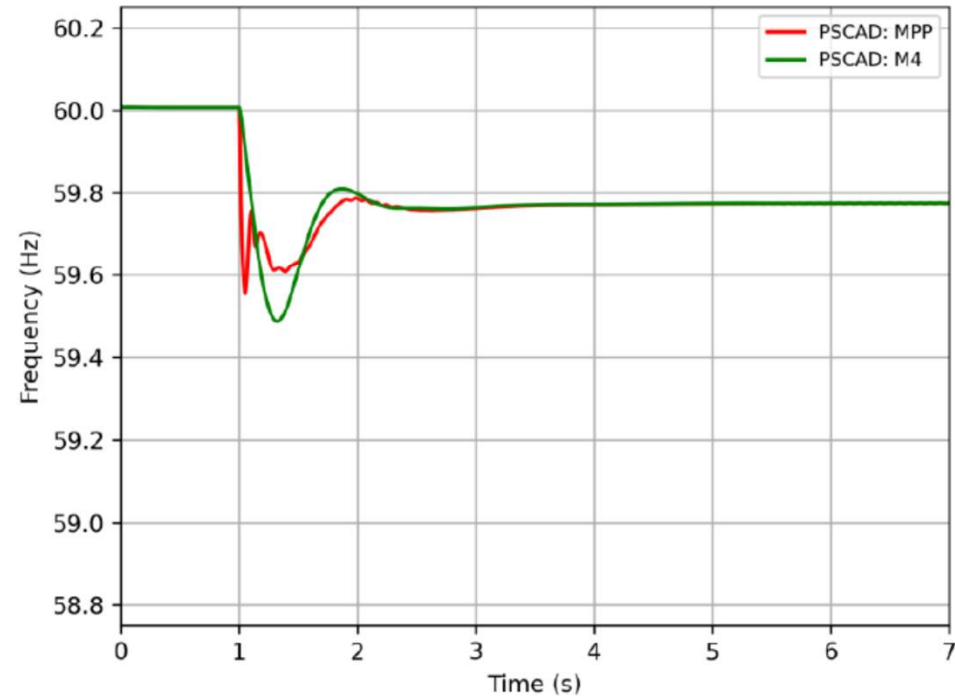
- Scenario 1 --> Scenario 3: reduced inertia and fewer voltage sources
 - Exacerbated oscillatory modes in S3, both in damping and quantity of modes
- PSSE simulation for Scenario 3 is numerically unstable shortly after the fault

Scenario 3: Largest Generator Trip (GFL vs. GFM)

HPP as a GFL



HPP as a GFM



- Substantial increase in primary damping; major reduction in faster modes
- Nadir is raised significantly (58.7 to 59.5 Hz), and ROCOF improved (despite no increase in inertia)

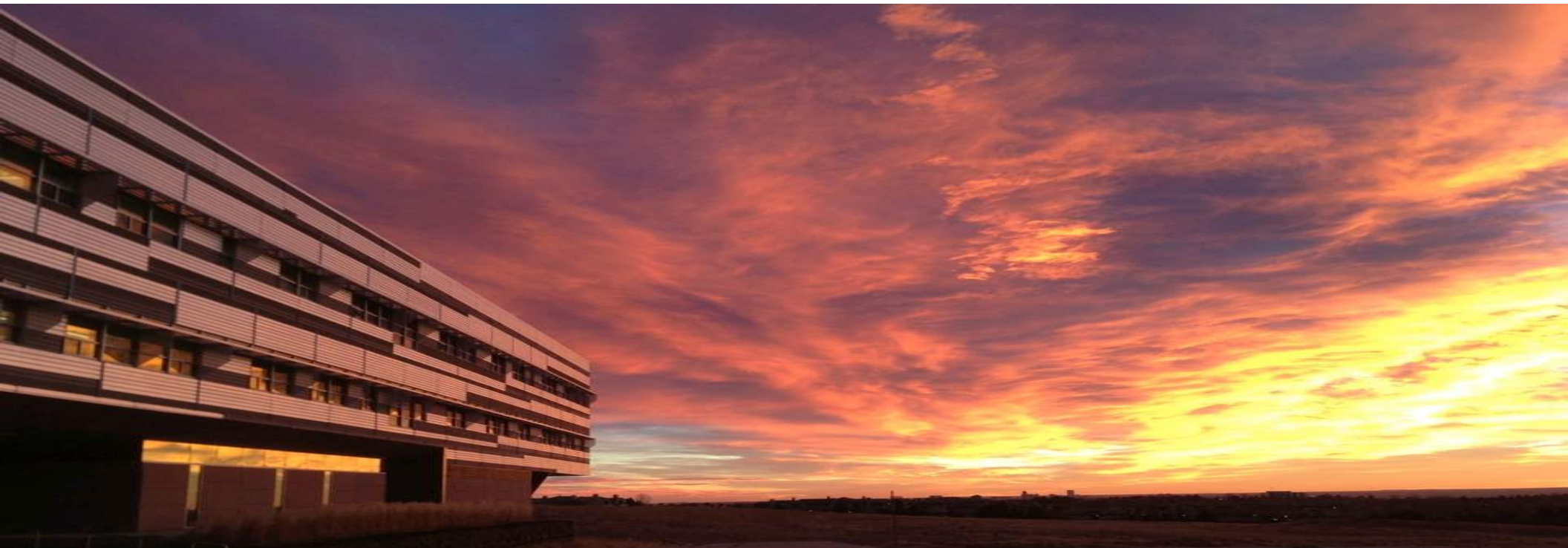
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Conclusions and Implications

- Is damping just as important as inertia in “low-inertia power systems”?
- First order relation of GFM between electrical and pre-converter power permits substantial ‘damping’ for SGs (which have a second order relation).
 - Relation between pre-converter power and frequency is also inverted for these devices
 - SGs change pre-converter power due to frequency changes...
 - GFMs change frequency due to pre-converter power changes...
- The network frequency is no longer easily approximated by an aggregate swing equation
- A larger ROCOF no longer means a lower nadir
- *Do we need GFMs already?*
 - *How many? Where? Which types of devices?*
 - *Should this be an interconnection requirement, or should there be a market?*

Acknowledgements

- Dr. Amir Sajadi – CU Boulder (now Span)
- Dr. Wallace Kenyon – CU Boulder
- Matt Bossart – CU Boulder
- Dr. Andy Hoke – NREL





Thank you!



Extra Slides

Importance of Reactive Power

- Provides voltage control to ensure proper operations
- Voltage control important for:
 - Preventing damage to generators and motors
 - Reducing line losses
 - Preventing voltage collapse
 - Occurs when the system is trying to serve more load than the voltage can support

Reactive Power Sinks and Sources

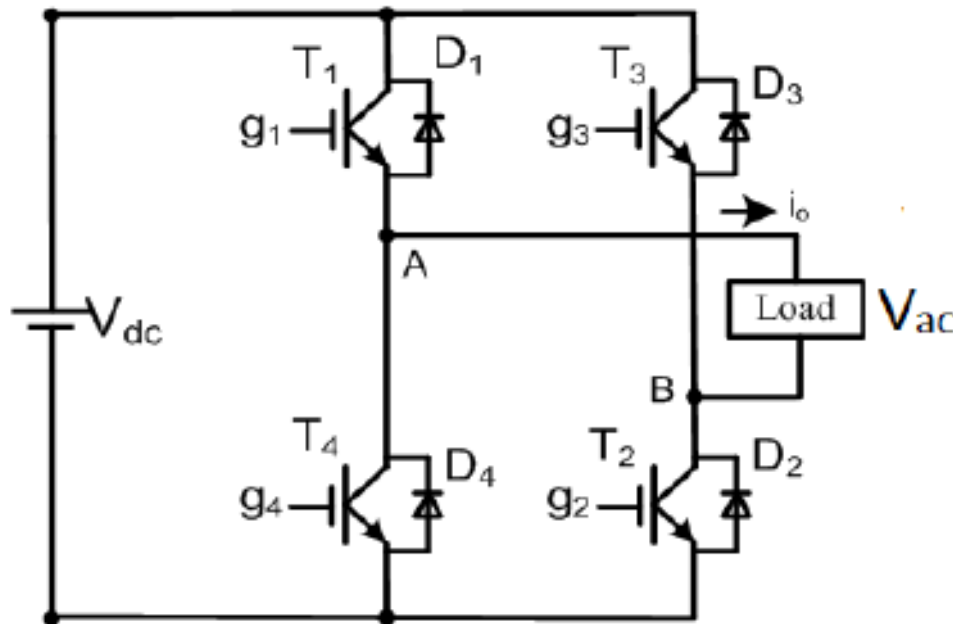
- Sources:
 - Shunt capacitors
 - Underground AC lines (high capacitance)
 - Overhead AC lines (light loading)
 - Capacitance exceeds reactive lines due to impedance
- Sinks:
 - Transformers – reactive losses
 - Shunt reactors
 - Overhead AC lines (heavy loading)
 - Load (aggregated at transmission level)

AC Power System

- Electricity loads can be **resistive** (e.g. heaters), **inductive** (e.g. motors), and **capacitive** (e.g. capacitors).
- **Active power** is the power that is dissipated in the resistance of the load.
- **Reactive power** is the power that is exchanged between reactive components. Capacitors generate reactive power and inductors consume it.
- **Apparent power** is taken into account when designing and operating power systems, because although the current associated with reactive power does no work at the load, it still must be supplied by the power source.
- **Frequency control**: active power balance (system wide)
- **Voltage control**: reactive power balance (local)
- **Electricity is traded in terms of active power over a period of time.**

Single Phase Inverter

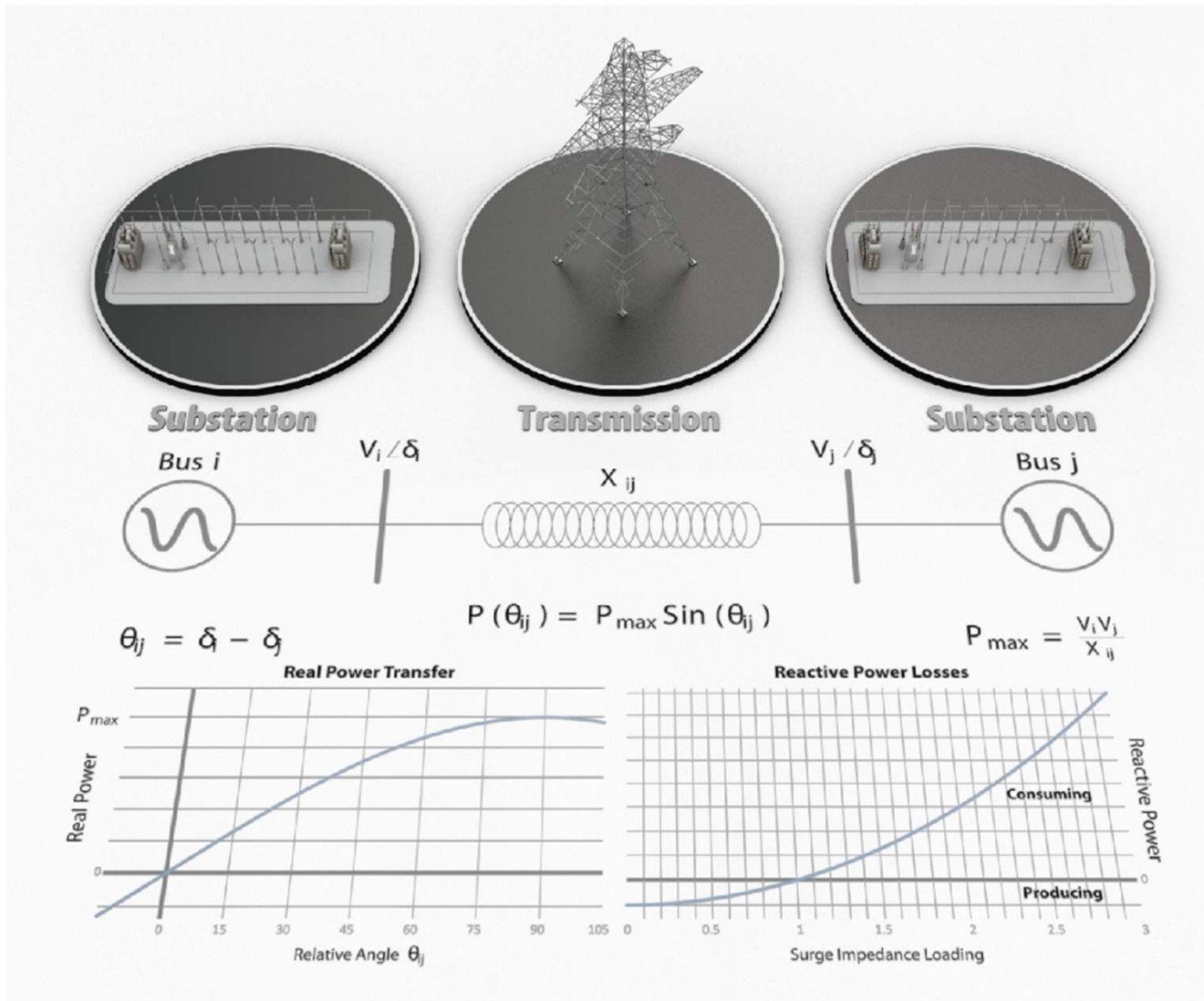
Full-bridge Switch Topology:



Hassan M. Abdar, researchgate.net

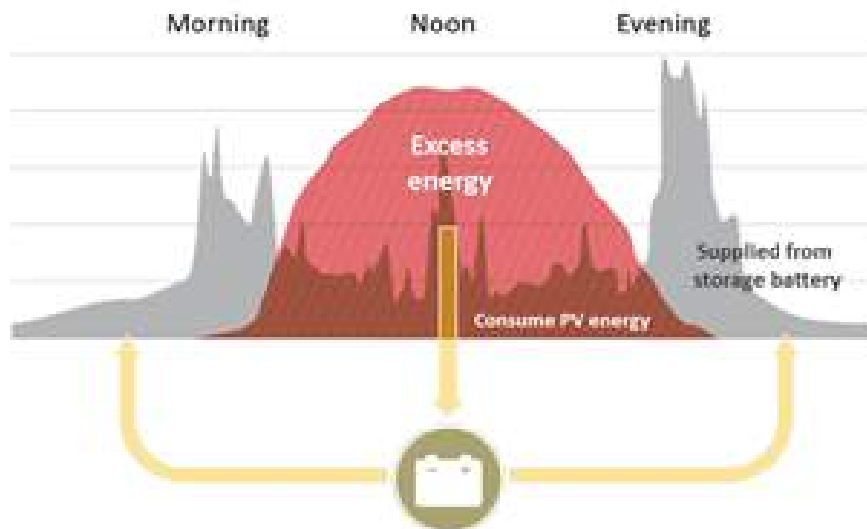
- T_1/T_2 & T_3/T_4 operate as pairs
- When T_1/T_2 are conducting, T_3/T_4 are not and i_o is positive
- When T_3/T_4 are conducting, T_1/T_2 are not and i_o is negative

Power Flow Primer

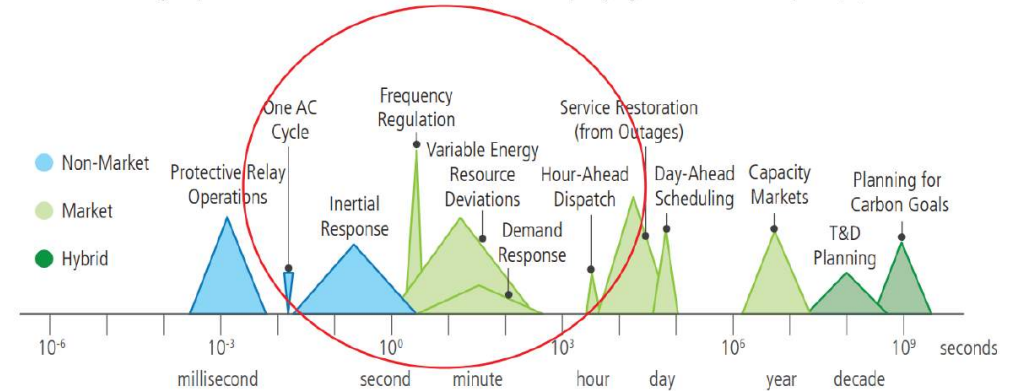


Energy Storage

- Backup power in case of grid disconnection
- Rate management
- Self-consumption
- Renewable shifting/ smoothing
- Increased PV accommodation
- Demand response, Congestion management, Deferrals
- Ancillary services/Frequency regulation



Markets are used for grid operations in the order of seconds to minutes, such as frequency regulation and demand response (DR). Some essential

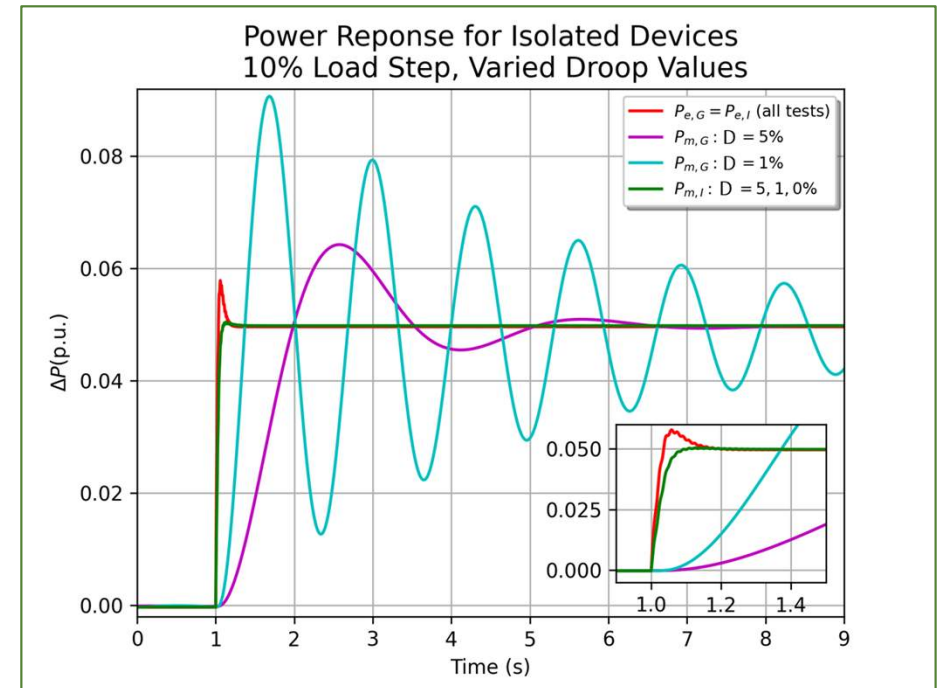
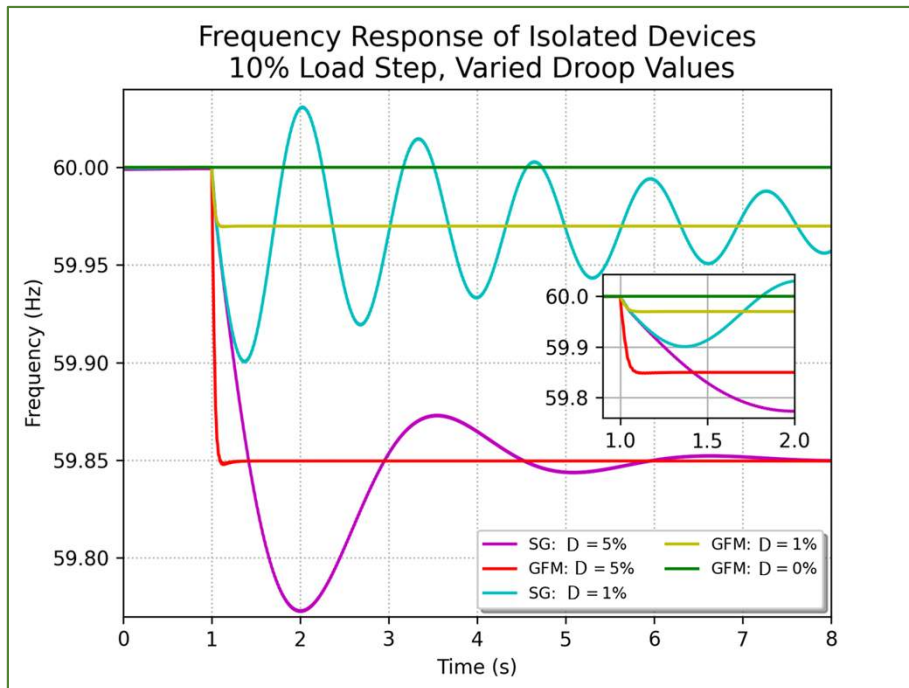


reliability capabilities, such as inertial response, occur faster than typical market signals. Acronyms: transmission and distribution (T&D), alternating current (AC).

Source: US DOE Quadrennial Energy Review, Second Installment, January 2017

Droop-e: Exponential Droop as a Function of Power Output for Grid Forming Inverters with Autonomous Power Sharing

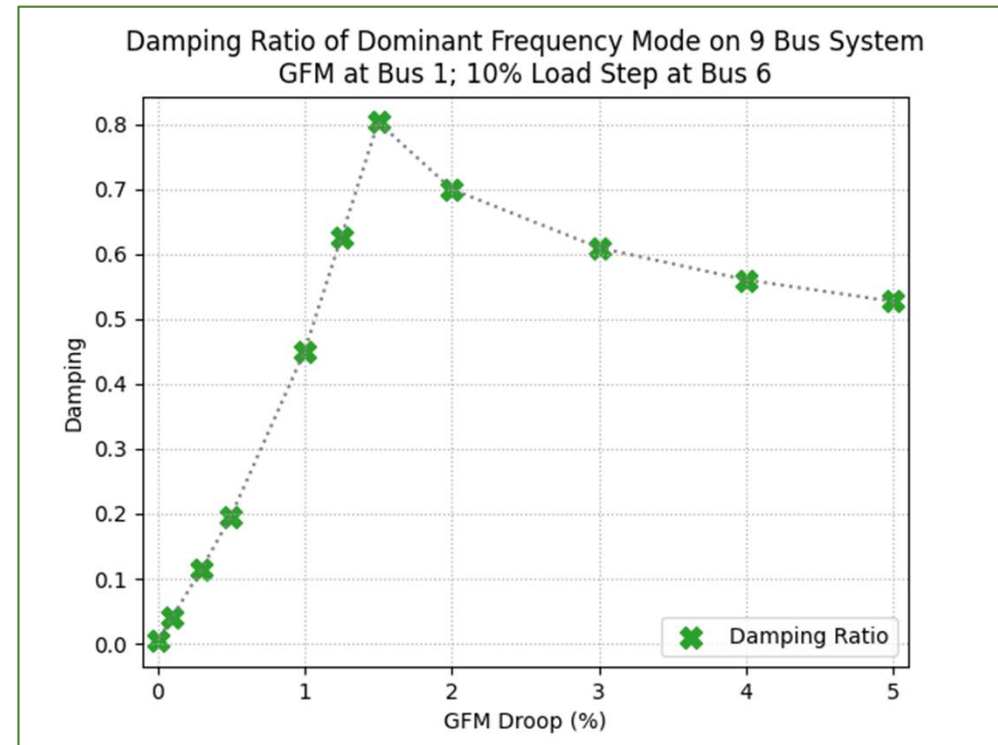
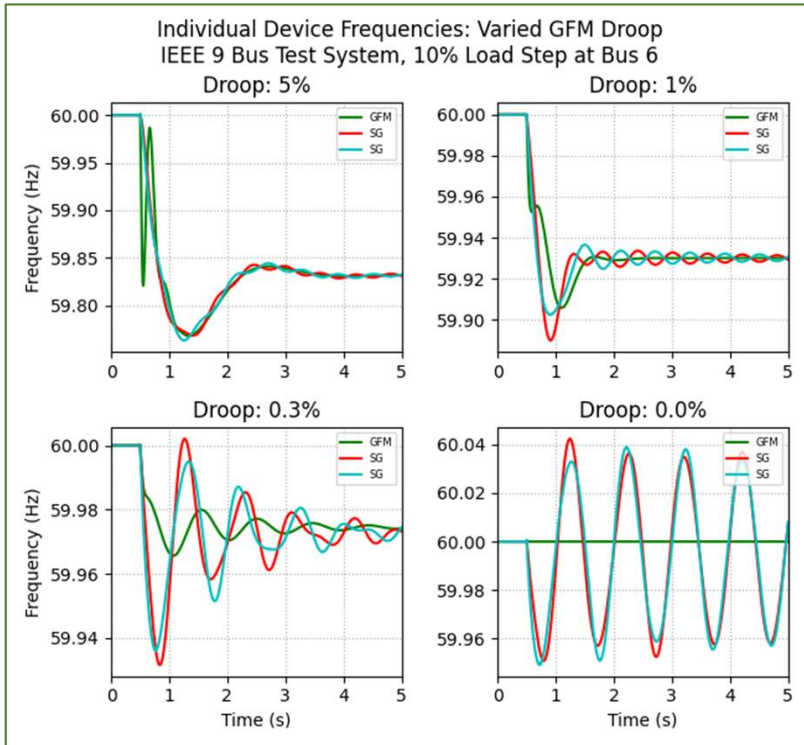
Inspiration for Treating D Dynamically



- Adjusting the droop gain of synchronous generators yields instability for smaller values
- Response of grid-forming inverter to these droop gain changes is stable regardless of value

Droop-e: Exponential Droop as a Function of Power Output for Grid Forming Inverters with Autonomous Power Sharing

Initial limit investigation yields a curious loss in damping for static droop gains below 1.5%

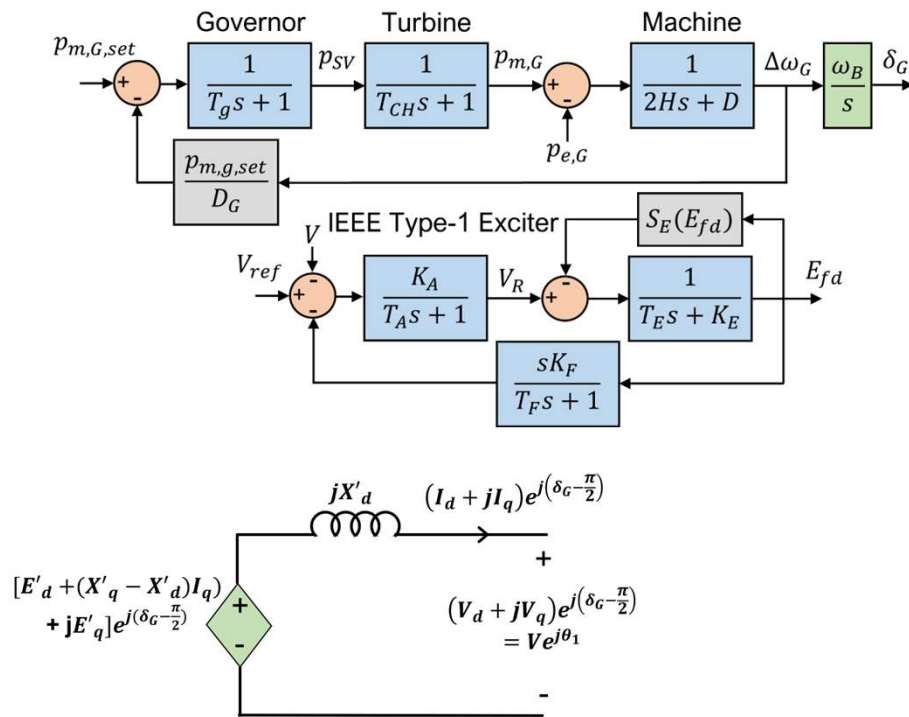


- For droop gains below 1.5%, there's an inversion in the damping ratio trend (based on average frequency)
- Time domain indicates the neighborhood below 0.5% creates large, persistent oscillations
- Looks like the GFM is just exchanging power with the SGs, which oscillate in phase

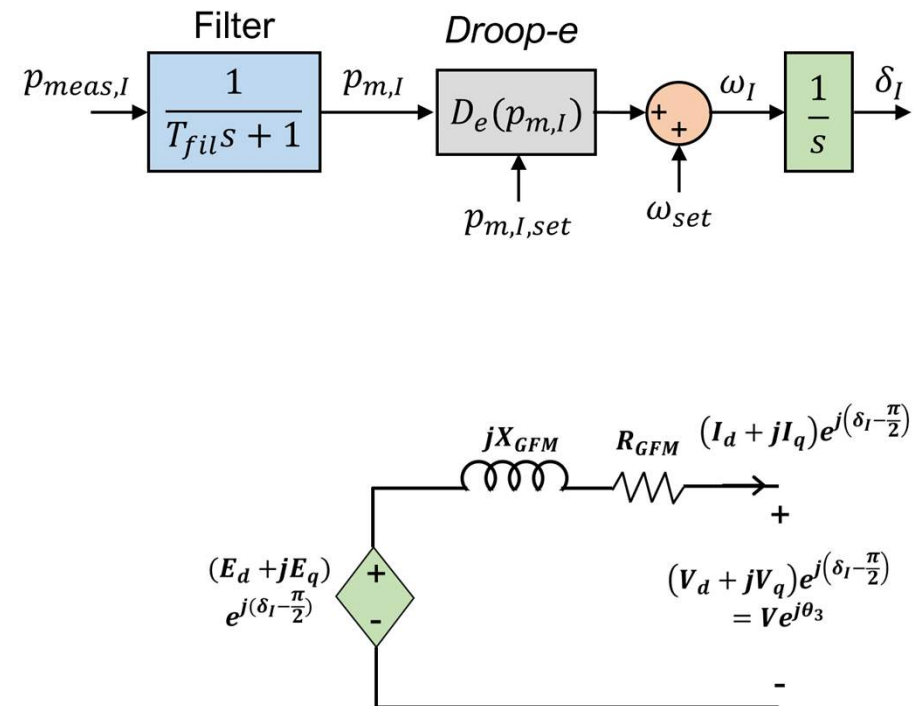
Droop-e: Exponential Droop as a Function of Power Output for Grid Forming Inverters with Autonomous Power Sharing

Models Used for Small Signal Stability Analysis

Synchronous Generator



Grid-Forming Inverter



- Assumed constant voltage for grid-forming inverter, greatly reduces model complexity